Measurements, uncertainties and probabilistic inference/forecasting

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Short reminder

We have seen how the exponential distribution arises from the Poisson process.

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The Exponential is a Geometric in the continuum (it makes no sense to speak about the "precise trial", but we can talk about "time the occurrence")

Exponential random number generator

Exercise: use the algoritm of *inverting the cumulative* to write an *exponential random number generator*

reminder:

$$f(t) = \frac{1}{\tau} e^{-t/\tau}$$
$$= r e^{-rt}$$

$$F(t) = 1 - e^{-t/\tau} \\ = 1 - e^{-rt}$$

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Both the Exponential and the Geometric have the property of 'no memory':

If the 'success' is not occurred up to a certain 'point' (trial or instant), all probabilistic considerations restart from that that 'point'.

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- the Geometric distribution describes the number of trials between consecutive successes (and in this case it is convenient to make X starting from 0, instead than from 1);
- the Exponential distribution describes the time interval between two consecutive events (as long as r remains 'practically' constant).

(An interesting exercise)

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$$= 1 - e^{-\Delta t/\tau}$$
$$(\text{If } \Delta t \ll \tau)$$
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If we have at a given instant N nuclei, how many will decay in Δt?

(An interesting exercise - cont.d 1)

$$X \sim \mathcal{B}(N, \frac{\Delta t}{\tau})$$

$$E[X] = N \cdot \frac{\Delta t}{\tau} [= N \cdot r \cdot \Delta t]$$

$$\sigma(X) = \sqrt{\frac{\Delta t}{\tau} \cdot \left(1 - \frac{\Delta t}{\tau}\right) \cdot N} \approx \sqrt{\frac{\Delta t}{\tau} \cdot N}$$

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Relative uncertainty (E[X] > 0):

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The process can be seen as deterministic:

(An interesting exercise – cont.d 2)

$$\Delta N = -\mathsf{E}[X] = -N \frac{\Delta t}{\tau}$$

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that we can 'conveniently extend' to the continuum as

$$\frac{dN}{dt} = -\frac{N}{\tau},$$

resulting in

$$N(t) = N_0 \cdot e^{-t/\tau}.$$

(An interesting exercise – cont.d 3) Twofold meaning of τ :

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 $\blacktriangleright \ \{\Delta N, \, \Delta t, \, N\} \quad \rightarrow r \quad \rightarrow \quad \tau$

(without having to observe the instant of 'birth' and of dead of single objects)

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Quite not an easy concept for the general public \longrightarrow

How life times are perceived...

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- This is how the new was reported by a major Italian newspaper (Corriere della Sera):

Observed how a proton dies. It was 10^{25} years old.

The very venerably aged proton

Corriere della Sera. 1st June 1984

Venerdì 1 giugno 1984

INTERNO

L'eccezionale avvenimento scientifico illustrato al convegno di cosmofisica dell'Aquila

«Abbiamo visto come muore un protone» Gli scienziati italiani spiegano: aveva 10 mila triliardi di anni

La comunicazione è stata fatta dagli studiosi che operano nel laboratorio sotto il Monte Bianco - La particella che hanno visto disintegrarsi il 17 maggio scorso era la seconda al cui «decesso» assistevano in diretta - Questo evento rarissimo ha un'enorme importanza per le moderne teorie unificate della fisica

DAL NOSTRO INVIATO SPECIALE L'AQUILA - Il protone dà segni di stanchezza. I cosmofisici che lavorano nel laboratorio sotto il monte Bianco ne hanno visto disintegrarsi uno il 17 maggio scorso. Aveva un'età venerabilissima: circa diecimila triliardi di anni. E' il lavori congressuali, i cento fisecondo protone la cui morte viene colta in diretta dagli scienziati italiani da quando è cominciato l'esperimento NU-SEX, dalle iniziali di -Nucleon stability experiment.

La comunicazione di questo importante risultato scientifico è stata data l'altro ieri, con la prudenza necessaria, al secondo «Convegno nazionale di fisica cosmica-, che si tiene all'Aquila, dal fisico sperimentale Pio Picchi.

NUSEX è una collaborazione fra l'Istituto di cosmofisica del CNR di Torino e i laboratori INFN di Milano e di Frascati per le moderne teorie unificate l della fisica, ha accresciuto l'interesse per un altro e più grande laboratorio sotterraneo dove si studieranno questi fenomeni: il laboratorio sotto il

Gran Sasso Durante un intermezzo dei sici riuniti a L'Aquila hanno visitato le gallerie dove, entro secondo finanziamento di ses- fisici di tutto il mondo». santa miliardi per il completamento delle opere pubbliche, e

della strumentazione scientifica.

-Sotto il Gran Sasso inizieremo, molto probabilmente, con tre esperimenti - spiega il professor Renato Scrimaglio, direttore del costruendo laboratorio -: 1) lo studio del decadimento del protone; 2) lo studio dei neutrini solari; 3) la ricerca di una particella chiadue anni, sorgeranno i nuovi mata monopolo magnetico. Si laboratori dell'INFN. Il parla- tratta di ricerche di frontiera mento ha da poco approvato il aperte alla collaborazione dei

I programmi dettagliati degli esperimenti saranno definiora gli studiosi aspettano che ti al più presto da una commis-

anche il proponente del laboratorio sotto il Gran Sasso, La commissione si riunirà per la prima volta il 4 giugno prossimo. I finanziamenti degli esperimenti scientifici saranno assicurati nell'ambito del bilancio 1985-1990 dell'INFN di cui si aspetta l'approvazione. Esso prevede una spesa complessiva di mille miliardi dei quali un centinaio da destinare alla strumentazione del laboratorio sotto il Gran Sasso.

Sotto 1.400 metri di roccia, ad ammirare la grande camera alta venti metri in cui si stuvenga dato il via all'acquisto sione presieduta dal fisico An- dieranno le particelle, si è av-

tonino Zichichi, che è stato i venturato anche il professor Bruno Rossi, 81 anni, uno dei padri fondatori della fisica cosmica. -E' un paesaggio dantesco - ha esclamato -. Se quando ero giovane ricercatore mi avessero detto che per studiare la radiazione cosmica sarebbe stato necessario ficcarsi qui dentro non ci avrei creduto-

- E se potesse ricominciare da capo - gli abbiamo chiesto - verrebbe a lavorarci, qui sotto?

-Ah no, certamente no-, ha risposto il professore scuotendo la testa

In una conferenza mondiale a Roma si proporranno nuove strategie per le attività ittiche

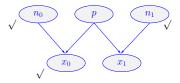
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Back to the

inferential/predictive problem related to the binomial model



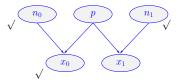
Joint inference and prediction



Let's do the math.



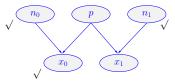
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Three observed variables

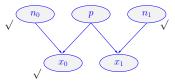




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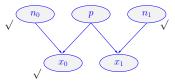
Three **observed variables** (no uncertainty): n_0 , x_0 and n_1 .





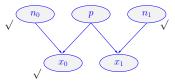
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- Two unobserved variables (uncertain value)



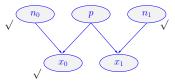


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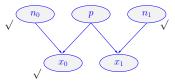


- Three observed variables (no uncertainty): n₀, x₀ and n₁.
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- $f(n_0, x_0, n_1)$ is a number, given the model.



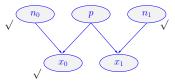
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 It might be difficult to calculate, but it is a number.

$$f(p, x_1 | n_0, x_0, n_1) = \frac{f(p, x_1, n_0, n_1, x_0)}{f(n_0, x_0, n_1)}$$



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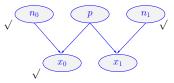
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 $\tilde{f}(p, x_1 | n_0, x_0, n_1) = f(p, x_1, n_0, n_1, x_0)$

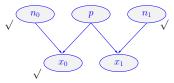
 $\tilde{f()}$: unnormalized pdf.



Using the chain rule ('bottom-up') (and neglecting all factors that do not depend on p and x_1):

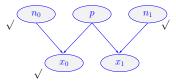
 $f(p, x_1 | n_0, x_0, n_1) \propto f(x_0 | n_0, p) \cdot f(x_1 | p, n_1) \cdot f_0(p)$





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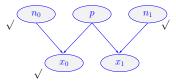


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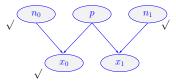


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Problem almost solved



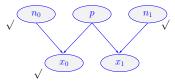
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Possibly calculate the normalization, then <u>all</u> moments and probability intervals of interest.



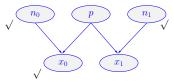
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- Possibly calculate the normalization, then <u>all</u> moments and probability intervals of interest.
- Do it numerically



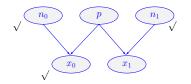
Using the chain rule ('bottom-up') (and neglecting all factors that do not depend on p and x_1):

 $\begin{aligned} f(p, x_1 \mid n_0, x_0, n_1) & \propto & f(x_0 \mid n_0, p) \cdot f(x_1 \mid p, n_1) \cdot f_0(p) \\ & \propto & p^{x_0} (1-p)^{n_0-x_0} \cdot \frac{p^{x_1} (1-p)^{n_1-x_1}}{x_1! (n_1-x_1)!} f_0(p) \end{aligned}$

$$\tilde{f}(p, x_1 | n_0, x_0, n_1) = \frac{p^{x_0 + x_1}(1-p)^{n_0 + n_1 - x_0 - x_1}}{x_1! (n_1 - x_1)!} \cdot f_0(p)$$

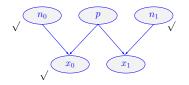
Problem almost solved

- Possibly calculate the normalization, then <u>all</u> moments and probability intervals of interest.
- Do it numerically or by by sampling.



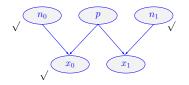
 \Rightarrow sample $\tilde{f}(p, x_1 | n_0, x_0, n_1)$





 \Rightarrow sample $\tilde{f}(p, x_1 | n_0, x_0, n_1)$ using Monte Carlo techniques

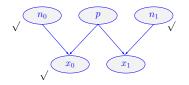




 \Rightarrow sample $\tilde{f}(p, x_1 | n_0, x_0, n_1)$ using Monte Carlo techniques

\Rightarrow Markov Chain Monte Carlo (MCMC)



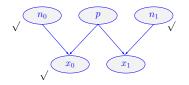


 \Rightarrow sample $\tilde{f}(p, x_1 | n_0, x_0, n_1)$ using Monte Carlo techniques

⇒ Markov Chain Monte Carlo (MCMC)

 \Rightarrow JAGS does it for us

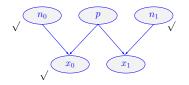




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⇒ Markov Chain Monte Carlo (MCMC)

- \Rightarrow JAGS does it for us
 - by Gibbs sampler (JAGS: Just Another Gibbs Sampler) if pdf's involved allow it;

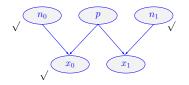


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⇒ Markov Chain Monte Carlo (MCMC)

- \Rightarrow JAGS does it for us
 - by Gibbs sampler (JAGS: Just Another Gibbs Sampler) if pdf's involved allow it;
 - by Metropolis

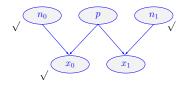




 \Rightarrow sample $\tilde{f}(p, x_1 | n_0, x_0, n_1)$ using Monte Carlo techniques

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 - by Gibbs sampler (JAGS: Just Another Gibbs Sampler) if pdf's involved allow it;
 - by Metropolis ("when the going gets tough, the tough get going" - J. Belushi)



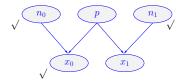
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⇒ Markov Chain Monte Carlo (MCMC)

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JAGS called from R using the package rjags.

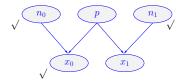
Graphical models: some terminology



- nodes (observed/unobserved);
- child/childred;
- parent(s).

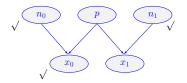


Graphical models: some terminology



- nodes (observed/unobserved);
- child/childred;
- parent(s).
- A node without parents needs a prior (node p in this case)

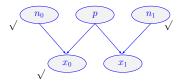
Joint inference and prediction in JAGS



Model

```
model{
    x0 ~ dbin(p, n0);
    x1 ~ dbin(p, n1);
    p ~ dbeta(1, 1);
}
```

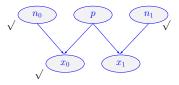
Joint inference and prediction in JAGS



Then the model has to be in a file.



Joint inference and prediction in JAGS



Then the model has to be in a file.

For such a small model we can write it directly from ${\sf R}$ on a temporary file:

```
model = "tmp_model.bug"
write("
model{
    x0 ~ dbin(p, n0);
    x1 ~ dbin(p, n1);
    p ~ dbeta(1, 1);
}
", model)
```

Use of JAGS from R via rjags

```
Second part of the R script (\Rightarrow inf_p_rd_jags.R)
```

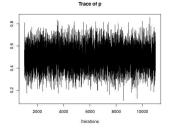
```
library(rjags)
```

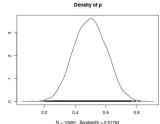
```
data = list(n0=20, x0=10, n1=10)
```

```
jm <- jags.model(model, data)
chain <- coda.samples(jm, c("p", "x1"), n.iter=10000)</pre>
```

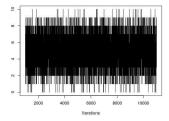
```
plot(chain)
print(summary(chain))
```

Use of JAGS from R via rjags (n0 = 20, x0 = 10, n1 = 10)

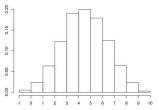




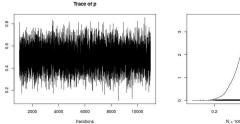


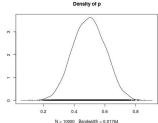




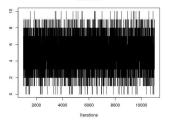


Use of JAGS from R via rjags (n0 = 20, x0 = 10, n1 = 10)

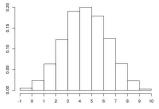




Density of x1



Trace of x1



 $p = 0.498 \pm 0.105; x_1 = 4.98 \pm 1.86$

(10000 samples).

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Inference and prediction with JAGS/rjags

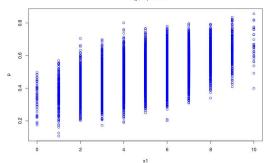
Comparison with exact result of $f(x_1 | n_0, x_0, n_1)$ $f(x_1 | n_0, x_0, n_1 = 10)$ in %

$(x_1 n_0, x_0, n_1 = 10) \text{ m/} 0$					
<i>X</i> ₁	$\frac{X_1}{n_1}$	$\int x_0 = 1$	$\int x_0 = 10$	$\int x_0 = 100$	$\int x_0 = 1000$
		$\int n_0 = 2$	$n_0 = 20$	$n_0 = 200$	$n_0 = 2000$
0	0	3.85	0.42	0.12	0.10
1	0.1	6.99	2.29	1.11	0.99
2	0.2	9.44	6.51	4.67	4.42
3	0.3	11.19	12.54	11.88	11.74
4	0.4	12.24	18.07	20.21	20.48
5	0.5	12.59	20.33	24.02	24.55
6	0.6	12.24	18.07	20.21	20.48
7	0.7	11.19	12.54	11.88	11.74
8	0.8	9.44	6.51	4.67	4.42
9	0.9	6.99	2.29	1.11	0.99
10	1	3.84	0.42	0.12	0.10
$E(X_1)$		5	5	5	5
$\sigma[X_1]$		2.64	1.87	1.62	1.58

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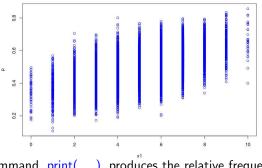
Inference and prediction with JAGS/rjags Scatter plot of sampled $f(p, x_1 | n_0, x_0, n_1)$

Inference and prediction with JAGS/rjags Scatter plot of sampled $f(p, x_1 | n_0, x_0, n_1)$



cor(p,x1) = 0.56

Inference and prediction with JAGS/rjags Scatter plot of sampled $f(p, x_1 | n_0, x_0, n_1)$



(The last command, print(...), produces the relative frequencies of occurrance of $x_1 \rightarrow try$ it)

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Self made Gibbs sampler

Take, as in the JAGS example, a uniform $f_0(p) \rightarrow f_0(p) = 1$:

$$f(p, x_1 | n_0, x_0, n_1) \propto \frac{p^{x_0}(1-p)^{n_0-x_0} \cdot p^{x_1}(1-p)^{n_1-x_1}}{x_1! (n_1-x_1)!}$$



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In the first step (i = 0)• extract $p^{(i=0)}$ at random: p = runif(1, 0, 1);



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• extract
$$x_1^{(i=0)}$$
 conditioned also by $p = p^{(i=0)}$:

$$f(x_1 \mid n_0, x_0, n_1, p) \propto \frac{p^{x_0}(1-p)^{n_0-x_0} \cdot p^{x_1}(1-p)^{n_1-x_1}}{x_1! (n_1-x_1)!}$$

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$$\propto \frac{p^{x_1}(1-p)^{n_1-x_1}}{x_1! (n_1-x_1)!}$$

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In the first step (i = 0)
 extract p⁽ⁱ⁼⁰⁾ at random: p = runif(1, 0, 1);
 (or fix a value by hand)

• extract $x_1^{(i=0)}$ conditioned <u>also</u> by $p = p^{(i=0)}$: $f(x_1 \mid n_0, x_0, n_1, p) \propto \frac{p^{x_0}(1-p)^{n_0-x_0} \cdot p^{x_1}(1-p)^{n_1-x_1}}{x_1! (n_1-x_1)!}$ $\propto \frac{p^{x_1}(1-p)^{n_1-x_1}}{x_1! (n_1-x_1)!}$

 \rightarrow x1 = rbinom(1, n1, p)

First step: \rightarrow p = runif(1, 0, 1) (or fix a value) \rightarrow x1 = rbinom(1, n1, p)



First step:

```
 \rightarrow p = runif(1, 0, 1) 
(or fix a value)
 \rightarrow x1 = rbinom(1, n1, p)
```

Then

1. i = i + 1; extract $p^{(i)}$ conditioned <u>also</u> by $x_1^{(i-1)}$:

```
 \begin{array}{rcl} f(p \mid n_0, x_0, n_1, x_1) & \propto & p^{x_0} (1-p)^{n_0-x_0} \cdot p^{x_1} (1-p)^{n_1-x_1} \\ & \propto & p^{x_0+x_1} \cdot (1-p)^{n_0+n_1-x_0-x_1} \end{array}
```

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```
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```

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2. Extract $x_1^{(i)}$, conditioned by $p^{(i)}$, as in Step 1

First step:

```
 \rightarrow p = runif(1, 0, 1) 
(or fix a value)
 \rightarrow x1 = rbinom(1, n1, p)
```

Then

1. i = i + 1; extract $p^{(i)}$ conditioned <u>also</u> by $x_1^{(i-1)}$:

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Summarizing, for $i \ge 1$



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1. i = i + 1

then extract $p^{(i)}$:



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then extract $p^{(i)}$:

$$p^{(i)} \sim \text{Beta}(r = x_0 + x_1 + 1, s = n_0 + n_1 - x_0 - x_1 + 1)$$



Summarizing, for $i \ge 1$

1. i = i + 1

then extract $p^{(i)}$:

 $p^{(i)} \sim \text{Beta}(r = x_0 + x_1 + 1, s = n_0 + n_1 - x_0 - x_1 + 1)$

2. extract $x_1^{(i)}$:

 $x_1^{(i)} \sim \mathcal{B}_{n_1,p};$

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Summarizing, for $i \ge 1$

1. i = i + 1

then extract $p^{(i)}$:

 $p^{(i)} \sim \text{Beta}(r = x_0 + x_1 + 1, s = n_0 + n_1 - x_0 - x_1 + 1)$

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Then do loop through steps 1 and 2 'many times'.



Summarizing, for $i \ge 1$

1. i = i + 1

then extract $p^{(i)}$:

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2. extract $x_1^{(i)}$:

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At the end, we have the histories of the variables of interest

Summarizing, for $i \ge 1$

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Then do loop through steps 1 and 2 'many times'.

At the end, we have the histories of the variables of interest
▶ the points (p⁽ⁱ⁾, x₁⁽ⁱ⁾) will 'visit' the (p, x₁) space according to f(p, x₁).

Summarizing, for $i \ge 1$

1. i = i + 1

then extract $p^{(i)}$:

 $p^{(i)} \sim \text{Beta}(r = x_0 + x_1 + 1, s = n_0 + n_1 - x_0 - x_1 + 1)$

2. extract $x_1^{(i)}$:

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Then do loop through steps 1 and 2 'many times'.

At the end, we have the histories of the variables of interest the points $(p^{(i)}, x_1^{(i)})$ will 'visit' the (p, x_1) space

according to
$$f(p, x_1)$$
.

(There are theorems...)

Gibbs sampler, implemented in R

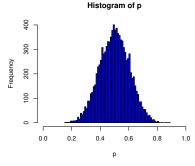
```
# initialize the history vectors
```

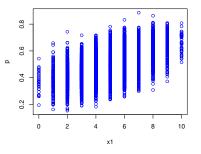
N = 10000; p = x1 = rep(0, N)

```
# observed nodes
n0 = 20; x0 = 10; n1 = 10
```

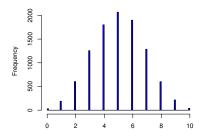
 $\longrightarrow \texttt{inf}_p\texttt{p_pred}_g\texttt{ibbs.R}$

Inference/prediction by a Gibbs sampler implemented in R





Histogram of x1



mean(p) = 0.501sigma(p) = 0.104 mean(x1) = 5.031 sigma(x1) = 1.817 rho(p,x1) = 0.548

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Same problem solved using hit/miss

```
# model parameters, N and uf()
# as in the previous script
# find the maximum
p <- seq(0,1,len=101)
x1 <- 0:n1
f_{max} = 0
for (i in 1:length(p)) {
    for (j in 1:length(x1)) {
      f = uf(p[i], x1[j], n0, x0, n1)
    if(f > f.max) f.max = f
  }
}
f.max <- f.max * 1.1 # exaggerated safety factor
```

Same problem solved using hit/miss (cont.d)

```
# sample in 2D
#1. random choice in the plane (p,x1)
p.r <- runif(N)
x1.r <- sample(0:n1, N, rep=TRUE)</pre>
```

```
# 2. Calculate the function in correspondence of the points
f <- numeric(N)
for (i in 1:N) {
    f[i] <- uf(p.r[i], x1.r[i], n0, x0, n1)
}</pre>
```

```
# 3. accept events
hit <- runif(N)*f.max <= f # accepted events ('hit')
p <- p.r[hit]
x1 <- x1.r[hit]</pre>
```

```
## => inf_p_pred_hit-miss.R
```



As an **exercise**, for completeness, try to solve the problem numerically (no sampling):

• discretize the problem making a grid in the (p, x_1) plane;



- discretize the problem making a grid in the (p, x_1) plane;
- calculate the unnormalized pdf in each elements of the grid;

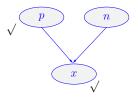


- discretize the problem making a grid in the (p, x_1) plane;
- calculate the unnormalized pdf in each elements of the grid;
- calculate the normalization constant;

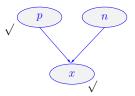


- discretize the problem making a grid in the (p, x_1) plane;
- calculate the unnormalized pdf in each elements of the grid;
- calculate the normalization constant;
- calculate all moments of interest, including correlation the coefficient;

- discretize the problem making a grid in the (p, x_1) plane;
- calculate the unnormalized pdf in each elements of the grid;
- calculate the normalization constant;
- calculate all moments of interest, including correlation the coefficient;
- (optional) make a lego plot, or a false-color plot to visualize the shape of the distribution.

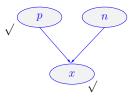






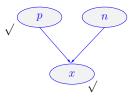
Think at a detector having a well known efficiency ($\epsilon \equiv p$)





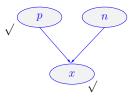
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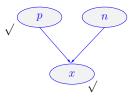
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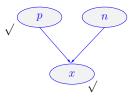


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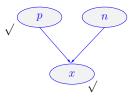


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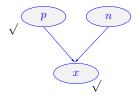
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Not to be confused with a different problem:

- a Poisson process has produced x in the measuring time T;
- ▶ what is λ of the related Poisson distribution? $\longrightarrow f(\lambda | x)$? [or, more precisely, what is the rate r? $\longrightarrow f(r | x, T)$?]

Extending the model

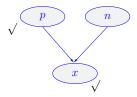
Our problem (but in Physics it is often not so simple)





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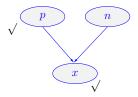
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n independent Bernoulli processes

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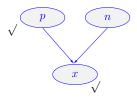
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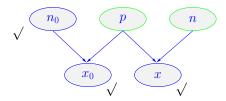
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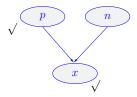
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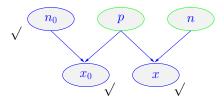
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But what is n?

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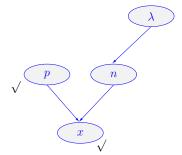
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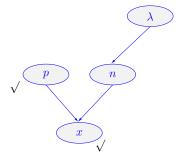


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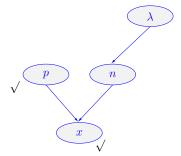
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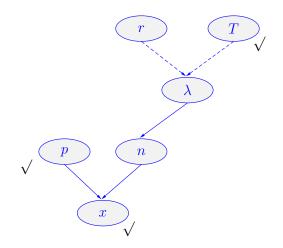
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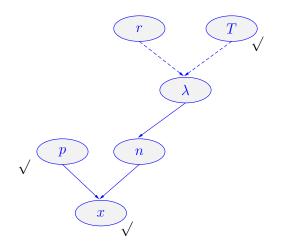
But, as we have seen studying the **Poisson process**, λ is not really physical $\longrightarrow \lambda = r T$ (© GdA, GSSI-04 14/06/21, 32/65

 $\lambda = r \cdot T$:



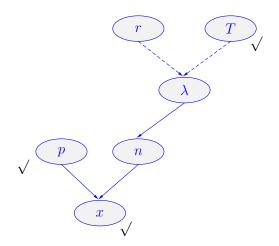
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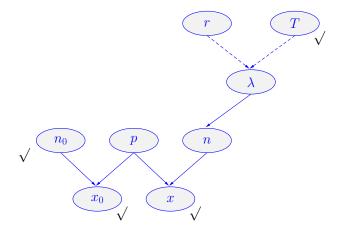
(Dashed arrows used in literature for deterministic links)

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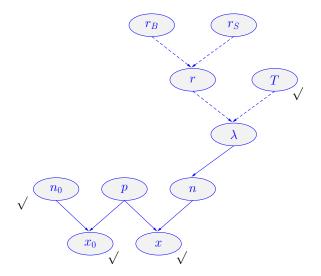
(Dashed arrows used in literature for deterministic links) In JAGS, e.g., lambda <- r * T;

Remembering that *p* was got from a measurement:



The rate r gets contributions from signal and background

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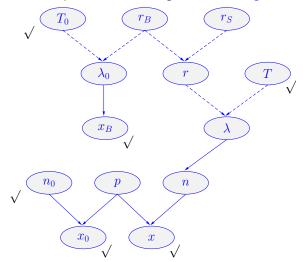
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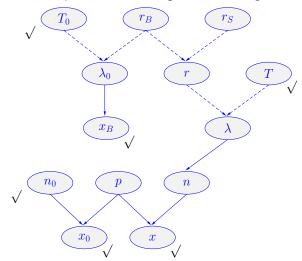
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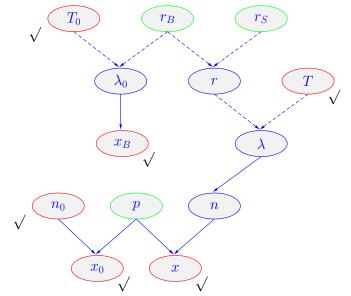


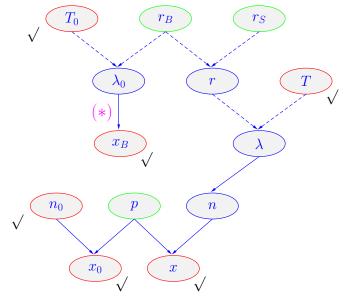
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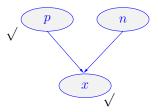


(T_0 and T assumed to be measured with sufficient accuracy)



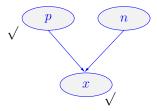


(*) Assuming unity efficiency





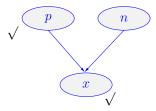
Back to our initial problem



 $f(n \mid p, x) \propto f(x \mid n, p) \cdot f_0(n)$

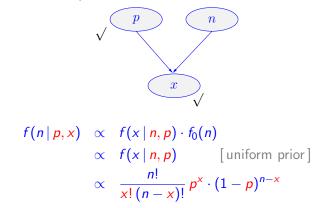


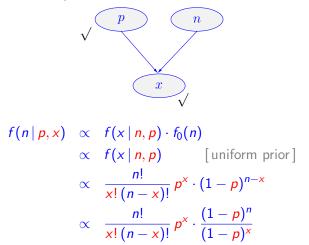
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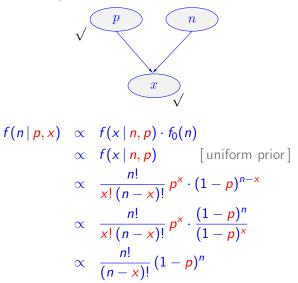


$\begin{array}{ll} f(n \mid p, x) & \propto & f(x \mid n, p) \cdot f_0(n) \\ & \propto & f(x \mid n, p) & [\text{uniform prior}] \end{array}$









This time the unnormalized probability function

$$\tilde{f}(n | p, x) = \frac{n!}{(n-x)!} (1-p)^n$$

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Using p = 0.75 and x = 10 and $n_{max} = 30$

► calculate the vector of $\tilde{f}(n | p, x)$ for $x \le n \le n_{max}$;

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- ► calculate the vector of $\tilde{f}(n | p, x)$ for $x \le n \le n_{max}$;
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- make a barplot of the distribution;
- calculate $P(n \ge 20)$

Inferring *n* 'assuming' *p* and *x* Example in R with p = 0.75 and x = 10

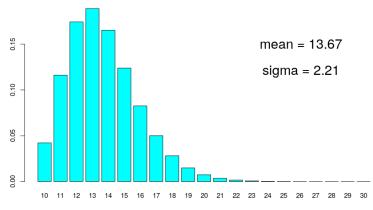
Left as exercise

(1-D version of that proposed at the end of last lecture)



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 $f(n \mid x = 10, p = 0.75)$



Inferring n 'assuming' p and xOr we can feed JAGS with the following simple model

```
model{
    x ~ dbin(p, n);
    n ~ dnegbin(0.001, 1) I(nmin,);
}
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The remaining R code is left as **exercise**

Moving to the Poisson model





set up the problem;

solution for uniform prior;



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- the case of no events observed;

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- solution for uniform prior;
- the case of no events observed;
- prior conjugate;
- predictive distribution;
- from λ to r (not covered, since it is straightforward; but remember that the 'physical quantity' is r)

$$f(\lambda \,|\, x, \mathcal{P}) = \frac{\frac{\lambda^x e^{-\lambda}}{x!} f_{\circ}(\lambda)}{\int_0^\infty \frac{\lambda^x e^{-\lambda}}{x!} f_{\circ}(\lambda) \,\mathrm{d}\lambda} \,.$$

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$$f(\lambda \,|\, x, \mathcal{P}) = \frac{\frac{\lambda^{x} e^{-\lambda}}{x!} f_{\circ}(\lambda)}{\int_{0}^{\infty} \frac{\lambda^{x} e^{-\lambda}}{x!} f_{\circ}(\lambda) \,\mathrm{d}\lambda}.$$

Assuming $f_{\circ}(\lambda)$ constant up to a certain $\lambda_{max} \gg x$ and making the integral by parts we obtain

$$f(\lambda | x, \mathcal{P}) = \frac{\lambda^{x} e^{-\lambda}}{x!}$$
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Summaries

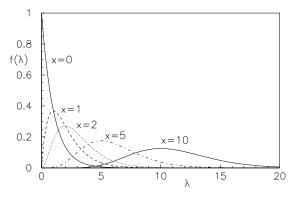
$$E(\lambda) = x + 1,$$

$$Var(\lambda) = x + 1,$$

$$\lambda_m = x$$

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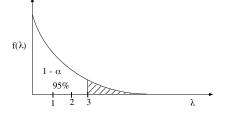
Some examples of $f(\lambda)$



For 'large' $x f(\lambda)$ it becomes Gaussian with expected value x and standard deviation \sqrt{x} .

The difference between the most probable λ and its expected value for small x is due to the asymmetry of $f(\lambda)$.

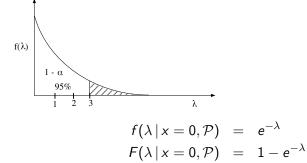
(From a flat prior!)



$$f(\lambda | x = 0, \mathcal{P}) = e^{-\lambda}$$

$$F(\lambda | x = 0, \mathcal{P}) = 1 - e^{-\lambda}$$

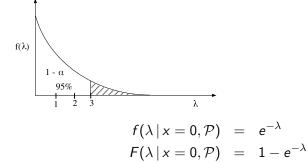
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Upper probabilistic limit (e.g. at 95% probability):

 $P(\lambda \leq \lambda_u \,|\, x = 0) = F(\lambda_u \,|\, x = 0) = 0.95$

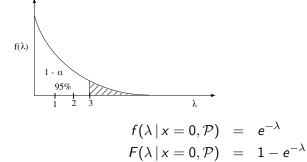
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1 - F(\lambda_u \,|\, x = 0) = e^{-\lambda_u} = 0.05

(From a flat prior!)

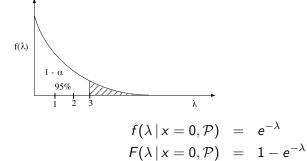


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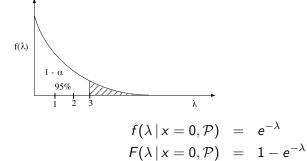


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But not because $f(x = 0 | \lambda = 3) = e^{-3} = 0.05!$

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$$\lambda_u = 3 \text{ at } 95\% \text{ probability}.$$
But not because $f(x = 0 | \lambda = 3) = e^{-3} = 0.05!$
n this case it works just by chance

Do you remember? (From first lecture)

In general $P(A | B) \neq P(B | A)$



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In general $P(A | B) \neq P(B | A)$

- $P(\text{Positive} | \overline{HIV}) \neq P(\overline{HIV} | \text{Positive})$
- $P(Win | Play) \neq P(Play | Win)$ [Lotto]
- $P(Pregnant | Woman) \neq P(Woman | Pregnant)$

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Very little to laugh...



Conjugate prior

$$f(\lambda | x) \propto \lambda^x e^{-\lambda} \cdot f_{\circ}(\lambda)$$



Conjugate prior

$$\begin{array}{rcl} f(\lambda \,|\, x) & \propto & \lambda^x \, e^{-\lambda} \cdot f_{\circ}(\lambda) \\ & \propto & \lambda^x \, e^{-\lambda} \cdot \lambda^a \, e^{-b\,\lambda} \end{array}$$

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Inferring Poisson's λ Conjugate prior

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Does such a probability function 'exist'?

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Does such a probability function 'exist'?

 $\Rightarrow \mathsf{Gamma}\ \mathsf{distribution}$



$$\begin{aligned} X &\sim \operatorname{Gamma}(c,r):\\ f(x \mid \operatorname{Gamma}(c,r)) &= \frac{r^c}{\Gamma(c)} x^{c-1} e^{-rx} \qquad \left\{ \begin{array}{c} r, \ c > 0\\ x \geq 0 \end{array} \right., \end{aligned}$$

where

$$\Gamma(c) = \int_0^\infty x^{c-1} e^{-x} \mathrm{d}x$$

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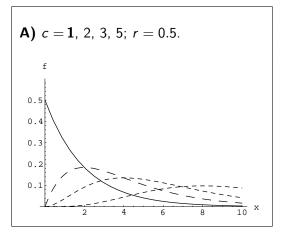
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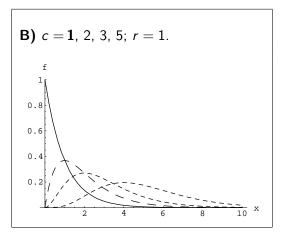
The Erlang distribution is important to get a physical intuition of the properties of Gamma and then of the χ^2 !

Some examples



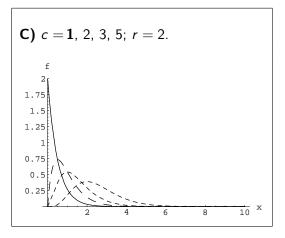
r: rate (if the variable is a time, then *r* is Poisson rate).

Some examples



r: rate (rate increases \rightarrow distributions squized)

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Gamma (and $\chi^2)$ distribution $_{\rm Summaries}$

$$E(X) = \frac{c}{r}$$

$$Var(X) = \frac{c}{r^2} = \frac{E(X)}{r}$$

$$mode(X) = \begin{cases} 0 & \text{if } c \le 1 \\ \frac{c-1}{r} & \text{if } c > 1 \end{cases}$$

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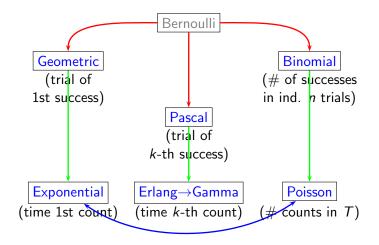
Therefore, for the χ^2 (\rightarrow c = $\nu/2$, r = 1/2)

$$E(\chi^2) = \nu$$

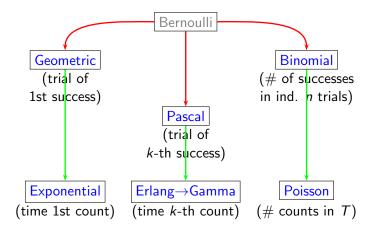
$$Var(\chi^2) = 2\nu$$

$$mode(\chi^2) = \begin{cases} 0 & \text{if } \nu \le 2\\ \nu - 2 & \text{if } \nu > 2 \end{cases}$$

Distributions derived from the Bernoulli process

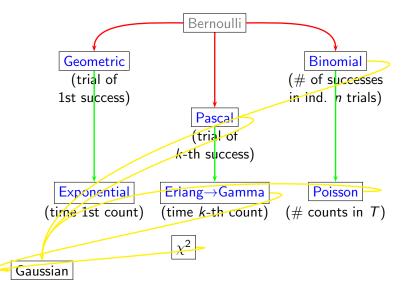


Distributions derived from the Bernoulli process



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Distributions derived from the Bernoulli process



Use of gamma conjugate prior

$$f(\lambda \mid x, \text{Gamma}(c_i, r_i)) \propto [\lambda^x e^{-\lambda}] \times [\lambda^{c_i-1} e^{-r_i \lambda}]$$



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Updating rule

 $c_f = c_i + x$ $r_f = r_i + 1$

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A "flat conjugate" prior (not just academic!):

 → exponential with very large τ (or vanishing r)
 c = 1, r → 0

 $f(\lambda \mid x, \text{Gamma}(c_i = 1, r_i \rightarrow 0)) \propto \lambda^{\chi} e^{-\lambda}$

We have seen how to learn about λ given the observed x (hereafter x_p)

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(assuming same r and T)



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Just intuitive arguments for large number behaviour (e.g. $x_p = 100$)

► λ will be \approx 100, with 'standard uncertainty' \approx 10: $\rightarrow \lambda = 100 \pm 10;$

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- by how much? → Left as exercise

Inferring λ and predicting future nr of counts with JAGS Model file (inf_lambda_pred.bug)

```
model {
   X ~ dpois(lambda);
   lambda ~ dexp(0.00001)
   Y ~ dpois(lambda);
}
```

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R stearing script:

```
modello = "inf_lambda_pred.bug" # file with model
dati <- NULL # oggetto con i dati
dati$X <- 100
jm <- jags.model(modello, dati)
update(jm, 100)
catena <- coda.samples(jm, c("lambda","Y"), n.iter=10000)
print(summary(catena))
plot(catena)
```

Adding the background



$$r = r_s + r_B$$



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$$\lambda = r T = r_s T + r_B T$$

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$$X \sim \mathcal{P}_{\lambda}$$



$$r = r_s + r_B$$

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$$\begin{array}{rcl} X & \sim & \mathcal{P}_{\lambda} \\ f(r \, | \, x, r_B, T) & \propto & f(x \, | \, r, r_B, T) \cdot f_0(r) \end{array}$$



Just an extra, independent, Poisson process in the production of events in the observation time T:

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Uncertainty on r_B ?



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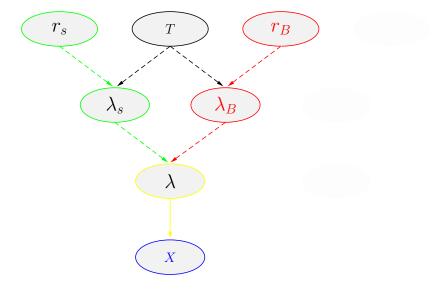
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Uncertainty on r_B ? Usual way: integrate over all possible values

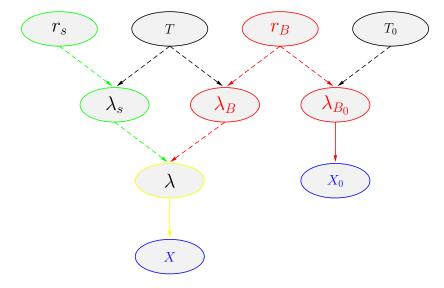
$$f(r \mid x, T) = \int_0^\infty f(r \mid x, r_B, T) \cdot f(r_B) dr_B$$

Signal and background



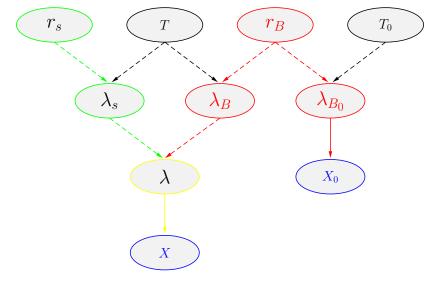
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Signal and background



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Signal and background



 $\Rightarrow inf_r_bck_measured.R \\\Rightarrow inf_r_bck_measured.bug$

Inferring signal and background with JAGS

```
model {
   X ~ dpois(lambda)
   lambda <- ls + lB
   ls <- r * T
   r ~ dgamma(1, 0.00001) # gamma, but indeed dexp(0.00001)
   1B <- rB * T
   # experiment with background only
   1B0 < - rB * TB
   XB ~ dpois(1B0)
   rB ~ dgamma(1, 0.00001) # vague priors also on the bkgd
}
```

Inferring signal and background with JAGS model = "inf_r_bck_measured.bug" # model file

data <- NULL # R list containing data data\$X <- 100 # observed nr of counts from signal+bkgd data\$T <- 10 # time of measurement signal+background data\$TB <- 4 # time of measurement of background alone data\$XB <- 20 # observed nr of counts from bkgd alone</pre>

jm <- jags.model(model, data) # define the model</pre>

print(summary(chain))
plot(chain)

The End

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