

# How opinions and infections evolve on dynamic random graphs

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# Outline

- ▶ Lecture 1. Background and motivation for **opinion dynamics** and **infection models** on static graphs
- ▶ Lecture 2. **Voter model** on dense dynamic random graphs: Part I
- ▶ Lecture 3. **Voter model** on dense dynamic random graphs: Part II
- ▶ Lecture 4. **SIR epidemic model** on dense dynamic random graphs

# Goals

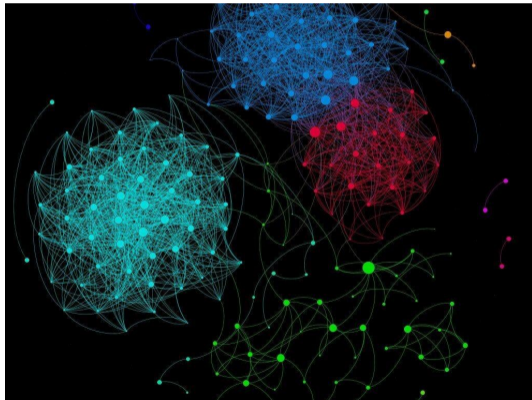
- ▶ Describe the evolution of **dynamic networks together** with **dynamic processes** running on them
- ▶ Highlight the challenging when dealing with **co-evolution**
- ▶ Outline some **open questions** and possible **directions for future work**

# LECTURE 1

Opinion dynamics and infection models on static graphs

# Interacting systems on networks: A big picture

Many complex systems can be seen as **dynamical processes** evolving on networks

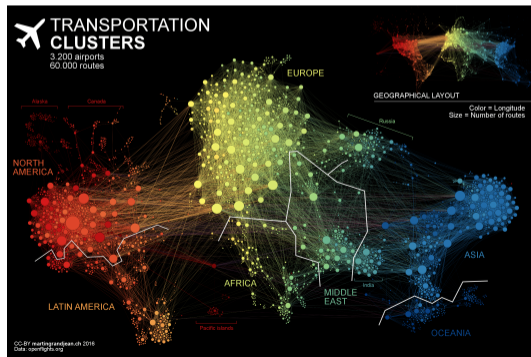


# What is a network?

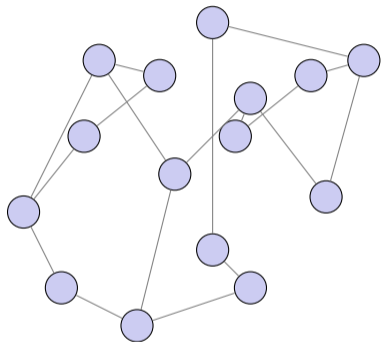
- A **network** is a set of **nodes** (people, computers, genes, neurons) connected by **edges** (interactions, friendships, communication, infection pathways, influence)
- **Key features**
  - ▶ **Node degree**: number of connections per node
  - ▶ **Network density**: fraction of possible edges that exist
  - ▶ **Communities**: groups of nodes more connected among themselves
  - ▶ **Dynamics on networks**: how node states evolve along edges (opinions, infections, activity...)

## Examples of real-world networks

- ▶ **Social networks:** friendships, online interactions
- ▶ **Biological networks:** spread of an infection, protein interactions, neurons
- ▶ **Technological networks:** internet, communication systems, power grids
- ▶ **Transportation networks:** air traffic, road systems

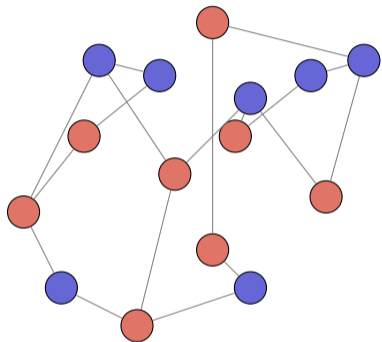


# Dynamics on networks



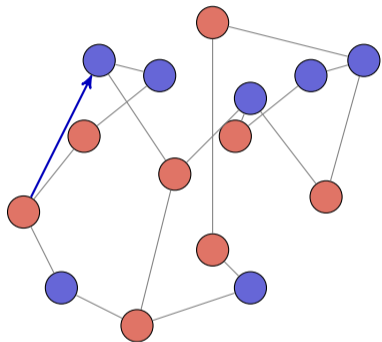
nodes = agents, edges = interactions

# Dynamics on networks



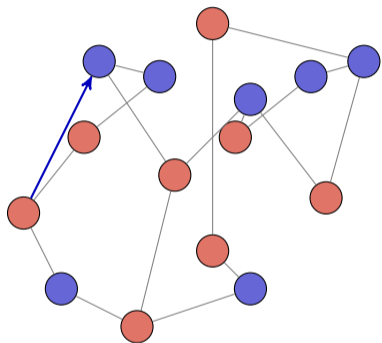
red/blue = states of agents

# Dynamics on networks

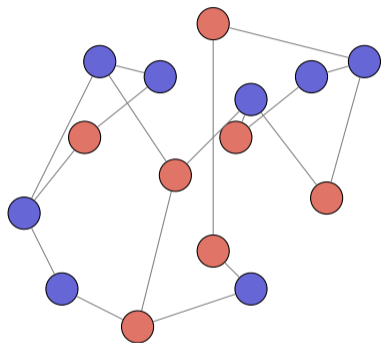


nodes **copy** neighbors along arrows

# Dynamics on networks



nodes **copy** neighbors along arrows



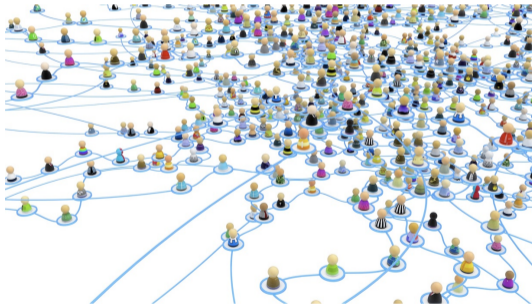
network after one step of the dynamics

# Why study dynamic processes on networks?

- These processes are inherently **dynamic**
  - ▶ states change over time
  - ▶ small local interactions can lead to large-scale effects
- **Key questions**
  - ▶ What are the possible long-term behaviors?
  - ▶ How fast does the system reaches equilibrium (if any)?
  - ▶ How can local interactions produce global behavior?

## The voter model

Given a **connected graph**  $G = (V, E)$ , each vertex is associated with an opinion 0 or 1. The **voter model** is a **Markov process**  $(\xi_t)_{t \geq 0}$  on the state space  $\{0, 1\}^V$ , where each vertex at **rate 1** selects uniformly at random one of its neighbours and adopts its opinion



Write [0] and [1] to denote the configurations  $\eta \equiv 0$  and  $\eta \equiv 1$ , respectively. These configurations are both **traps** for the dynamics: if all sites have the same opinion, then no change of opinion occurs

Denote by  $\xi_t(i)$  the opinion of vertex  $i$  at time  $t$ . We analyse the evolution of the fraction of **discordant edges**

$$\mathcal{D}_t = \frac{D_t}{M}, \quad D_t = |\{(i, j) \in E : \xi_t(i) \neq \xi_t(j)\}|,$$

where  $M = |E|$ . This is an interesting quantity because it monitors the **size of the boundary** between **the two opinions**

The **consensus time** is defined as

$$\tau_{cons} = \inf\{t \geq 0 : \xi_t(i) = \xi_t(j) \forall i, j \in V\}$$

For **finite graphs**, we know that  $\tau_{cons} < \infty$  **with probability 1** (either at [0] or [1])

The interest lies then in the determining the **relevant time scales** on which consensus is reached, and how it is reached.

## The voter model on the complete graph

The number of 1-opinions at time  $t$ , given by

$$O_t = \sum_{i \in V} \xi_t(i),$$

performs a **continuous-time nearest-neighbour random walk** on the set  $\{0, 1, \dots, n\}$  ( $n = |V|$ ) with transition rates

$$\begin{aligned} m \rightarrow m + 1 & \quad \text{at rate } m(n - m) \frac{1}{n - 1} \\ m \rightarrow m - 1 & \quad \text{at rate } (n - m)m \frac{1}{n - 1} \end{aligned}$$

This is the same as the **Moran model** from **population genetics**

Set  $\mathcal{O}_t = \frac{1}{n}O_t$  the fraction of 1-opinions at time  $t$ . Then the process  $(\mathcal{O}_{sn})_{s \geq 0}$  converges in law as  $n \rightarrow \infty$  to the Fisher-Wright diffusion  $(\theta_s)_{s \geq 0}$  on  $[0, 1]$  given by

$$d\theta_s = \sqrt{2\theta_s(1 - \theta_s)}dW_s,$$

where  $(W_s)_{s \geq 0}$  is a standard Brownian motion

The number of discordant edges is

$$D_t = \frac{O_t(n - O_t)}{2}$$

and therefore the proportion of discordant edges is

$$\mathcal{D}_t = \frac{O_t(n - O_t)}{n(n - 1)} = \frac{n}{n(n - 1)}O_t(1 - O_t)$$

It follows that the process  $(\mathcal{D}_{sn})_{s \geq 0}$  converges in law as  $n \rightarrow \infty$  to the process

$$(\theta_s(1 - \theta_s))_{s \geq 0}$$

In the mean field setting of the complete graph, the fraction of discordant edges is the product of the fractions of the two opinions.

The latter property on non-complete graphs, in particular, on random graphs

## The voter model on random regular graphs

Consider the **regular random graph**  $G_{d,n} = (V, E)$  of **degree**  $d \geq 3$ , consisting of

$$|V| = n \text{ vertices}$$

$$|E| = m = \frac{dn}{2} \text{ edges}$$

Recall that  $\mathcal{O}_t$  denotes the **fraction** of **1-opinions** at time  $t$ . Then **Chen, Choi, Cox 2016** showed that the process  $(\mathcal{O}_{sn})_{s \geq 0}$  **converges in law** as  $n \rightarrow \infty$  to the **Fisher-Wright diffusion**  $(\theta_s)_{s \geq 0}$  given by

$$d\theta_s = \sqrt{2\alpha_d \theta_s (1 - \theta_s)} dW_s,$$

where  $(W_s)_{s \geq 0}$  is a **standard Brownian motion**, and

$$\alpha_d = \frac{d-2}{d-1}$$

## The voter model on directed sparse random graphs

Avena, Capannoli, Hazra, Quattropiani 2023, Capannoli 2024

Under **mild conditions** on the sequence of **in- and out-degrees**, the same scaling applies and an **explicit formula** can be derived for the **diffusion constant**  $\alpha_{d^{in}, d^{out}}$

For instance, if  $d^{in} = d^{out}$  (Eulerian graph), then

$$\alpha_{d^{in}, d^{out}} = \left( \frac{m_2}{m_1^2} - 1 + \sqrt{1 - \frac{1}{m_1}} \right)^{-1},$$

where  $m_1, m_2$  are the **first and second moment** of the **limit of the empirical degree distribution**

## The contact process

Given a **connected graph**  $G = (V, E)$ , each vertex is associated with a state 0 (healthy) or 1 (infected). The **contact process** is a **Markov process**  $(\xi_t)_{t \geq 0}$  on the state space  $\{0, 1\}^V$ .

Each infected vertex **becomes healthy at rate 1**, **independently** of the states of the other vertices, while each healthy vertex **becomes infected at rate  $\lambda$  times the number of infected neighbours**, with  $\lambda \in (0, \infty)$  the **infection rate**

The **configuration** at time  $t$  is  $\xi_t = \{\xi_t(i) : i \in V\}$ , with  $\xi_t(i)$  the **state at time  $t$  of vertex  $i$**

Note that  $[0]$  is a **trap** for the dynamics: if **all sites are healthy**, then **no infection** will ever occur. The focus will be on understanding how the **extinction time**

$$\tau_{[0]} = \inf\{t \geq 0 : \xi_t(i) = 0 \forall i \in V\}$$

behaves as  $|V| = n \rightarrow \infty$ , depending on the **value of  $\lambda$**  and the **properties of the graph**. In particular, we will look at the **average extinction time** starting from the **configuration where every vertex is infected**  $\mathbb{E}_{[1]}[\tau_{[0]}]$

The contact process is **much harder** than the voter model because it does not have a nice dual. In fact, it is **self-dual**

## The contact process on the complete graph

The number of infections at time  $t$ , given by

$$I_t = \sum_{i \in V} \xi_t(i),$$

performs a **continuous-time nearest-neighbour random walk** on the set  $\{0, 1, \dots, n\}$  with transition rates

$$\begin{aligned} m \rightarrow m + 1 & \quad \text{at rate } \lambda m(n - m) \\ m \rightarrow m - 1 & \quad \text{at rate } m \end{aligned}$$

Write  $\mathcal{I}_t = \frac{1}{n} I_t$  for the **fraction** of infections at time  $t$ . This process is **continuous-time nearest-neighbour random walk** on the set  $\left\{0, \frac{1}{n}, \dots, \frac{n-1}{n}, 1\right\}$  with transition rates

$$\begin{aligned} x \rightarrow x + n^{-1} & \quad \text{at rate } \lambda x(1 - x)n^2 \\ x \rightarrow x - n^{-1} & \quad \text{at rate } xn \end{aligned}$$

This process has a **strong drift upward**, which becomes zero for  $x = 1 - \frac{1}{\lambda n}$ , i.e., very close to **full infection** when  $\lambda n \gg 1$

Let  $\tau_{[0]}$  be the **extinction time**. Then

$$\log \mathbb{E}_{[1]}[\tau_{[0]}] = n(1 + \log(\lambda n)) + o(n), \quad n \rightarrow \infty$$

The contact process on the complete graph is **supercritical** for all  $\lambda > 0$  as  $n \rightarrow \infty$

For any  $\lambda \in (0, \infty)$ ,

$$\lim_{n \rightarrow \infty} \mathbb{P}_{[1]} \left( \frac{\tau_{[0]}}{\mathbb{E}_{[1]}[\tau_{[0]}]} > t \right) = e^{-t} \quad \forall t > 0 \quad \text{metastability}$$

In the **mean-field setting** of the **complete graph**, the **fraction of infected vertices** performs a random walk.

The latter property fails on **non-complete graphs**, in particular, on **random graphs**:  $(\mathcal{I}_t)_{t \geq 0}$  **loses the Markov property**

- ▶ **Chatterjee, Durrett 2009, Mountford, Mourrat, Valesin, Yao 2016**: the contact process on the **configuration model with power law degree distribution** is **supercritical** regardless of the value of  $\lambda$
- ▶ **Can, Schapira 2015, Mourrat, Valesin, Yao 2013, Linker, Mitsche, Schapira, Valesin 2020**: the case  $\tau \in (1, 2]$  is included
- ▶ **Cator, Don 2021**: contact process on **configuration model with i.i.d. degrees**

## Limitations of static networks

So far, the underlying graph is **fixed in time**. This assumption is often **unrealistic**:

- Social contacts **change over time**
- Individuals **move and form new connections**
- Interaction patterns are inherently **dynamic**

## Two coupled dynamics

In many systems, we have two interacting processes:

- ▶ **State dynamics:**
  - opinions, infections, activity
- ▶ **Network dynamics:**
  - edges appear and disappear
  - connections are resampled

These two levels influence each other:

- ▶ Who you meet affects your state
- ▶ Your state may affect whom you meet

This leads to a **co-evolutionary feedback between vertex and network dynamics**