# Measurements, uncertainties and probabilistic inference/forecasting 

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## Back to the exponential distribution

Short reminder
We have seen how the exponential distribution arises from the Poisson process.

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- The Exponential is a Geometric in the continuum (it makes no sense to speak about the "precise trial", but we can talk about "time the occurrence")


## Exponential random number generator

Exercise: use the algoritm of inverting the cumulative to write an exponential random number generator

- reminder:

$$
\begin{aligned}
f(t) & =\frac{1}{\tau} e^{-t / \tau} \\
& =r e^{-r t} \\
F(t) & =1-e^{-t / \tau} \\
& =1-e^{-r t}
\end{aligned}
$$

## Property of "no memory"

Both the Exponential and the Geometric have the property of 'no memory':
If the 'success' is not occurred up to a certain 'point' (trial or instant), all probabilistic considerations restart from that that 'point'.

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P\left(X>x+x_{0} \mid X>x_{0}\right)=P(X>x)
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- the 'zero' of the counting (or of the time) can be taken when a 'success' has occurred; hence
- the Geometric distribution describes the number of trials between consecutive successes (and in this case it is convenient to make $X$ starting from 0 , instead than from 1 );
- the Exponential distribution describes the time interval between two consecutive events (as long as $r$ remains 'practically' constant).


## Decay life time and half time

(An interesting exercise)
Imagine we have, at $t=0, N(0)=N_{0}$ nuclei.

- Probability that one nucleus decays in the time interval between 0 and $\Delta T$ :


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&= 1-e^{-\Delta t / \tau} \\
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- If we have at a given instant $N$ nuclei, how many will decay in $\Delta t$ ?


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(An interesting exercise - cont.d 1)

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\begin{aligned}
X & \sim \mathcal{B}\left(N, \frac{\Delta t}{\tau}\right) \\
\mathrm{E}[X] & =N \cdot \frac{\Delta t}{\tau}[=N \cdot r \cdot \Delta t] \\
\sigma(X) & =\sqrt{\frac{\Delta t}{\tau} \cdot\left(1-\frac{\Delta t}{\tau}\right) \cdot N} \approx \sqrt{\frac{\Delta t}{\tau} \cdot N}
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v=\frac{\sigma(X)}{\mathrm{E}[X]}=\frac{1}{\sqrt{\mathrm{E}[X]}}
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- $N$ 'large'
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- N 'large'
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$v \rightarrow 0$
- The process can be seen as deterministic:


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(An interesting exercise - cont.d 2)

$$
\Delta N=-\mathrm{E}[X]=-N \frac{\Delta t}{\tau}
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## Decay life time and half time

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\begin{aligned}
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that we can 'conveniently extend' to the continuum as

$$
\frac{d N}{d t}=-\frac{N}{\tau}
$$

resulting in

$$
N(t)=N_{0} \cdot e^{-t / \tau}
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(An interesting exercise - cont.d 3 )
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- $\{\Delta N, \Delta t, N\} \rightarrow r \rightarrow \tau$
(without having to observe the instant of 'birth' and of dead of single objects)


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Quite not an easy concept for the general public $\longrightarrow$

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How life times are perceived...

Many years ago there was a claim of a proton decay observed in an underground experiment:

- The 'observed' lifetime was about $10^{25}$ years (order of magnitude - details are irrelevant);


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- The 'observed' lifetime was about $10^{25}$ years (order of magnitude - details are irrelevant);
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## Observed how a proton dies. It was $10^{25}$ years old.

# The very venerably aged proton 

Corriere della Sera, 1st June 1984

L'eccezionale avvenimento scientifico illustrato al convegno di cosmofisica dell'Aquila

# "Abbiamo visto come muore un protone" Gli scienziati italiani spiegano: aveva 10 mila triliardi di anni 

La comunicazione è stata fatta dagli studiosi che operano nel laboratorio sotto il Monte Bianco - La particella che hanno visto disintegrarsi il 17 maggio scorso era la seconda al cui «decesso" assistevano in diretta - Questo evento rarissimo ha un'enorme importanza per le moderne teorie unificate della fisica

DAL NOSTRO invuto spechas
L'AQUILA - Il protone dà segni di stanchezza I cosmonsici che lavorano nel laboratorio sotto il monte Bianco ne hanno visto disintegrarsi uno il 17 maggio scorso. Aveva un'età venerabilissima: circa diecimila triliardi di anni. E' il secondo protone la cul morte viene colta in diretta dagli scienziati italiani da quando è cominciato l'esperimento NUSEX, dalle iniziall di -Nucleon stability experimentr.
La comunicazione di questo importante risultato scientifico è stata data l'altro feri, con la prudenza necessaria, al secondo -Convegno nazionale di fisica cosmica=, che si tiene Aquila, dal físico sperimen tale Pio Picchi
NUSEX ê una collaborazione fra 1'Istituto di cosmofisica del CNR di Torino e i laboratori INFN di Milano e di Frascat


#### Abstract

per le moderne teorie unificate della fisica, ha accresciuto $l^{\prime}$ in teresse per un altro e piú grande laboratorio sotterraneo do ve si studieranno questi fenomeni: il laboratorio sotto il Gran Sasso. Durante un intermezzo dei lavori congressuall, i cento $\AA$ sici riuniti a L'Aquila hanno visitato le gallerie dove, entro due anni, sorgeranno i nuovi laboratori dell'INFN. Il parla mento ha da poco approvato it secondo finanziamento di sessanta miliardi per il completa mento delle opere pubbliche. ora gli studiosi aspettano che venga dato il via all'acquisto

\section*{della strumentazione scientifica.} -Sotto il Gran Sasso inizieremo, molto probabilmente. con tre esperimenti - spiega ii professor Renato Scrimaglio, direttore del costruendo laboratorio - : 1) lo studio del decadimento del protone; 2) lo studio del neutrini solarl; 3) la ricerca di una particella chiamata monopolo magnetico. Si tratta di ricerche di frontiera aperte alla collaborazione del fisici di tutto il mondo. I programmi dettagliati degli esperimenti saranno definiti al piú presto da una commissione presieduta dal fisico An-


tonino Zichichi, che è stato anche il proponente del laboratorio sotto il Gran Sasso. La commissione si riunirà per la prima volta il 4 giugno prossimo. I finanziamenti degli esperimenti scientifici saranno assicurati nell'ambito del bllancio 1985-1990 dell'INFN di cui si aspetta l'approvazione. Esso prevede una spesa complessiva di mille miliardi dei quall un centinaio da destinare alla strumentazione del laboratorio sotto il Gran Sasso.
Sotto 1.400 metri di roccia, ad ammirare la grande camera alta venti metri in cui si studieranno le particelle, si è av-
venturato anche il professor Bruno Rossi, 81 anni, uno del padri fondatori della fisica cosmica. - E' un paesaggio dantesco - ha esclamato - Se quando ero giovane ricercatore mi avessero detto che per studiare la radiazione cosmica sarebbe stato necessario ficcarsi qui dentro non ci avrel creduton.

- E se potesse ricominciare da capo - gli abbiamo chiesto - verrebbe a lavorarci, qui sotto?
*Ah no, certamente no-, ha risposto 11 professore scuotendo la testa.
Franco Foresta Martin

In una conferenza mondiale a Roma si proporranno nuove strategie per le attività ittiche
Ia FAn numfa al raddnmmin della mesea

## Back to the

inferential/predictive problem
related to the binomial model

## Joint inference and prediction



Let's do the math.

## Joint inference and prediction



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- Three observed variables


## Joint inference and prediction



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- Three observed variables (no uncertainty): $n_{0}, x_{0}$ and $n_{1}$.


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- $f\left(n_{0}, x_{0}, n_{1}\right)$ is a number, given the model. It might be difficult to calculate, but it is a number.

$$
f\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right)=\frac{f\left(p, x 1, n_{0}, n_{1}, x_{0}\right)}{f\left(n_{0}, x_{0}, n_{1}\right)}
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f\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right) & =\frac{f\left(p, x 1, n_{0}, n_{1}, x_{0}\right)}{f\left(n_{0}, x_{0}, n_{1}\right)} \\
& \propto f\left(p, x 1, n_{0}, n_{1}, x_{0}\right)
\end{aligned}
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& \propto f\left(p, x 1, n_{0}, n_{1}, x_{0}\right) \\
\tilde{f}\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right) & =f\left(p, x 1, n_{0}, n_{1}, x_{0}\right)
\end{aligned}
$$

$\tilde{f()}$ : unnormalized pdf.

## Joint inference and prediction



Using the chain rule ('bottom-up')
(and neglecting all factors that do not depend on $p$ and $x_{1}$ ):

$$
f\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right) \propto f\left(x_{0} \mid n_{0}, p\right) \cdot f\left(x_{1} \mid p, n_{1}\right) \cdot f_{0}(p)
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- Possibly calculate the normalization, then all moments and probability intervals of interest.


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- Possibly calculate the normalization, then all moments and probability intervals of interest.
- Do it numerically


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Using the chain rule ('bottom-up')
(and neglecting all factors that do not depend on $p$ and $x_{1}$ ):

$$
\begin{aligned}
f\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right) & \propto f\left(x_{0} \mid n_{0}, p\right) \cdot f\left(x_{1} \mid p, n_{1}\right) \cdot f_{0}(p) \\
& \propto p^{x_{0}}(1-p)^{n_{0}-x_{0}} \cdot \frac{p^{x_{1}}(1-p)^{n_{1}-x_{1}}}{x_{1}!\left(n_{1}-x_{1}\right)!} f_{0}(p) \\
\tilde{f}\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right) & =\frac{p^{x_{0}+x_{1}}(1-p)^{n_{0}+n_{1}-x_{0}-x_{1}}}{x_{1}!\left(n_{1}-x_{1}\right)!} \cdot f_{0}(p)
\end{aligned}
$$

## Problem almost solved

- Possibly calculate the normalization, then all moments and probability intervals of interest.
- Do it numerically or by by sampling.


## Joint inference and prediction


$\Rightarrow$ sample $\tilde{f}\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right)$

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$\Rightarrow$ sample $\tilde{f}\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right)$ using Monte Carlo techniques

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- by Gibbs sampler (JAGS: Just Another Gibbs Sampler) if pdf's involved allow it;


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JAGS called from R using the package rjags.

## Graphical models: some terminology



- nodes (observed/unobserved);
- child/childred;
- parent(s).


## Graphical models: some terminology



- nodes (observed/unobserved);
- child/childred;
- parent(s).
- A node without parents needs a prior (node $p$ in this case)


## Joint inference and prediction in JAGS



Model

```
model\{
    x0 ~ dbin(p, n0);
    x1 ~ dbin(p, n1);
    p ~ dbeta (1, 1);
\}
```


## Joint inference and prediction in JAGS



Then the model has to be in a file.

## Joint inference and prediction in JAGS



Then the model has to be in a file.
For such a small model we can write it directly from R on a temporary file:

```
model = "tmp_model.bug"
write("
model{
    x0 ~ dbin(p, n0);
    x1 ~ dbin(p, n1);
    p ~ dbeta(1, 1);
F
", model)
```


## Use of JAGS from R via rjags

Second part of the R script ( $\Rightarrow$ inf_p_pred_jags.R )
library(rjags)
data $=$ list( $\mathrm{n} 0=20, \mathrm{x} 0=10$, $\mathrm{n} 1=10$ )
jm <- jags.model(model, data)
chain <- coda.samples(jm, c("p", "x1"), n.iter=10000)
plot(chain)
print(summary(chain))

## Use of JAGS from R via rjags

( $n 0=20, x 0=10, n 1=10$ )

Trace of $p$


Trace of x 1


Density of $p$


Density of x 1


## Use of JAGS from R via rjags

$(n 0=20, x 0=10, n 1=10)$



Trace of x1



$$
p=0.498 \pm 0.105 ; x_{1}=4.98 \pm 1.86
$$

(10000 samples).

## Inference and prediction with JAGS/rjags

Comparison with exact result of $f\left(x_{1} \mid n_{0}, x_{0}, n_{1}\right)$

$$
f\left(x_{1} \mid n_{0}, x_{0}, n_{1}=10\right) \text { in } \%
$$

| $X_{1}$ | $\frac{x_{1}}{n_{1}}$ | $\left\{\begin{array}{l}x_{0}=1 \\ n_{0}=2\end{array}\right.$ | $\left\{\begin{array}{l}x_{0}=10 \\ n_{0}=20\end{array}\right.$ | $\left\{\begin{array}{l}x_{0}=100 \\ n_{0}=200\end{array}\right.$ | $\left\{\begin{array}{l}x_{0}=1000 \\ n_{0}=2000\end{array}\right.$ |
| ---: | ---: | ---: | ---: | ---: | ---: |
| 0 | 0 | 3.85 | 0.42 | 0.12 | 0.10 |
| 1 | 0.1 | 6.99 | 2.29 | 1.11 | 0.99 |
| 2 | 0.2 | 9.44 | 6.51 | 4.67 | 4.42 |
| 3 | 0.3 | 11.19 | 12.54 | 11.88 | 11.74 |
| 4 | 0.4 | 12.24 | 18.07 | 20.21 | 20.48 |
| 5 | 0.5 | 12.59 | 20.33 | 24.02 | 24.55 |
| 6 | 0.6 | 12.24 | 18.07 | 20.21 | 20.48 |
| 7 | 0.7 | 11.19 | 12.54 | 11.88 | 11.74 |
| 8 | 0.8 | 9.44 | 6.51 | 4.67 | 4.42 |
| 9 | 0.9 | 6.99 | 2.29 | 1.11 | 0.99 |
| 10 | 1 | 3.84 | 0.42 | 0.12 | 0.10 |
| $\mathrm{E}\left(X_{1}\right)$ | 5 | 5 | 5 | 5 |  |
| $\sigma\left[X_{1}\right]$ | 2.64 | 1.87 | 1.62 | 1.58 |  |

## Inference and prediction with JAGS/rjags

Scatter plot of sampled $f\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right)$

```
p <- as.vector(chain[[1]][,1])
x1 <- as.vector(chain[[1]][,2])
plot(x1, p, col='blue',
    main=sprintf("cor(p,x1) = %.2f", cor(p,x1)))
print( table(x1)/10000 )
```


## Inference and prediction with JAGS/rjags

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print( tah7n/*1)/1nnnn )
                                    \operatorname{cor}(p,x1)=0.56
```



## Inference and prediction with JAGS/rjags

Scatter plot of sampled $f\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right)$

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plot(x1, p, col='blue',
    main=sprintf("cor(p,x1) = %.2f", cor(p,x1)))
print( tah7n/w1)/1nnnn )
                                    \operatorname{cor}(p,x1)=0.56
```


(The last command, print(...), produces the relative frequencies of occurrance of $x_{1} \rightarrow$ try it)

## Self made Gibbs sampler

Take, as in the JAGS example, a uniform $f_{0}(p) \rightarrow f_{0}(p)=1$ :

$$
f\left(p, x_{1} \mid n_{0}, x_{0}, n_{1}\right) \propto \frac{p^{x_{0}}(1-p)^{n_{0}-x_{0}} \cdot p^{x_{1}}(1-p)^{n_{1}-x_{1}}}{x_{1}!\left(n_{1}-x_{1}\right)!}
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In the first step $(i=0)$

- extract $p^{(i=0)}$ at random: $\mathrm{p}=\operatorname{runif}(1,0,1)$;


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In the first step $(i=0)$

- extract $p^{(i=0)}$ at random: $\mathrm{p}=\operatorname{runif}(1,0,1)$; (or fix a value by hand)
- extract $x_{1}^{(i=0)}$ conditioned also by $p=p^{(i=0)}$ :

$$
f\left(x_{1} \mid n_{0}, x_{0}, n_{1}, p\right) \propto \frac{p^{x_{0}}(1-p)^{n_{0}-x_{0}} \cdot p^{x_{1}}(1-p)^{n_{1}-x_{1}}}{x_{1}!\left(n_{1}-x_{1}\right)!}
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\propto & \frac{p^{x_{1}}(1-p)^{n_{1}-x_{1}}}{x_{1}!\left(n_{1}-x_{1}\right)!} \\
& \rightarrow \mathrm{x} 1=\operatorname{rbinom}(1, \mathrm{n} 1, \mathrm{p})
\end{aligned}
$$

## Self made Gibbs sampler (cont.d)

First step:
$\rightarrow \mathrm{p}=\operatorname{runif}(1,0,1)$
$\quad($ or fix a value)
$\rightarrow \mathrm{x} 1=\operatorname{rbinom}(1, \mathrm{n} 1, \mathrm{p})$

## Self made Gibbs sampler (cont.d)

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$$
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\end{aligned}
$$

## Then

1. $i=i+1$; extract $p^{(i)}$ conditioned also by $x_{1}^{(i-1)}$ :

$$
\begin{aligned}
f\left(p \mid n_{0}, x_{0}, n_{1}, x_{1}\right) & \propto p^{x_{0}}(1-p)^{n_{0}-x_{0}} \cdot p^{x_{1}}(1-p)^{n_{1}-x_{1}} \\
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$$

2. Extract $x_{1}^{(i)}$, conditioned by $p^{(i)}$, as in Step 1

## Self made Gibbs sampler (cont.d)

First step:

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\end{aligned}
$$

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& \propto p^{x_{0}+x_{1}} \cdot(1-p)^{n_{0}+n_{1}-x_{0}-x_{1}} \quad[\rightarrow \operatorname{Beta}()]
\end{aligned}
$$

2. Extract $x_{1}^{(i)}$, conditioned by $p^{(i)}$, as in Step 1; $\Rightarrow$ then go to 1 .

## Self made Gibbs sampler (cont.d)

Summarizing, for $i \geq 1$

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$$
p^{(i)} \sim \operatorname{Beta}\left(r=x_{0}+x_{1}+1, s=n_{0}+n_{1}-x_{0}-x_{1}+1\right)
$$

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$$
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$$

2. extract $x_{1}^{(i)}$ :

$$
x_{1}^{(i)} \sim \mathcal{B}_{n_{1}, p}
$$

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Then do loop through steps 1 and 2 'many times'.

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At the end, we have the histories of the variables of interest

## Self made Gibbs sampler (cont.d)

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At the end, we have the histories of the variables of interest

- the points $\left(p^{(i)}, x_{1}^{(i)}\right)$ will 'visit' the $\left(p, x_{1}\right)$ space according to $f\left(p, x_{1}\right)$.


## Self made Gibbs sampler (cont.d)

Summarizing, for $i \geq 1$

1. $i=i+1$
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Then do loop through steps 1 and 2 'many times'.

At the end, we have the histories of the variables of interest

- the points $\left(p^{(i)}, x_{1}^{(i)}\right)$ will ' $v i s i t$ ' the $\left(p, x_{1}\right)$ space according to $f\left(p, x_{1}\right)$.
(There are theorems...)


## Gibbs sampler, implemented in R

```
# initialize the history vectors
N = 10000; p = x1 = rep(0, N)
```

\# observed nodes
$\mathrm{n} 0=20 ; \mathrm{x} 0=10 ; \mathrm{n} 1=10$
\# initial p and n1
$\mathrm{p}[1]=\operatorname{rbeta}(1,1,1) \quad$ \# uniform
$\mathrm{x} 1[1]=\operatorname{rbinom}(1, \mathrm{n} 1, \mathrm{p}[1])$
\# cat(sprintf("p = \%f, $x 1=\% d \backslash n ", p[1], x 1[1]))$
for (i in 2:N) \{
$\mathrm{p}[\mathrm{i}]=\mathrm{rbeta}(1, \mathrm{x} 0+\mathrm{x} 1[\mathrm{i}-1]+1, \mathrm{n} 0+\mathrm{n} 1-\mathrm{x} 0-\mathrm{x} 1[\mathrm{i}-1]+1)$
$\mathrm{x} 1[\mathrm{i}]=\operatorname{rbinom}(1, \mathrm{n} 1, \mathrm{p}[\mathrm{i}])$
\# cat(sprintf("p = \%f, x1 = \%d\n", p[i], x1[i]))
\}
$\longrightarrow$ inf_p_pred_gibbs.R

Inference/prediction by a Gibbs sampler implemented in R
Histogram of $p$



Histogram of $\mathbf{x 1}$


$$
\begin{aligned}
& \operatorname{mean}(p)=0.501 \\
& \operatorname{sigma}(p)=0.104 \\
& \\
& \operatorname{mean}(x 1)=5.031 \\
& \operatorname{sigma}(x 1)=1.817 \\
& \\
& \text { rho }(p, x 1)=0.548
\end{aligned}
$$

## Same problem solved using hit/miss

```
# model parameters, N and uf()
# as in the previous script
# find the maximum
p <- seq(0,1,len=101)
x1 <- 0:n1
f.max = 0
for (i in 1:length(p)) {
    for (j in 1:length(x1)) {
        f = uf(p[i], x1[j], n0, x0, n1)
    if( f > f.max ) f.max = f
    }
}
f.max <- f.max * 1.1 # exaggerated safety factor
```


## Same problem solved using hit/miss (cont.d)

\# sample in 2D
\#1. random choice in the plane ( $\mathrm{p}, \mathrm{x} 1$ )
p.r <- runif(N)
x1.r <- sample(0:n1, N, rep=TRUE)
\# 2. Calculate the function in correspondence of the points
f <- numeric(N)
for (i in 1:N) \{
f[i] <- uf(p.r[i], x1.r[i], n0, x0, n1)
\}
\# 3. accept events
hit <- runif(N)*f.max <= $f \quad \#$ accepted events ('hit')
p <- p.r[hit]
x1 <- x1.r[hit]
\#\# => inf_p_pred_hit-miss.R

## Same problem solved numerically

As an exercise, for completeness, try to solve the problem numerically (no sampling):

## Same problem solved numerically

As an exercise, for completeness, try to solve the problem numerically (no sampling):

- discretize the problem making a grid in the ( $p, x_{1}$ ) plane;


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As an exercise, for completeness, try to solve the problem numerically (no sampling):

- discretize the problem making a grid in the ( $p, x_{1}$ ) plane;
- calculate the unnormalized pdf in each elements of the grid;


## Same problem solved numerically

As an exercise, for completeness, try to solve the problem numerically (no sampling):

- discretize the problem making a grid in the ( $p, x_{1}$ ) plane;
- calculate the unnormalized pdf in each elements of the grid;
- calculate the normalization constant;


## Same problem solved numerically

As an exercise, for completeness, try to solve the problem numerically (no sampling):

- discretize the problem making a grid in the ( $p, x_{1}$ ) plane;
- calculate the unnormalized pdf in each elements of the grid;
- calculate the normalization constant;
- calculate all moments of interest, including correlation the coefficient;


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- discretize the problem making a grid in the ( $p, x_{1}$ ) plane;
- calculate the unnormalized pdf in each elements of the grid;
- calculate the normalization constant;
- calculate all moments of interest, including correlation the coefficient;
- (optional) make a lego plot, or a false-color plot to visualize the shape of the distribution.


## $n$ independent Bernoulli processes

Inferring $n$


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Think at a detector having a well known efficiency ( $\epsilon \equiv p$ )

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Think at a detector having a well known efficiency ( $\epsilon \equiv p$ ):

- we have recorded $x$ 'signals';


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- how many particles impinged the detector?


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Inferring $n$


Think at a detector having a well known efficiency ( $\epsilon \equiv p$ ):

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- how many particles impinged the detector? $\longrightarrow f(n \mid x, p) \boldsymbol{?}$

Not to be confused with a different problem:

- a Poisson process has produced $x$ in the measuring time $T$;
- what is $\lambda$ of the related Poisson distribution?


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Inferring $n$


Think at a detector having a well known efficiency ( $\epsilon \equiv p$ ):

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- how many particles impinged the detector? $\longrightarrow f(n \mid x, p)$ ?

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- a Poisson process has produced $x$ in the measuring time $T$;
what is $\lambda$ of the related Poisson distribution? $\longrightarrow f(\lambda \mid x) \boldsymbol{?}$


## $n$ independent Bernoulli processes

Inferring $n$


Think at a detector having a well known efficiency ( $\epsilon \equiv p$ ):

- we have recorded $x$ 'signals';
- how many particles impinged the detector? $\longrightarrow f(n \mid x, p) \boldsymbol{?}$

Not to be confused with a different problem:

- a Poisson process has produced $x$ in the measuring time $T$;
- what is $\lambda$ of the related Poisson distribution? $\longrightarrow f(\lambda \mid x)$ ? [or, more precisely, what is the rate $r$ ? $\longrightarrow f(r \mid x, T)$ ? ]


## $n$ independent Bernoulli processes

Extending the model
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But what is $n$ ?

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$\longrightarrow \lambda=r T$

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In JAGS, e.g., lambda <- r * T;

## Extending the model

Remembering that $p$ was got from a measurement:


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( $T_{0}$ and $T$ assumed to be measured with sufficient accuracy)

## Extending the model



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${ }^{(*)}$ Assuming unity efficiency

## Inferring $n$ 'assuming' $p$ and $x$

Back to our initial problem


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## Exercise

This time the unnormalized probability function

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\tilde{f}(n \mid p, x)=\frac{n!}{(n-x)!}(1-p)^{n}
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- make a barplot of the distribution;
- calculate $P(n \geq 20)$


## Inferring $n$ 'assuming' $p$ and $x$

Example in R with $p=0.75$ and $x=10$

## Left as exercise

(1-D version of that proposed at the end of last lecture)

## Result $\Rightarrow$

## Inferring $n$ 'assuming' $p$ and $x$

$$
f(n \mid x=10, p=0.75)
$$



## Inferring $n$ 'assuming' $p$ and $x$

Or we can feed JAGS with the following simple model

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model{
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The remaining $R$ code is left as exercise


## Moving to the Poisson model

## Inferring Poisson's $\lambda$

- set up the problem;


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- set up the problem;
- solution for uniform prior;
- the case of no events observed;
- prior conjugate;
- predictive distribution;
- from $\lambda$ to $r$ (not covered, since it is straightforward; but remember that the 'physical quantity' is $r$ )


## Inferring Poisson's $\lambda$

$$
f(\lambda \mid x, \mathcal{P})=\frac{\frac{\lambda^{x} e^{-\lambda}}{x!} f_{0}(\lambda)}{\int_{0}^{\infty} \frac{\lambda^{x} e^{-\lambda}}{x!} f_{0}(\lambda) d \lambda} .
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## Inferring Poisson's $\lambda$

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f(\lambda \mid x, \mathcal{P})=\frac{\frac{\lambda^{x} e^{-\lambda}}{x!} f_{\circ}(\lambda)}{\int_{0}^{\infty} \frac{\lambda^{x} e^{-\lambda}}{x!} f_{\circ}(\lambda) \mathrm{d} \lambda}
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Assuming $f_{0}(\lambda)$ constant up to a certain $\lambda_{\max } \gg x$ and making the integral by parts we obtain

$$
\begin{aligned}
& f(\lambda \mid x, \mathcal{P})=\frac{\lambda^{x} e^{-\lambda}}{x!} \\
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Summaries

$$
\begin{aligned}
\mathrm{E}(\lambda) & =x+1, \\
\operatorname{Var}(\lambda) & =x+1, \\
\lambda_{m} & =x
\end{aligned}
$$

## Some examples of $f(\lambda)$



For 'large' $x f(\lambda)$ it becomes Gaussian with expected value $x$ and standard deviation $\sqrt{x}$.

The difference between the most probable $\lambda$ and its expected value for small $x$ is due to the asymmetry of $f(\lambda)$.

## Inferring $\lambda$ from $x=0$

(From a flat prior!)


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f(\lambda \mid x=0, \mathcal{P}) & =e^{-\lambda} \\
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$\mathrm{f}(\lambda)$


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But not because $f(x=0 \mid \lambda=3)=e^{-3}=0.05$ !
In this case it works just by chance

## $P(A \mid B) \leftrightarrow P(B \mid A)$

Do you remember? (From first lecture)

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- $P($ Win $\mid$ Play $) \neq P($ Play $\mid$ Win $) \quad$ [Lotto]
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Very little to laugh...

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Does such a probability function 'exist'?
$\Rightarrow$ Gamma distribution

## Gamma distribution

$X \sim \operatorname{Gamma}(c, r):$

$$
f(x \mid \operatorname{Gamma}(c, r))=\frac{r^{c}}{\Gamma(c)} x^{c-1} e^{-r x} \quad\left\{\begin{array}{l}
r, c>0 \\
x \geq 0
\end{array},\right.
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f\left(x \mid \chi_{\nu}^{2}\right)=f(x \mid \operatorname{Gamma}(\nu / 2,1 / 2))
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$X \sim \operatorname{Gamma}(c, r):$

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f(x \mid \operatorname{Gamma}(c, r))=\frac{r^{c}}{\Gamma(c)} x^{c-1} e^{-r x} \quad\left\{\begin{array}{l}
r, c>0 \\
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The Erlang distribution is important to get a physical intuition of the properties of Gamma and then of the $\chi^{2}$ !

## Gamma distribution

## Some examples

$$
\text { A) } c=\mathbf{1}, 2,3,5 ; r=0.5 \text {. }
$$


$r$ : rate (if the variable is a time, then $r$ is Poisson rate).

## Gamma distribution

Some examples

$$
\text { B) } c=\mathbf{1}, 2,3,5 ; r=1 .
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$r$ : rate (rate increases $\rightarrow$ distributions squized)

## Gamma distribution

Some examples
C) $c=1,2,3,5 ; r=2$.

$r$ : rate (rate increases $\rightarrow$ distributions squized)

## Gamma (and $\chi^{2}$ ) distribution

Summaries

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\begin{aligned}
\mathrm{E}(X) & =\frac{c}{r} \\
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Therefore, for the $\chi^{2}(\rightarrow c=\nu / 2, r=1 / 2)$

$$
\begin{aligned}
\mathrm{E}\left(\chi^{2}\right) & =\nu \\
\operatorname{Var}\left(\chi^{2}\right) & =2 \nu \\
\operatorname{mode}\left(\chi^{2}\right) & = \begin{cases}0 & \text { if } \nu \leq 2 \\
\nu-2 & \text { if } \nu>2\end{cases}
\end{aligned}
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## Distributions derived from the Bernoulli process



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## Inferring the Poisson's $\lambda$

Use of gamma conjugate prior

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f\left(\lambda \mid x, \operatorname{Gamma}\left(c_{i}, r_{i}\right)\right) \propto\left[\lambda^{x} e^{-\lambda}\right] \times\left[\lambda^{c_{i}-1} e^{-r_{i} \lambda}\right]
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f\left(\lambda \mid x, \operatorname{Gamma}\left(c_{i}=1, r_{i} \rightarrow 0\right)\right) \propto \lambda^{x} e^{-\lambda}
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We have seen how to learn about $\lambda$ given the observed $x$ (hereafter $x_{p}$ )

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Inferring $\lambda$ and predicting future nr of counts with JAGS Model file (inf_lambda_pred.bug)

```
model {
    X ~ dpois(lambda);
    lambda ~ dexp(0.00001)
    Y ~ dpois(lambda);
}
```


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R stearing script:
modello = "inf_lambda_pred.bug" \# file with model
dati <- NULL \# oggetto con i dati
dati\$X <- 100
jm <- jags.model(modello, dati)
update(jm, 100)
catena <- coda.samples(jm, c("lambda","Y"), n.iter=10000)
print(summary(catena))
plot(catena)

## Adding the background

## Adding background - a practical introduction with Jags

- Just an extra, independent, Poisson process in the production of events in the observation time $T$ :


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X \sim \mathcal{P}_{\lambda}
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Uncertainty on $r_{B}$ ?

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Uncertainty on $r_{B}$ ? Usual way: integrate over all possible values

$$
f(r \mid x, T)=\int_{0}^{\infty} f\left(r \mid x, r_{B}, T\right) \cdot f\left(r_{B}\right) d r_{B}
$$

## Signal and background



## Signal and background



## Signal and background


$\Rightarrow$ inf_r_bck_measured.R
$\Rightarrow$ inf_r_bck_measured.bug

## Inferring signal and background with JAGS

```
model {
    X ~ dpois(lambda)
    lambda <- ls + lB
    ls <- r * T
    r ~ dgamma(1, 0.00001) # gamma, but indeed dexp(0.00001)
    lB <- rB * T
    # experiment with background only
    1BO <- rB * TB
    XB ~ dpois(lBO)
    rB ~ dgamma(1, 0.00001) # vague priors also on the bkgd
}
```


## Inferring signal and background with JAGS

model = "inf_r_bck_measured.bug" \# model file
data <- NULL \# R list containing data
data\$X <- 100 \# observed nr of counts from signal+bkgd
data\$T <- 10 \# time of measurement signal+background data\$TB <- 4 \# time of measurement of background alone data\$XB <- 20 \# observed nr of counts from bkgd alone
jm <- jags.model(model, data) \# define the model
update(jm, 100) \# "burn in": history not recorded, \# just to get rid of initial position
\# (exaggerated in this case!)
chain <- coda.samples(jm, c("r","rB"), n.iter=10000)
print(summary(chain))
plot(chain)

## The End

