Nonlinear Perron-Frobenius theory and applications

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ingular vectors

Multihomogeneous PF theorem

Example applications

Conclusions

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Introduction •••••••

Introduction:

Cone theoretic proof of the PF theorem for positive matrices

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Perron eigenvector

Consider the problem:

Find x such that $Ax = \lambda x$

Perron eigenvector

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Perron-Frobenius theorem

If A is positive then there exists a unique solution $x^\star > 0, \; \|x^\star\| = 1$ and

$$x_{m+1} = Ax_m / \|Ax_m\| \xrightarrow{m \to \infty} x^*$$

for any choice of $x_0 > 0$.

Perron eigenvector

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for any choice of $x_0 > 0$.

How do you prove that?

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Cone-theoretic proof

Hilbert-Birkhoff projective metric

x, y positive vectors $d_H(x, y) = \log\left(\max_i \frac{x_i}{y_i} \max_i \frac{y_i}{x_i}\right)$

 d_H is projective i.e. $d_H(x,y) = d_H(\alpha x, \beta y)$, $\forall \alpha, \beta > 0$. Thus

Example applications

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Cone-theoretic proof

Observation 1

Eigenvector	\iff	Fixed point
$Ax = \lambda x$	\iff	$d_H(Ax, x) = 0$

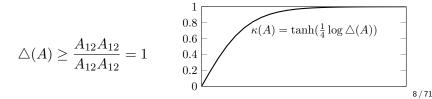
Observation 2

Take any norm $\|\cdot\|$ and let $S_{++} = \{x > 0 : \|x\| = 1\}$ Then (S_{++}, d_H) is a complete metric space.

Cone-theoretic proof

Birkhoff-Hopf theorem

Let A be any positive matrix. Then $d_H(Ax, Ay) \leq \kappa(A) d_H(x, y) \qquad \forall x, y > 0$ where $\kappa(A) = \tanh(\frac{1}{4}\operatorname{diam}(A)) = \tanh(\frac{1}{4}\log \triangle(A))$, and $\Delta(A) = \Delta(A^T) = \max_{ijhk} \frac{A_{ij}A_{hk}}{A_{ik}A_{hj}}$



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Birkhoff contraction ratio - example

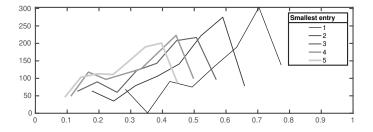


Figure: Each line shows the distribution of $\kappa(A)$ over 1000 random matrices A with entries between s and 10. Different curves correspond to different values of $s \in \{1, 2, \ldots, 5\}$.

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Cone-theoretic proof

lf

$$G(x) = Ax / \|Ax\|$$

then

$$d_H(G(x), G(y)) = d_H(Ax, Ay) \le \kappa(A)d_H(x, y)$$

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Cone-theoretic proof

lf

$$G(x) = Ax / \|Ax\|$$

then

$$d_H(G(x), G(y)) = d_H(Ax, Ay) \le \kappa(A)d_H(x, y)$$

Thus: if A is a positive matrix, G is a contraction in the metric space (S_{++}, d_H) , with contraction constant $\kappa(A)$.

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Cone-theoretic proof

lf

$$G(x) = Ax / \|Ax\|$$

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Thus: if A is a positive matrix, G is a contraction in the metric space (S_{++}, d_H) , with contraction constant $\kappa(A)$.

Using the Banach fixed point theorem we conclude that:

 $Ax_m/\|Ax_m\| \xrightarrow{m \to \infty} x^*$ as $\kappa(A)^m$ and x^* is the unique positive eigenvector of A

Introduction: Nonlinear matrix eigenvectors

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Nonlinear Perron eigenvector

Let
$$f:\mathbb{R}^n\to\mathbb{R}^n$$
 be such that $x>0\Longrightarrow f(x)>0$

Consider the problem

Find x such that $Af(x) = \lambda x$

For the time being: $f(x) = x^{\alpha} =$ component-wise power, $\alpha \neq 0$

Example applications

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Nonlinear Perron eigenvector

Let
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Consider the problem

Find x such that $Af(x) = \lambda x$

For the time being: $f(x) = x^{\alpha} =$ component-wise power, $\alpha \neq 0$

Can we do the same?

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Dilatations

$$\alpha \in \mathbb{R} \implies d_H(x^{\alpha}, y^{\alpha}) = |\alpha| d_H(x, y)$$

Therefore

$$d_H(Af(x), Af(y)) \le \kappa(A) d_H(f(x), f(y)) = \underbrace{|\alpha| \kappa(A)}_{\text{contraction constant}} d_H(x, y)$$

Example applications

Nonlinear Perron eigenvector

Consider the problem

Find x such that $Ax^{\alpha} = \lambda x$

Theorem

If $|\alpha|\kappa(A)<1$ then there exists a unique solution $x^{\star}>0,\;\|x^{\star}\|=1$ and

$$x_{m+1} = A x_m^{\alpha} / \|A x_m^{\alpha}\| \xrightarrow{m \to \infty} x^{\star} \text{ as } \left(|\alpha|\kappa(A)\right)^m$$

What about other spectral equations?

Singular vectors: PF theorem for singular vectors Singular vectors ○●○○○○○○○○○○○ Multihomogeneous PF theorem

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Singular vectors

Consider the problem

Find
$$(x,y)$$
 such that
$$\begin{cases} Ay = \lambda x \\ A^T x = \lambda y \end{cases}$$

$$\mathcal{A} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} & A \\ A^T & \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \lambda \begin{bmatrix} x \\ y \end{bmatrix}$$

Problem: Even if A is positive, it holds

$$\kappa(A) = \kappa(A^T) < 1$$
 but $\kappa\left(\begin{bmatrix} A \\ A^T \end{bmatrix} \right) = 1$

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Problem: Even if A is positive, it holds

$$\kappa(A) = \kappa(A^T) < 1$$
 but $\kappa\left(\begin{bmatrix} A \\ A^T \end{bmatrix} \right) = 1$

Solution: "Higher-order" Hilbert metric

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"Order-2" Birkhoff-Hopf theorem

$$\begin{bmatrix} d_H(Ay, Av) \\ d_H(A^Tx, A^Tu) \end{bmatrix} \leq \begin{bmatrix} \kappa(A) \\ \kappa(A^T) \end{bmatrix} \begin{bmatrix} d_H(x, u) \\ d_H(y, v) \end{bmatrix} = K(\mathcal{A}) \begin{bmatrix} d_H(x, u) \\ d_H(y, v) \end{bmatrix}$$

We call $K(\mathcal{A})$ "Lipschitz matrix" of $\mathcal{A} = \begin{bmatrix} A \\ A^T \end{bmatrix} : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n \times \mathbb{R}^n$

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"Order-2" Birkhoff-Hopf theorem

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We call $K(\mathcal{A})$ "Lipschitz matrix" of $\mathcal{A} = \begin{bmatrix} A \\ A^T \end{bmatrix} : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n \times \mathbb{R}^n$

Theorem

For any positive matrix A there exists a metric δ_H on $\mathbb{R}^n\times\mathbb{R}^n$ st

$$\delta_H\left(\mathcal{A}\begin{bmatrix}x\\y\end{bmatrix}, \mathcal{A}\begin{bmatrix}u\\v\end{bmatrix}\right) \le \rho\left(K(\mathcal{A})\right)\delta_H\left(\begin{bmatrix}x\\y\end{bmatrix}, \begin{bmatrix}u\\v\end{bmatrix}\right)$$

for all (x,y) > 0, (u,v) > 0.

 δ_H is defined in terms of any positive eigenvector of ${\cal A}$

... moreover

Observation 1

Take any norm $\|\cdot\|$ and let $S^2_{++} = \{(x,y) > 0 : \|x\| = \|y\| = 1\}$ Then (S^2_{++}, δ_H) is a complete metric space

... moreover

Observation 1

Take any norm
$$\|\cdot\|$$
 and let $S^2_{++} = \{(x,y) > 0 : \|x\| = \|y\| = 1\}$
Then (S^2_{++}, δ_H) is a complete metric space

Observation 2

If G is the "normalized version" of
$$\mathcal{A}$$

$$G\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}Ay/||Ay||\\A^Tx/||A^Tx||\end{bmatrix}$$
then
$$\delta_H\left(G\left(\begin{bmatrix}x\\y\end{bmatrix}\right), G\left(\begin{bmatrix}u\\v\end{bmatrix}\right)\right) = \delta_H\left(\mathcal{A}\begin{bmatrix}x\\y\end{bmatrix}, \mathcal{A}\begin{bmatrix}u\\v\end{bmatrix}\right)$$

... moreover

Observation 3

For this particular case we have

$$\rho(K(\mathcal{A})) = \rho\left(\begin{bmatrix} \kappa(A) \\ \kappa(A^T) \end{bmatrix} \right) = \kappa(A)$$

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Perron-Frobenius theorem for singular values

Consider the problem

Find
$$(x, y)$$
 such that
$$\begin{cases} Ay = \lambda x \\ A^T x = \lambda y \end{cases}$$

Theorem

If A is positive then there exists a unique solution $x^\star,y^\star>0$ such that $\|x^\star\|=\|y^\star\|=1$ and

$$\begin{bmatrix} x_{m+1} \\ y_{m+1} \end{bmatrix} = \begin{bmatrix} Ay_m / \|Ay_m\| \\ A^T x_m / \|A^T x_m\| \end{bmatrix} \xrightarrow{m \to \infty} \begin{bmatrix} x^\star \\ y^\star \end{bmatrix} \text{ as } \kappa(A)^m$$

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Singular vectors: Nonlinear matrix singular vectors

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More in general

Find
$$(x,y)$$
 such that
$$\begin{cases} Ay^{\beta} = \lambda x \\ Bx^{\alpha} = \mu y \end{cases}$$

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More in general

Find
$$(x,y)$$
 such that
$$\begin{cases} Ay^{\beta} = \lambda x \\ Bx^{\alpha} = \mu y \end{cases}$$

Application examples:

• Matrix norms:

$$\begin{array}{l} \text{Compute } \|A\|_{p,q} = \max_{x \neq 0} \|Ax\|_q / \|x\|_p \\ \text{Boils down to } \textcircled{} \text{ for } \alpha = 1/(p-1) \text{ and } \beta = q/(q-1) \end{array}$$

Matrix rescaling (matrix Sibkhorn method) and entropy minimization:

Find a diagonal D_1, D_2 such that D_1AD_2 is doubly stochastic Boils down to \circledast for $\alpha=\beta=-1$

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Birkhoff-Hopf theorem

$$\begin{bmatrix} d_H(Ay^{\beta}, Av^{\beta}) \\ d_H(Bx^{\alpha}, Bu^{\alpha}) \end{bmatrix} \leq \underbrace{\begin{bmatrix} \kappa(A) \\ \kappa(B) \end{bmatrix}}_{K} \begin{bmatrix} |\alpha| \\ |\beta| \end{bmatrix}_{K} \begin{bmatrix} d_H(x, u) \\ d_H(y, v) \end{bmatrix}$$

Theorem

There exists a metric δ_H such that

$$\delta_{H}\left(\begin{bmatrix}Ay^{\beta}\\Bx^{\alpha}\end{bmatrix},\begin{bmatrix}Av^{\beta}\\Bu^{\alpha}\end{bmatrix}\right) \leq \rho(K)\,\delta_{H}\left(\begin{bmatrix}x\\y\end{bmatrix},\begin{bmatrix}u\\v\end{bmatrix}\right)$$

and $\rho(K) = \sqrt{|\alpha\beta|\kappa(A)\kappa(B)}.$

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Nonlinear Perron singular vector

Find
$$(x, y)$$
 such that
$$\begin{cases} Ay^{\beta} = \lambda x \\ Bx^{\alpha} = \mu y \end{cases}$$

Theorem

If $|\alpha\beta|\kappa(A)\kappa(B)<1$ then there exists a unique solution $x^\star,y^\star>0$ such that $\|x^\star\|=\|y^\star\|=1$ and

$$\begin{bmatrix} x_{m+1} \\ y_{m+1} \end{bmatrix} = \begin{bmatrix} Ay_m^{\beta}/\|Ay_m^{\beta}\| \\ Bx_m^{\alpha}/\|Bx_m^{\alpha}\| \end{bmatrix} \xrightarrow{m \to \infty} \begin{bmatrix} x^{\star} \\ y^{\star} \end{bmatrix} \text{ as } \left(|\alpha\beta|\kappa(A)\kappa(B)\right)^{m/2}$$

Moreover: If $A = B^T$ then $\lambda = \mu$

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Singular vectors:

Example of application: matrix operator norm

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Mixed matrix norms

Compute
$$||A|| = \max_{x \neq 0} \frac{||Ax||}{||x||}$$

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Mixed matrix norms

Compute
$$||A||_{p,q} = \max_{x \neq 0} \frac{||Ax||_p}{||x||_q}, \quad 1 < p, q < +\infty$$

NP-hard to approximate if $p=q\neq 1,2,\infty$ [Hendrickx, Olshevsky, 2009]

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Mixed matrix norms

$$\text{Compute } \|A\|_{p,q} = \ \max_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_q}, \quad 1 < p,q < +\infty$$

NP-hard to approximate if $p = q \neq 1, 2, \infty$ [Hendrickx, Olshevsky, 2009]

Observations

1. If
$$A > 0$$
 then $\max_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_q} = \max_{x > 0} \frac{\|Ax\|_p}{\|x\|_q}$

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Mixed matrix norms

$$\text{Compute } \|A\|_{p,q} = \ \max_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_q}, \quad 1 < p,q < +\infty$$

NP-hard to approximate if $p=q\neq 1,2,\infty$ [Hendrickx, Olshevsky, 2009]

Observations

1. If
$$A > 0$$
 then $\max_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_q} = \max_{x > 0} \frac{\|Ax\|_p}{\|x\|_q}$

2.
$$\nabla_x \left(\frac{\|Ax\|_p}{\|x\|_q} \right) = 0 \iff A^T (Ax)^{p-1} = \sigma x^{q-1}$$

Example applications

$$A^{T}(Ax)^{p-1} = \sigma x^{q-1} \iff \begin{cases} (Ax)^{p-1} = \lambda y \\ A^{T}y = \mu x^{q-1} \end{cases}$$

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$$\begin{split} A^{T}(Ax)^{p-1} &= \sigma \, x^{q-1} \iff \begin{cases} (Ax)^{p-1} &= \lambda \, y \\ A^{T}y &= \mu \, x^{q-1} \end{cases} \\ & \Longleftrightarrow \begin{cases} Ax &= \widetilde{\lambda} \, y^{\frac{1}{p-1}} \\ A^{T}y &= \mu \, x^{q-1} \end{cases} \end{split}$$

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$$\begin{split} A^{T}(Ax)^{p-1} &= \sigma \, x^{q-1} \iff \begin{cases} (Ax)^{p-1} &= \lambda \, y \\ A^{T}y &= \mu \, x^{q-1} \end{cases} \\ & \Longleftrightarrow \begin{cases} Ax &= \widetilde{\lambda} \, y^{\frac{1}{p-1}} \\ A^{T}y &= \mu \, x^{q-1} \end{cases} \\ \begin{pmatrix} u &= x^{q-1} \\ v &= y^{\frac{1}{p-1}} \end{pmatrix} \iff \begin{cases} Au^{\frac{1}{q-1}} &= \widetilde{\widetilde{\lambda}} \, v \\ A^{T}v^{p-1} &= \widetilde{\mu} \, u \end{cases} \end{split}$$

Example applications

$$\begin{split} A^{T}(Ax)^{p-1} &= \sigma \, x^{q-1} \iff \begin{cases} (Ax)^{p-1} &= \lambda \, y \\ A^{T}y &= \mu \, x^{q-1} \end{cases} \\ & \Longleftrightarrow \begin{cases} Ax &= \widetilde{\lambda} \, y^{\frac{1}{p-1}} \\ A^{T}y &= \mu \, x^{q-1} \end{cases} \\ \begin{pmatrix} u &= x^{q-1} \\ v &= y^{\frac{1}{p-1}} \end{pmatrix} \iff \begin{cases} Au^{\frac{1}{q-1}} &= \widetilde{\widetilde{\lambda}} \, v \\ A^{T}v^{p-1} &= \widetilde{\mu} \, u \end{cases} \end{split}$$

.

Computing $||A||_{p,q}$ is equivalent to solving $\begin{cases} Au^{\alpha} = \\ A^T v^{\beta} \end{cases}$

$$\begin{cases} Au^{\alpha} = \lambda \, v \\ A^T v^{\beta} = \mu \, u \end{cases}$$

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Mixed matrix norms: Theorem

Compute
$$||A||_{p,q} = \max_{x \neq 0} \frac{||Ax||_p}{||x||_q}, \quad 1 < p, q < +\infty$$

Theorem

We can compute
$$||A||_{p,q}$$
 if $q > \kappa(A)^2(p-1) + 1$.

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Mixed matrix norms: Theorem

Compute
$$||A||_{p,q} = \max_{x \neq 0} \frac{||Ax||_p}{||x||_q}, \quad 1 < p, q < +\infty$$

Theorem

We can compute
$$||A||_{p,q}$$
 if $q > \kappa(A)^2(p-1) + 1$.

The condition is **necessary and sufficient** for $A_{\varepsilon} = \begin{bmatrix} \varepsilon & 1 \\ 1 & \varepsilon \end{bmatrix}$, $\varepsilon > 0$

Example applications

Mixed matrix norms: Theorem

Compute
$$||A||_{p,q} = \max_{x \neq 0} \frac{||Ax||_p}{||x||_q}, \quad 1 < p, q < +\infty$$

Theorem

We can compute
$$||A||_{p,q}$$
 if $q > \kappa(A)^2(p-1) + 1$.

The condition is **necessary and sufficient** for $A_{\varepsilon} = \begin{bmatrix} \varepsilon & 1 \\ 1 & \varepsilon \end{bmatrix}$, $\varepsilon > 0$ Moreover, if for example $\varepsilon = 3/4$, we have

$$\begin{array}{ll} \mbox{Classical condition ([1-4]):} & (q-1) \geq (p-1) \\ \mbox{New condition:} & (q-1) > 0.0016 \cdot (p-1) \end{array}$$

[1] Boyd ('73), [2] N.Higham ('92), [3] Bhaskara, Vijayaraghavan ('11), [4] Gautier, Hein ('16)

The contractive case

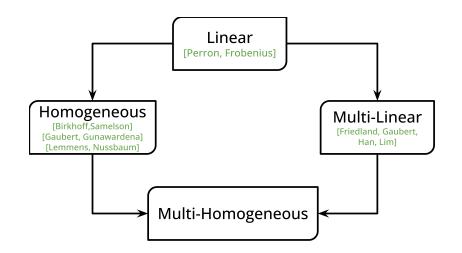
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Multihomogeneous operators

The spectral equation

Find
$$(x, y)$$
 such that
$$\begin{cases} Ag(y) = Ay^{\beta} = \lambda x \\ Bf(x) = Bx^{\alpha} = \mu y \end{cases}$$

is an example of a multihomogeneous spectral problem, just like

Find x such that $Af(x) = Ax^{\alpha} = \lambda x$

is an example of a homogeneous spectral problem.

Multihomogeneous operators

Homogeneity

 $F: \mathbb{R}^n \to \mathbb{R}^n$ is θ -homogeneous, in symbols $F \in \hom(\theta)$, if $F(\lambda x) = \lambda^{\theta} F(x)$ for all $\lambda > 0$ and all x

 $\theta \in \mathbb{R}$ is called homogeneity degree

Multihomogeneity

 $X_d := \mathbb{R}^{n_1} \times \cdots \times \mathbb{R}^{n_d}$

 $F: X_d \to X_d$ is Θ -homogeneous, in symbols $F \in \hom(\Theta)$, if

 $F_i(x_1,\ldots,\lambda x_j,\ldots,x_d) = \lambda^{\Theta_{ij}}F_i(x)$ for all $\lambda > 0$ and all $x \in X_d$

 $\boldsymbol{\varTheta} \in \mathbb{R}^{d \times d}$ is called homogeneity matrix

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Examples: Linear and multilinear operators

• $F(x) = Ax \in \text{hom}(1)$

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- $F(x) = Ax \in \text{hom}(1)$
- $F(x) = Ax^{\alpha} \in \hom(\alpha)$

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- $F(x) = Ax \in \text{hom}(1)$
- $F(x) = Ax^{\alpha} \in \hom(\alpha)$
- $F(x) = Af(x) \in \hom(\theta)$ provided $f \in \hom(\theta)$

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- $F(x) = Ax \in hom(1)$
- $F(x) = Ax^{\alpha} \in \hom(\alpha)$
- $F(x) = Af(x) \in \hom(\theta)$ provided $f \in \hom(\theta)$

•
$$F(x,y) = \begin{bmatrix} Ay \\ Bx \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right)$$

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- $F(x) = Ax \in \text{hom}(1)$
- $F(x) = Ax^{\alpha} \in \hom(\alpha)$
- $F(x) = Af(x) \in \hom(\theta)$ provided $f \in \hom(\theta)$

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$$F(x, y) = \begin{bmatrix} Ay \\ Bx \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}\right)$$

• $F(x, y) = \begin{bmatrix} Ay^{\beta} \\ Bx^{\alpha} \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} 0 & \beta \\ \alpha & 0 \end{bmatrix}\right)$

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- $F(x) = Ax \in \text{hom}(1)$
- $F(x) = Ax^{\alpha} \in \hom(\alpha)$
- $F(x) = Af(x) \in \hom(\theta)$ provided $f \in \hom(\theta)$

•
$$F(x, y) = \begin{bmatrix} Ay \\ Bx \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}\right)$$

• $F(x, y) = \begin{bmatrix} Ay^{\beta} \\ Bx^{\alpha} \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} 0 & \beta \\ \alpha & 0 \end{bmatrix}\right)$
• $F(x, y) = \begin{bmatrix} Af(x, y) \\ Bg(x, y) \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} \alpha_1 & \alpha_2 \\ \beta_1 & \beta_2 \end{bmatrix}\right)$ provided
 $f \in \operatorname{hom}([\alpha_1, \alpha_2]), g \in \operatorname{hom}([\beta_1, \beta_2])$

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Examples: Linear and multilinear operators

If T is a 3rd-order tensor, define z = Txy as $z_i = \sum_{jk} T_{jk} x_j y_k$

•
$$F(x, y, z) = \begin{bmatrix} T_1 yz \\ T_2 xz \\ T_3 xy \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \right)$$

Example applications

Examples: Linear and multilinear operators

If T is a 3rd-order tensor, define z = Txy as $z_i = \sum_{jk} T_{jk} x_j y_k$

- $F(x, y, z) = \begin{bmatrix} T_1 yz \\ T_2 xz \\ T_3 xy \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}\right)$ • $F(x, y, z) = \begin{bmatrix} T_1 f(x, y, z) \\ T_2 g(x, y, z) \end{bmatrix} \in \operatorname{hom}\left(\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_2 \end{bmatrix}\right) \text{ provided}$
- $F(x, y, z) = \begin{bmatrix} T_1 f(x, y, z) \\ T_2 g(x, y, z) \\ T_3 h(x, y, z) \end{bmatrix} \in \operatorname{hom} \left(\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \right)$ provided $f \in \operatorname{hom}([a_1, a_2, a_3]), g \in \operatorname{hom}([b_1, b_2, b_3]), h \in \operatorname{hom}([c_1, c_2, c_3])$

Example applications

Examples: Linear and multilinear operators

If T is a 3rd-order tensor, define z=Txy as $z_i=\sum_{jk}T_{jk}x_jy_k$

• $F(x, y, z) = \begin{bmatrix} T_1 yz \\ T_2 xz \\ T_3 xy \end{bmatrix} \in \operatorname{hom} \left(\begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \right)$ • $F(x, y, z) = \begin{bmatrix} T_1 f(x, y, z) \\ T_2 g(x, y, z) \\ T_3 h(x, y, z) \end{bmatrix} \in \operatorname{hom} \left(\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \right)$ provided $f \in \operatorname{hom}([a_1, a_2, a_3]), g \in \operatorname{hom}([b_1, b_2, b_3]), h \in \operatorname{hom}([c_1, c_2, c_3])$

General tensor mapping

For a collection of tensors
$$T = [T_1, \dots, T_d]$$
, $x = [x_1, \dots, x_d] \in X_d$,
 $F(x) = Tf(x) \in \hom(\Theta)$ provided $f \in \hom(\Theta)$

Singular vectors

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Multihomogeneous eigenproblem

We want to consider systems of spectral equations...

Example applications

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Multihomogeneous eigenproblem

We want to consider systems of spectral equations...

 $x = (x_1, \ldots, x_d) \in X_d$ and $\lambda \in \mathbb{R}^d$ are an eigenpair for the multhom operator $F: X_d \to X_d$ if $\begin{cases} F_1(x) = \lambda_1 x_1 \\ F_2(x) = \lambda_2 x_2 \\ \vdots \\ F_d(x) = \lambda_d x_d \end{cases}$ In symbols $F(x) = \boldsymbol{\lambda} \otimes x$

Let $F: X_d \to X_d \in \hom(\Theta)$ be such that

- Continuous
- Positive: F(x) > 0 if x > 0
- Order-preserving: $F(x) \ge F(y)$ if $x \ge y$
- $\rho(|\varTheta|) < 1, \ |\cdot| = {\rm component}$ wise
- There exists v>0 such that $v^T|\varTheta|=\lambda v^T$, $\|v\|=1$

Then

• there exists a unique $x^* \in S_d$ st $x^* > 0$, $F(x^*) = {oldsymbol \lambda} \otimes x^*$

•
$$x^{(k+1)} = G(x^{(k)}) \rightarrow x^*$$
 as $\rho(|\Theta|)^k$

where $G_i(x) = F_i(x) / \|F_i(x)\|_i$, and $S_d = \{x \in X_d : \|x_i\|_i = 1\}$

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Multihomogeneous BH theorem

A. It applies to maps of the form $F(x) = Tf(x) \in \hom(\Theta)$.

Example applications

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Multihomogeneous BH theorem

- A. It applies to maps of the form $F(x) = Tf(x) \in \hom(\Theta)$.
- B. It is based on the mode-j tensor contraction ratio

$$\kappa_{j}(T) = \tanh\left(\frac{1}{4}\log \triangle_{j}(T)\right)$$

with $\triangle_{j}(T) = \max_{\substack{i_{1},\dots,i_{m}\\k_{1},\dots,k_{m}}} \frac{T_{i_{1},\dots,i_{j-1},i_{j},i_{j+1},\dots,i_{m}}}{T_{i_{1},\dots,i_{j-1},k_{j},i_{j+1},\dots,i_{m}}} \frac{T_{k_{1},\dots,k_{j-1},k_{j},k_{j+1},\dots,k_{m}}}{T_{k_{1},\dots,k_{j-1},i_{j},k_{j+1},\dots,k_{m}}}$

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Multihomogeneous BH theorem

A. It applies to maps of the form $F(x) = Tf(x) \in \hom(\Theta)$.

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C. It states that

There exists $K(\mathbf{T}, \Theta) \in \mathbb{R}^{d \times d}$ defined in terms of $\kappa_j(T_i)$ and Θ , such that Θ in the PF theorem can be replaced by $K(\mathbf{T}, \Theta)$: • if there exists $T_i > 0$, then $\rho(K(\mathbf{T}, \Theta)) < \rho(\Theta)$ • otherwise, $\kappa_j(T_i) = 1$ for all i, j and $K(\mathbf{T}, \Theta) = \Theta$

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Example: tensor singular vectors



Find
$$(x, y, z)$$
 such that
$$\begin{cases} T_1 y^{\beta} z^{\gamma} = \lambda x \\ T_2 x^{\alpha} z^{\gamma} = \mu y \\ T_3 x^{\alpha} y^{\beta} = \sigma z \end{cases}$$

Tensor norm: $||T||_{p,q,r} = \max_{x,y \neq 0} \frac{||Txy||_p}{||x||_q ||y||_r}$ [Friedland, Gaubert, Han, 2016]

$$K(\mathbf{T}, \Theta) = \begin{bmatrix} 0 & \kappa_2(T_1) & \kappa_3(T_1) \\ \kappa_2(T_2) & 0 & \kappa_3(T_2) \\ \kappa_2(T_3) & \kappa_3(T_3) & 0 \end{bmatrix} \begin{bmatrix} |\alpha| & & \\ & |\beta| & \\ & & |\gamma| \end{bmatrix}$$

Example applications

Conclusions

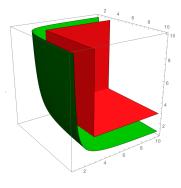
Comparison with Gaubert and Friedland

Theorem

[Friedland, Gaubert, Han], [Lim]

If T is "weakly irreducible" and $p,q,r\geq 3$ then there exist unique (x,y,z)>0 that realize that maximum





Singular vectors 000000000000000 Multihomogeneous PF theorem

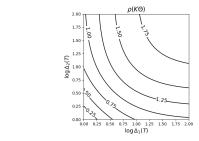
Example applications

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Example: tensor singular vectors

Find
$$(x, y)$$
 such that
$$\begin{cases} Tx^{\alpha}y^{\beta} = \lambda x \\ Sx^{\alpha}x^{\alpha} = \mu y \end{cases}$$

$$K(\mathbf{T}, \Theta) = \begin{bmatrix} \kappa_2(T_1) & \kappa_3(T_1) \\ \kappa_2(T_2) + \kappa_3(T_2) & 0 \end{bmatrix} \begin{bmatrix} |\alpha| \\ |\beta| \end{bmatrix}$$



Multihomogeneous PF theorem: Non-expansive case

Example applications

Conclusions

Matrix Perron–Frobenius theorem

Let $A \in \mathbb{R}^{n \times n}$ be such that $A \ge 0$. Then:

• There exists $x \ge 0$ such that $Ax = \lambda x$

•
$$\lambda \ge 0$$
 and $\lambda = \rho(A)$

if additionally, \boldsymbol{A} is irreducible, then

• $\rho(A) > 0$ and x is unique

if additionally, \boldsymbol{A} is primitive (aperiodic), then

•
$$x^{(k+1)} = G(x^{(k)}) = Ax^{(k)}/||Ax^{(k)}|| \longrightarrow x$$
, as $k \to \infty$

Linear operators F(x) = Ax are continuous and hom(1). Moreover, F is positive and order-preserving iff $A \ge 0$.

All the above "irreducibility assumptions" are not needed if $F \in \hom(\Theta)$ and $\rho(\Theta) < 1$ (or $\rho(T, \Theta) < 1$)

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Spectral radius

Observation

Let
$$F(x) \in hom(\theta)$$
. Then $F(x) = \lambda x$ iff $F(\alpha x) = (\alpha^{\theta-1}\lambda)\alpha x$.
 \implies Each eigenvector has infinitely many eigenvalues.

The notion of spectral radius makes sense only for $\theta = 1$

For multihomogeneous operators we will need $\varTheta \geq 0$ and $\rho(\varTheta) = 1$

Singular vectors

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Spectral radius via Gelfand formula

Definition

Homogeneous spectral radius

Let $F \in \hom(1)$ be continuous and order-preserving. Define

$$\rho(F) = \lim_{k \to \infty} \|F^k\|_+^{1/k} := \lim_{k \to \infty} \sup_{x \ge 0, x \ne 0} \left(\frac{\|F^k(x)\|}{\|x\|}\right)^{1/k}$$

Multihomogeneous PF theorem

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Irreducible and primitive matrices

There are different ways to define irreducibility / primitivity of a nonnegative matrix $A \in \mathbb{R}^{n \times n}$.

Irreducible and primitive matrices

There are different ways to define irreducibility / primitivity of a nonnegative matrix $A \in \mathbb{R}^{n \times n}$.

Irreducible iff

$$\sum_{k=0}^{n} A^k x > 0$$
 for all $x \ge 0$, $x \ne 0$

Primitive iff

There exists k st $A^k x > 0$ for all $x \ge 0$, $x \ne 0$

Remark: primitive \implies irreducible

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Homogeneous PF theorem

 $F \in hom(1)$ continuous, order-preserving is irreducible iff $\sum_{k=0}^{n} F^{k}(x) > 0$ for all $x \ge 0, x \ne 0$.

Example applications

Homogeneous PF theorem

 $F \in hom(1)$ continuous, order-preserving is **irreducible** iff $\sum_{k=0}^{n} F^{k}(x) > 0$ for all $x \ge 0, x \ne 0$.

Theorem

[Nussbaum, Eveson, Lemmens, Gaubert, ...]

Let $F \in hom(1)$ continuous, order-preserving, irreducible. Then,

- there exists $x^* > 0$ st $F(x^*) = \lambda x^*$
- $\lambda = \rho(F) > 0$ and $\rho(F) = \max\{|\mu| : F(x) = \mu x\}$

if moreover the Jacobian $F^\prime(x^*)$ is irreducible, then

• x^* is the unique positive eigenvector of F

if moreover the Jacobian $F^\prime(x^\ast)$ is primitive, then

•
$$x^{(k+1)} = G(x^{(k)}) = F(x^{(k)})/\|F(x^{(k)})\| \longrightarrow x$$
, as $k \to \infty$

Note: $F \in hom(1)$ is order-preserving iff $F'(x) \ge 0$ for all $x \ge 0$

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Example: Matrix-inheritance

$$\begin{split} F(x) &= g(Af(x)) \in \hom(1) \text{ with } f \in \hom(\theta), g \in \hom(\theta^{-1}). \end{split}$$
 For example, $F(x) = (Ax^{\alpha})^{1/\alpha}.$

Then

If A is irreducible, then

- there exists $x^* > 0$ st $F(x^*) = \lambda x^*$
- $\lambda=\rho(F)>0$ and $\rho(F)=\max\{|\mu|:F(x)=\mu x\}$

• x^* is the unique positive eigenvector of F

If moreover A is primitive, then

•
$$x^{(k+1)} = G(x^{(k)}) = F(x^{(k)})/\|F(x^{(k)})\| \longrightarrow x^*$$
, as $k \to \infty$

Example applications

Conclusions

Multihomogeneous spectral radius

Definition

Multihomogeneous spectral radius

Let $F: X_d \to X_d \in \hom(\Theta)$ be continuous and order-preserving. Assume that

- $\Theta \geq 0$ and $\rho(\Theta) = 1$
- there exists v>0 such that $v^T \Theta = \lambda v^T$, $\|v\| = 1$

Define

Theorem

Let $F \in \text{hom}(\Theta)$ continuous, order-preserving, irreducible. Assume $\Theta \ge 0$, $\rho(\Theta) = 1$ and $v^T \Theta = \lambda v^T$ with v > 0, ||v|| = 1. For $\lambda \in \mathbb{R}^d$, define $|||\lambda|||_v = |\lambda_1|^{v_1} \cdots |\lambda_d|^{v_d} = \exp ||\log(|\lambda|)||_{1,v}$

Theorem

Let $F \in hom(\Theta)$ continuous, order-preserving, irreducible. Assume $\Theta > 0$, $\rho(\Theta) = 1$ and $v^T \Theta = \lambda v^T$ with v > 0, ||v|| = 1. For $\lambda \in \mathbb{R}^d$, define $\|\boldsymbol{\lambda}\|_{\mathcal{A}} = |\lambda_1|^{v_1} \cdots |\lambda_d|^{v_d} = \exp \|\log(|\boldsymbol{\lambda}|)\|_{1,v}$ Then, for $S_d = \{x \in X_d : ||x_1||_1 = \cdots = ||x_d||_d = 1\}$, it holds • there exist $x^* \in S_d$, $x^* > 0$ and $\lambda \in \mathbb{R}^d$ st $F(x^*) = \lambda \otimes x^*$ • $\boldsymbol{\lambda} > 0$ and $\|\|\boldsymbol{\lambda}\|\|_{v} = \rho_{v}(F) = \max\{\|\|\boldsymbol{\mu}\|\|_{v} : F(x) = \boldsymbol{\mu} \otimes x\}$ if moreover the Jacobian $F'(x^*)$ is irreducible, then • $x^* \in S_d$ is the unique positive eigenvector of F in X_d if moreover the Jacobian $F'(x^*)$ is primitive, then

•
$$x^{(k+1)} = G(x^{(k)}) = \left(\frac{F_1(x^{(k)})}{\|F_1(x^{(k)})\|_1}, \dots, \frac{F_d(x^{(k)})}{\|F_d(x^{(k)})\|_d}\right) \longrightarrow x^* \in S_d$$

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Example applications: Constrained homogeneous optimization

Matrix singular vectors, again

Consider the constrained optimization problem

$$\begin{cases} \text{optimize} & x_1^T A x_2 \\ \text{subject to} & \|x_1\|_2 = \|x_2\|_2 = 1 \end{cases}$$

In general, the function $f: X_2 \to \mathbb{R}$, $f(x) = x_1^T A x_2$ is not convex. However, we know how to compute global max and global min:

Singular values and singular vectors of \boldsymbol{A}

Homogeneous singular vectors

For sufficiently smooth homogeneous functions $f:X_d\to \mathbb{R},\ g_i\in \mathbb{R}^{n_i}\to \mathbb{R}$

$$\begin{cases} \text{optimize} & f(x) \\ \text{subject to} & g_1(x_1) = \dots = g_d(x_d) = 1 \end{cases}$$

can be transformed into $F(x) = \lambda \otimes x$ for a multihomogeneous F

However, global max/min can be NP-hard

Example: graph clustering

- A = adjacency matrix of a graph with n nodes
- $f(x) = \frac{1}{2} \sum_{i=1}^{n} A_{ij} |x_i x_j|$ graph total variation
- $g(x) = ||x \operatorname{mean}(x)1||_1$

Then

- Graph clustering $\leftrightarrow \min f(x)$ st g(x) = 1
- Modularity maximization $\leftrightarrow \max f(x)$ st g(x) = 1

[T., Zhang, *Nonlinear Spectral Duality*] [T., Mercado, Hein, *Nonlinear modularity eigenvectors*]

Positive news

When f has nonegativity / order-preserving properties, we can solve these optimization problems globally Two examples:

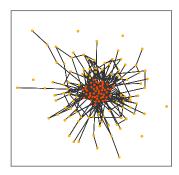
- Core-periphery detection
- Semi-supervised classification

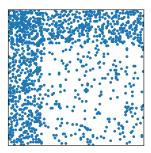
Example applications

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Core-periphery classification

Core: nodes strongly connected across the whole network **Periphery**: nodes strongly connected only to the core





Multihomogeneous PF theorem

Example applications

Core-periphery score

$$\begin{aligned} \max f(x) &:= \sum_{ij} A_{ij} (|x_i|^{\alpha} + |x_j|^{\alpha})^{1/\alpha} \\ \text{subject to } \|x\|_p = 1 \text{ and } x \ge 0 \end{aligned} \qquad (\alpha \text{ large})$$

Coreness score: " $x_i > x_j$ if i is more in the core than j"

- T., D. Higham, *SIMODS*, 2019
- 🔋 C. Higham, D. Higham, T., KDD, 2022

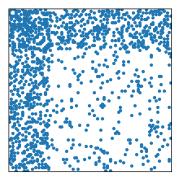
Singular vectors

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Core-periphery kernel



 $\alpha \text{ large} \Rightarrow (x^{\alpha} + y^{\alpha})^{1/\alpha} \approx \max\{x, y\}$

For a positive x > 0, $f(x) = \sum_{ij} A_{ij} (x_i^{\alpha} + x_j^{\alpha})^{1/\alpha}$ is large when edges $A_{ij} = 1$ involve at least one node with large core-score

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Connection with node degrees

If
$$p = 2$$
 and $\alpha = 1$ then *(arithmetic mean)*

$$\max f(x) \text{ st } \|x\|_p = 1 \iff \max_{x \ge 0} \frac{\|Ax\|_1}{\|x\|_2} = \|A\|_{2 \to 1}$$

and the maximizer is

 $x = degree \ vector$

Multihomogeneous PF theorem

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Connection with eigenvector centrality

If p = 1 and $\alpha = 0$ then (geometric mean)

$$\max f(x) \text{ st } \|x\|_p = 1 \iff \max_{x \ge 0} \frac{x^T A x}{x^T x} = \rho(A)$$

and the maximizer is

 $x = \mathsf{Perron}$ eigenvector of A

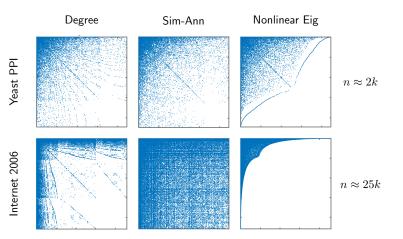
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Qualitative results



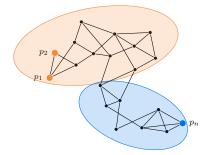
Degree coincides with NEig for $\alpha = 1$ and p = 2Convergence in a **few seconds** vs **several minutes** with Sim-Ann. Singular vectors

Multihomogeneous PF theorem

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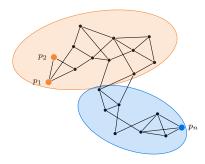
Semi-supervised graph clustering



We are given points/nodes $\{p_i\}$; we know that they belong to K classes; and we know the class of **some of them Goal:** assign classes to remaining points

Setting (cont.)

$$Y_{ij} = \begin{cases} 1 & \text{if } i \in \text{class } j \\ 0 & \text{otherwise} \end{cases}$$





Singular vectors

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Variance minimization

$$\begin{cases} \min f(X) := \left\| \frac{Y}{g(Y)} - X \right\|_F + \mu \sum_{e \in E} \left\{ A_e \sum_{i \in e} \left\| x_i - \left(\frac{\sum_{j \in e} x_j^p}{|e|} \right)^{1/p} \right\|_q \right\} \\ \text{subject to } g(X) = 1 \end{cases} \quad \text{Example: } g(X) = \|X\|_F \end{cases}$$

- [Flores, Calder, Lerman, Applied Comp Harmonic Analysis, 2022]
- [Slepcev, Thorpe, SIAP 2019]
- [Prokopchik, Benson, T., ICML, 2022]

Example applications: Entropy minimization and optimal transport

Example applications

Wasserstein distance

- $P(n) = \{x \in \mathbb{R}^n : x \ge 0, \operatorname{sum}(x) = 1\}$
- $a \in P(n_1)$, $b \in P(n_2)$, let $U(a,b) = \{M \ge 0 : M1 = 1, M^T1 = b\}$
- $C \in \mathbb{R}^{n_1 \times n_2}$ weight matrix

$$W(a,b) = \min_{M \in U(a,b)} \sum_{ij} M_{ij} C_{ij}$$

Sand pile problem:

- n_1 piles of sand, with a_i units of sand each.
- n_2 target locations, each should receive b_j units
- $M \in U(a, b)$ represents a possible solution: move M_{ij} units from i to j, so that all initial sand M1 = a is moved to the targets $M^T1 = b$
- $C_{ij} = \text{cost of moving one unit of sand from } i \text{ to } j$

Multimarginal optimal transport

•
$$U(a,b,c) = \{T \ge 0 : \sum_{jk} T_{ijk} = a_i, \sum_{ik} T_{ijk} = b_j, \sum_{ij} T_{ijk} = c_k\}$$

• $C \in \mathbb{R}^{n_1 \times n_2 \times n_3}$ weight tensor

$$W(a, b, c) = \min_{T \in U(a, b, c)} \sum_{ijk} T_{ijk} C_{ijk}$$

Sand pile problem:

- n_3 transportation means, with capacity c_k
- $C_{ijk} = \text{cost of moving one unit of sand from } i \text{ to } j \text{ by means of } k$

Computing W(a, b, c) can be very expensive...

Singular vectors 00000000000000 Multihomogeneous PF theorem

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Entropy regularization

$$\Phi_{\varepsilon}(T) = \langle T, C \rangle - \varepsilon E(T) = \varepsilon K L(T | \exp(-C/\varepsilon))$$

•
$$E(T) = -\sum_{ijk} T_{ijk} \log T_{ijk}$$
 entropy
• $KL(T|S) = \sum_{ijk} T_{ijk} \log(T_{ijk}/S_{ijk})$ Kullback–Leibler divergence

It can be shown that

$$\min_{T \in U(a,b,c)} \Phi_{\varepsilon}(T) \longrightarrow W(a,b,c) \text{ as } \varepsilon \to 0$$

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From divergence to eigenvectors

Let $L(T, \alpha, \beta, \gamma)$ be the Lagrangian of Φ_{ε} . Imposing the first-order conditions $\partial L/\partial T_{ijk} = 0$ yields

$$\log T_{ijk} = \frac{1}{\varepsilon} \Big(\alpha_i + \beta_j + \gamma_k - C_{ijk} \Big)$$

Thus, taking the exponent, we can rewrite the multimarginal opt transport problem as finding $(x, y, z) = (\exp(\alpha/\varepsilon), \exp(\beta/\varepsilon), \exp(\gamma/\varepsilon))$ such that

$$T_{ijk} = \exp(-C_{ijk}/\varepsilon)x_iy_jz_k \in U(a, b, c)$$

which in turn is equivalent to

$$\begin{cases} \sum_{jk} a_i^{-1} \exp(-C_{ijk}/\varepsilon) y_j z_k = x_i^{-1} \\ \sum_{ik} b_j^{-1} \exp(-C_{ijk}/\varepsilon) x_i z_k = y_j^{-1} \\ \sum_{ij} c_k^{-1} \exp(-C_{ijk}/\varepsilon) x_i y_j = z_k^{-1} \end{cases}$$

Comments and open questions

- Everything can be generalized to "any" cone
- Better convergence bounds?
 - Use eigenvalues of A somewhere
 - Use different distances (e.g. Ergodicity coefficients)
- Speed up power method?

Some references

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