



LIME clustering and energy response

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Detector evolution





cosmic ray at Segrè lab



x (pixels)

1750

2000

1750

2000

1 cm



Every season needs its clothes











cosmic ray at Segrè lab

x (macro-pixels)

100





Frascati is **notoriously** a radioactive place and exposed to a continuous shower of cosmic rays => in any data taken so far, we have this background overlapped

Occupancy depends on the volume (fixed), but also with the exposure:

- data taken with the DAQ has a minimum exposure of 200 ms => o(50 tracks/event)
- exposure can be reduced with data taken by hand with HOKAWO. We took some data with 50ms => o(10 tracks / event)

This talk focuses on results based on both types of data: they used the same clustering, geometrical and response corrections and analysis method.

Some parameters, though, are fine-tuned for 50ms or 200ms exposure.

BTW, what is next season, and which clothes we have to prepare?

LIME will go **under Gran Sasso** soon, so probably the occupancy will be **<2 tracks/event** => something naive and simple, as NNC or DBSCAN will be sufficient: back to the origin



Typical occupancy







Directional tracking



For this I. Pains has developed a clustering that search for patterns compatible with polynomials (line or 3rd order polynomial). Links to presentations <u>here</u> and <u>here</u>.

Reminder of the method:

- starts with DBSCAN with a short radius
- tests if starting from these clusters, one can find other clustered points compatible with a polynomial
 - the polynomial is fitted iteratively until points are added to the supercluster





- As soon as the occupancy increases, everything gets merged when the "seed" cluster is in a crowded region
- it is slow, because of the many fits/seed done
- 3-rd order polynomial sometimes not sufficient, but fitting with higher order can get crazy soon
- ATTEMPTs explored to improve:
- 1. Use "isolated" seeds to start directional search, i.e. with the miniminum $I = \sum_{i}^{\Delta R = 200} A_i$. (A_i = i
 - —pixel amplitude). If >1 has I=0, then sort by the best linear fit X^2 .
- 2. Use Bernstein polynomials to approximate the curve, to improve stability
- 3. Each pixel is "weighted" proportionally to its intensity to improve the contrast
- 4. The remaining clusters are done without fitting, with naive DBSCAN, only if they are isolated by directional clusters

The product is a merged collection of "SUPERCLUSTERS" which contains both long and short clusters



Examples: 200ms exposure

These are the typical images taken with the minimum camera aperture allowed with the CYGNO DAQ

- N.B. This is after a lot of tuning of parameters (isolation definition, clustering metric, etc.)





The eagerness of the directional is on purpose exaggerated because it is better to eat some piece of another track that leave a disjoint piece around (signal fake!)





Data taken with HOKAWO, without the DAQ





One step back: noise subtraction

Before clustering, there is all the usual chain of noise filtering:

 pedestal subtraction + zero suppression (pixel-wise) + neighbor filtering + median filtering + acceptance cuts



Bottom and top strips of the sensor hot after pixelby-pixel baseline subtraction

For now, cut away the strips:

 "acceptance" can be set in modules_config/ geometry_lime.txt

: 'lime',
: 0.152, # mm
: 2304,
: 'data/vignette_runs03930to03932.root',
: 0,
: 2304,
: 200,
: 2304-100,
g/geometry_lime.txt (END)



Vignetting corrections



Once the noise is subtracted, the response of each pixel is corrected with the inverse of the pure-optical vignetting map

 map obtained with white pictures => correct the main optical effect, independent on all other LIME geometrical non-uniformities



 unavoidable effect: the correction amplifies the noise in the low LY regions, so expect a worse energy resolution far from the center



Cluster properties



Once the superclusters are done, cluster shapes and properties can be computed and stored in the ntuples as plain floats.

Examples: length, width, row energy (in counts), transverse and longitudinal RMS and Gaussian widths, curved path length, etc.

Possibility to save all the pixels belonging to a cluster for furhter studies

N.B. this is independent on clustering technique: MODULARITY !



Let's use these data: energy response linearity





Data taken with a variable X-rays source: ²⁴¹Am source impinging different materials produce lines at characteristic energy lines

Note that:

- 1) X-rays yield lowers a lot when lowering energy (8 keV yield is 3% than 50 keV)
- 2) absorption by the LIME teflon window lower energies



=> we need a lot of data to get a peak at lower energies

People at LNF took a lot of data with multiple energy sources and detector configurations, so we can use this data to study **the linearity of LIME energy response in different conditions.**



Raw event displays



selection detail: track length cut a bit relaxed for higher energies







Raw energy spectra





Ti excited with 5.9 keV ⁵⁵Fe expected to emit 4.5 keV photons. First experimental setup: a thin layer in "penetration" mode

Data was taken later in "reflection" mode (see later on)



Expect to see inside LIME:

- •the fraction of 5.9 keV X-rays not absorbed by Ti and teflon window
- •a (smaller) fraction of 4.5 keV X-rays not absorbed by teflon window



LIME energy linearity results

energy response

Bkg is subtracted from no-source data, resulting spectrum fitted with a Gaussian.

Other bumps are seen, but used only the expected one

N.B. These are roughly at the Cu "line", but indeed Am source can excite the Cu inside LIME

Last two points affected by large SYSTEMATIC error from bkg subtraction



Physics interest is towards lower energies: can we go lower than 4.5 keV?



Going furhter down...





Davide, Roberto, Luigi took a lot of data with "45degree" reflection from material with the trolley built by Roberto

Energy corrections





- K is a global constant, computed as response to 5.9 keV averaged on x,y and z (GEM distance)
- C_i can account also drift field non-uniformities, but decided to keep it robust and simple: vignetting only
- F_{γ} can be computed on top of reconstructed clusters and it is discussed in the following



Corrections F_{γ}



To our knowledge, there are two main sources of light-yield non-uniformities, depending on either x-y (transverse projection) or z (distance wrt GEM plane):







- General principle is to derive a best estimate of the dependent variable (in this case the true cluster energy) given a set of independent variables (position, cluster shape parameters, etc)
- Davide's empiric correction was an energy correction using the projection of the energy scale onto 1 variable (density δ)
- In an event classification problem this is like using the projected likelihood in several variables (which is fully optimal as long as the correlations between variables are not relevant)
- In a classification problem one can use a multidimensional probability density, Boosted Decision Tree, or Neural Net to take into account the correlations
- We can do the same for multivariate regression
- This can easily correct F(x,y), but the hope is that cluster shapes can be sensitive also to F(z) through correlations



Selection and sample



Ideally this should be done on SIM. Target would be E_{true}/E_{reco} (or its full PDF, not just an estimator of it, as its mean)

PRO of the SIM: Can be trained on both ERs and NRs (our signals) of whatever energy / condition / prototype

CON of the SIM: Sensitive to data-SIM disagreement of ANY of the regression inputs. At this stage we haven't a reliable, extensive, data-SIM comparison in LIME

- keep in mind for the next future (needs a comparison of ALL the variables)

So right now train on DATA, ⁵⁵Fe, for which we have a sample with high statistics and high S/B ratio. Target is the known energy (5.9 keV, in raw pixel counts), normalized to the peak position

- Data taken with Z in the range [5-45] cm used
- Selection: length<100 pix ; width/length>0.6 ; 0.3<integral/9000<1.7 (cut away fake clusters and merged spots), R<900 pixels (avoid highly vignetted region)



Inclusive results



N.B. Raw resolution worse than July data because it includes data with z(source-GEM) < 15cm where saturation is happening smearing the energy response.







z = 11 cm

z = 36 cm





Results vs Z



light yield peak



Regression does NOT correct (yet) for saturation

=> look for more sensitive variables

Regression cures the variation vs z when there is not saturation

light yield resolution



Resolution significantly improved everywhere

Core Gaussian resolution can be better than 10% (if no saturation)



Conclusions



- We have now in our wardrobe (github) clothes (clusterings) for many Terrestrial seasons, on the surface, and under the surface
- We have analyzed most of the data taken with LIME so far at LNF, which is the worst situation in terms of backgrounds, to get results on efficiency and energy response in a wide range of energies
- The energy linearity in response to X-rays is reasonable in the range [4.5 50] keV
- raw energy resolution is about 15%, but MVA regression can improve it up to 7%, even if it doesn't correct yet for the saturation

After the MVA regression, the saturation introduce a non linearity of max 20% for the closest Z tested with 55Fe source (5 cm from the GEM)

- the same A-Z analysis should be performed on simulation to validate it (and to understand the origins of response differences)
- when the simulation can reproduce the performance observed in data under many aspects (energy, cluster shapes, etc), we can trust it to make physics projections (e.g. NR vs ER with sophisticated techniques) based on SIM.

- We should write a paper summarizing LIME detector performance with LNF data.

Backup





Developments in "autumn21" GIT branch (UNSTABLE!)

Starting from I. Pains directional clustering (3D "weighted" version, i.e. each pixel has weight = #photons)

- Done the minimal to run and achieve something reasonable:
- rebinned image x6 (x4 would be better to resolve overlaps, but too slow with this pileup)
- improved fits for the directional tracking
- tightened the isolation requirement when looking for "signal" small clusters after the long tracks have been reconstructed
 - preferred smaller efficiency to the risk of getting unclustered pieces of long tracks
 - residual subtraction will be done by the statistical analysis



Output super-clusters



350

350





We used it extensively to correct the energy response of the ECAL in CMS wrt many effects (local containment, pileup dependency, etc)





MVA implementation



- Input variables are used to train a multivariate regression using the Gradient Boost Regression (based on a BDT in scikit-learn).
- GBR target is integral/9000 (to have a variable centered at 1)
 - normalization also helps in reducing the phase space of the target variable when training with variable energy clusters
- The loss function are:
 - mean squared errors
 - 50% quantile (median), and 5% and 95% quantiles
 - 50% quantile gives the central prediction, the other two give per-cluster energy resolution estimates (+ and asymmetric errors)
- Detailed training options to be further optimized



Data used for MVA regression INFN

July 30th runs with ⁵⁵Fe with V_{GEM1} = 440 V at different Z values: 46, 36, 26, 6cm

- here focusing on Energy, but a dedicated regression can target Z (exploit dependency of cluster shapes - through diffusion, mainly) to give a per-cluster Z estimate
 - a straightforward way to make a 3D reconstruction. Need more Z points to test this (e.g. data taken in April and analyzed by Donatella)
- About 8000 clusters used, 90% for training, 10% for testing
- A thought for the future:
 - data with the source moved on all 4 sides of LIME would help covering uniformly the XY plane with spots