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"Probability is good sense reduced to a calculus" (S. Laplace)

Inferring 'proportions'

Let's turn the toy experiment to a 'serious' physics case:

Inferring H_j is the same as inferring the proportion of white balls:

$$H_j \iff j \iff p = \frac{j}{5}$$

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$$n: 6 \to \infty$$

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- ▶ Generalize White/Black → Success/Failure
- \Rightarrow efficiencies, branching ratios, . . .

What matters is **uncertainty**

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A number respect to which we are in condition of uncertainty

The first number rolling a die



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They could be referred to future, past, model parameters or even hyper-parameters.

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What matters is uncertainty!

But it must be a well defined number

 \blacktriangleright any uncertainty on its definition will increase our uncertainty about it (\rightarrow ISO)

A basic simple example, although conceptually very important.

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- Bernoulli process
 - X: 0, 1 (failure/success) f(0) = 1 − p f(1) = p
 it seems of practical irrelevance, → but of primary importance

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- The drunk man problem
 - Eight keys
 - After each trial he 'loses memory'
 - We watch him and cynically bet on the attempt on which he will succeed:
 - ► X = 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, ...?

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ightarrow On which number would you bet?

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• what is constant is $P(E_i | \overline{\bigcup_{j < i} E_j}) = p$, where $E_i \rightarrow X = i$.

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- \Rightarrow Beliefs are framed in a network!
 - Once we assess something, we are implicitly making an infinity of assessments concerning logically connected events!
 - We only need to make them explicit, using logic (trivial in principle, though it can be sometimes hard)

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(Observation at the basis of "propagation of uncertainties", the so called error propagation.)

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$$f(x) = p(1 - p)^{x-1}$$
Beliefs decrease geometrically
$$\Rightarrow \text{ Geometric distribution}$$

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х

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$$p = 1/2 \rightarrow \text{ tossing a coin}$$

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$$f(x) = p(1-p)^{x-1}$$

$$p = 1/18 \rightarrow \text{ a particular number}$$
at the Italian lotto $(p = 5/90)$

х

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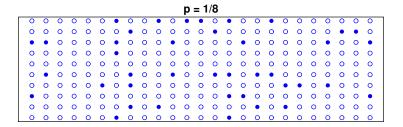
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$$f(x) = p(1 - p)^{x-1}$$
Most probable value does not depend on *p*.
Not a suitable indicator to state our expectation
The same is true for the range of possibilities: $X : 1, 2, ..., \infty$

Sequencees of Bernoulli trials

The smaller is p the longer we have to wait to get a 'success'.





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p = 1/8																									
(0	0	0	0	0	0	•	0	0	٠	0	٠	٠	0	٠	0	0	٠	0	0	0	0	0	0	0
	0	0	0	0	0	0	0	٠	0	0	0	0	0	٠	0	0	0	0	0	0	0	0	٠	٠	0
•	•	٠	0	0	0	0	٠	0	0	0	٠	0	0	0	0	٠	0	0	0	0	0	٠	0	0	•
	0	0	0	0	0	0	٠	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	0	٠	0	0	0	0	0	٠	0	0	٠	0	0	٠	٠	0	٠	٠	0	0	0	0	0	0	0
	0	0	0	0	0	٠	0	٠	0	0	0	0	0	0	0	0	0	0	٠	٠	0	•	0	0	0
	•	0	0	0	0	0	0	0	0	0	0	0	0	0	٠	٠	0	0	0	0	0	0	0	0	•
	0	0	0	0	0	0	0	٠	0	٠	0	0	0	0	0	0	٠	0	٠	0	0	0	0	0	0
	0	0	0	0	0	0	•	0	0	0	0	0	0	0	•	0	0	0	0	0	0	0	0	0	0
p = 1/2																									
	٠	٠	•	0	0	0	0	٠	٠	٠	٠	0	٠	0	0	٠	0	0	٠	•	٠	٠	٠	0	0
	0	•	•	٠	0	•	•	0	0	•	•	0	•	•	0	0	•	0	•	0	•	•	0	•	0
	0	٠	0	٠	0	0	0	0	0	٠	0	•	0	•	٠	•	0	٠	0	٠	0	0	0	•	0
	0	0	0	•	0	•	0	•	•	0	0	0	•	•	0	•	0	•	0	0	•	0	•	0	0
	•	0	0	٠	0	0	0	٠	0	0	٠	٠	0	0	٠	٠	0	0	0	0	0	0	٠	٠	0
	0	0	0	٠	0	0	٠	٠	٠	0	٠	0	0	•	٠	٠	٠	0	•	٠	0	•	0	0	•
	0	٠	٠	٠	0	٠	٠	٠	٠	0	0	٠	0	0	٠	0	٠	0	0	0	0	0	٠	0	0
	•	0	0	0	0	0	0	•	٠	٠	0	0	٠	٠	0	٠	٠	0	•	•	0	•	•	0	•
	0	٠	٠	٠	0	0	0	0	0	٠	0	0	•	٠	0	٠	٠	•	٠	٠	٠	٠	0	0	0
	•	0	•	٠	٠	•	٠	0	0	•	•	0	•	0	0	•	0	0	0	0	0	0	•	0	•



$$\mathsf{E}[X] = \sum_{x} x f(x)$$

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Variance(X) = $\sum_{x} (x - E[X])^2 f(x) \longrightarrow \sigma^2(X) \to \sigma = \sqrt{\sigma^2}$

More suitable quantity two summarize in two numbers the our probabilistic 'expectation' and its uncertainty:

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8 ...

$$E[X] = 1/p$$

$$\sigma(X) = \sqrt{1 - p}/p$$

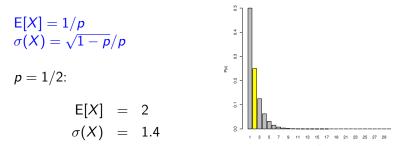
$$p = 1/8:$$

$$E[X] = 8$$

 $\sigma(X) = 7.5$

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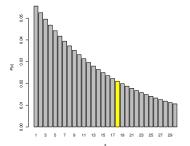
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$$\mathsf{E}[X] = 1/p \\ \sigma(X) = \sqrt{1-p}/p$$

$$p = 1/18:$$

 $E[X] = 18$
 $\sigma(X) = 17.5$



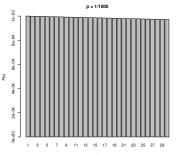
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$$\mathsf{E}[X] = 1/p \\ \sigma(X) = \sqrt{1-p}/p \xrightarrow[p \to 0]{} 1/p$$

→ rare events might happen at any moment! (Though they have 'zero' probability to happen at any given moment!)



 \implies Center of mass and momentum of inertia



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 $\sigma \neq \mathsf{RMS!}$



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Nasty comment of a non-HEP colleague during the discussion of a Tesi di Laurea in Rome (the poor student had presented several ROOT plots...):



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$\sigma \neq \mathsf{RMS}!$

Nasty comment of a non-HEP colleague during the discussion of a Tesi di Laurea in Rome (the poor student had presented several ROOT plots...):

"If he doesn't even understand the difference between *standard deviation* and *root mean square*, how can we trust that he understands the sophisticated things he is talking about?"

Normalization and cumulative distribution

$$\sum_{x=1}^{\infty} f(x | \mathcal{G}_p) = \sum_{x=1}^{\infty} (1-p)^{x-1} p$$
$$= p \sum_{x=1}^{\infty} q^{x-1}$$
$$= p \frac{1}{1-q} = 1$$

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$$= p \sum_{x=1}^{\infty} q^{x-1}$$
$$= p \frac{1}{1-q} = 1$$

$$F(x | \mathcal{G}_p) \equiv P(X \le x) = 1 - P(X > x)$$

= $1 - P(\overline{E}_1 \cap \overline{E}_2 \cap \dots \cap \overline{E}_x)$
= $1 - (1 - p)^x$ for $x = 1, 2, \dots$

Some details on the geometric distribution Expected value

$$E(X | \mathcal{G}_{p}) = \sum_{x=1}^{\infty} x f(x) = \sum_{x=1}^{\infty} x p (1-p)^{x-1}$$

$$= p \sum_{x=1}^{\infty} x q^{x-1}$$

$$= p \frac{d}{dq} \sum_{x=1}^{\infty} q^{x}$$

$$= p \frac{d}{dq} \left(\frac{1}{1-q}\right) = p \frac{1}{(1-q)^{2}}$$

$$= \frac{1}{p}$$

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= $p \frac{d}{dq} \left(\frac{1}{1-q}\right) = p \frac{1}{(1-q)^2}$
= $\frac{1}{p}$

Variance: calculation a bit more complicate $\rightarrow Var(X | \mathcal{G}_p) = q/p^2$

As implemented in packages

As implemented in packages

Usually the variable X is not defined the trial of the first success, but rather the number of trials <u>before</u> it.

➤ X is shifted by -1;



As implemented in packages

- \blacktriangleright X is shifted by -1;
- similarly the expected value;

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As implemented in packages

- \triangleright X is shifted by -1;
- similarly the expected value;
- variance invariant.
- Example in R:
 - > x <- rgeom(1000000, 1/8)
 - > mean(x)
 - [1] 6.993153
 - > sd(x)
 - [1] 7.474005

- E[X] and $\sigma(X)$ are just convenient summaries.
- In the general case they do not convey a precise confidence that X will occur in the range E[X] ± σ(X), though this probability is rather 'high' for typical f(x) of interest.

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- Anyway, it is important to be prepared to f(x) of any kind, because – fortunately! – Nature is not boring...
- In particular, f(x) might be asymmetric or, 'multinomial', i.e. with more than one local maximum.

Probability distributions and 'statistical' distributions

It is important to stress the difference between

- Probability distribution
 - To each possible outcome we associate how much we are confident on it:
- Statistical distribution

To each observed outcome we associated its (relative) frequency

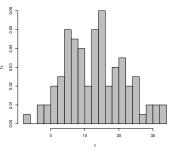
 $x \longleftrightarrow f_x$

 $x \longleftrightarrow f(x)$

(e.g. an histogram of experimental observations) Summaries ('mean', variance, ' σ ', 'skewness', etc) have similar names and analogous definitions, but conceptual different meaning.

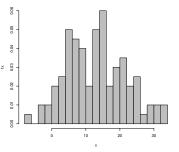
A histogram is not, usually, a probability distribution

In particular a histogram of experimental data is not a probability distribution (unless one reshuffles those events, and extracts one of them at random).



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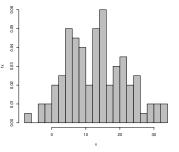
Average and variance

$$\overline{x} = \sum_{x} x f_{x}$$
$$\sigma^{2} = \sum_{x} (x - \overline{x})^{2} f_{x}$$

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Average and variance

$$\overline{x} = \sum_{x} x f_{x}$$
$$\sigma^{2} = \sum_{x} (x - \overline{x})^{2} f_{x}$$

→ Just a rough empirical description of the shape \Rightarrow center of mass and momentum of inertia! (Famous 'n/(n - 1)' correction: interference descriptive \leftrightarrow inferential statistics.)

Well known and understood Binomial distribution

► Each sequence of x successes and (n − x) failures has probability P_s(x, n, p) = p^x(1 − p)^(n−x).

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- The latter is the number of combinations of x elements taken from n "objects", and is equal to the binomial coefficient (and hence the name).

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- If we are only interested into the number of successes, independently of the order, we have to sum up all probabilities, that is multiply P_s(x, n, p) by the number of sequences.
- The latter is the number of combinations of x elements taken from n "objects", and is equal to the binomial coefficient (and hence the name).

$$f(x|\mathcal{B}_{n,p}) = \binom{n}{x} p^{x} (1-p)^{n-x} = \frac{n!}{x! (n-x)!} p^{x} (1-p)^{n-x}$$

Well known and understood Binomial distribution

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- We get finally

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Summaries (we shall see how to get them very easily)

$$\mu = \mathsf{E}[X \mid \mathcal{B}_{n,p}] = n p$$

$$\sigma[X \mid \mathcal{B}_{n,p}] = \sqrt{n p (1-p)}$$

$$v \equiv \frac{\sigma}{|\mu|} \propto \frac{1}{\sqrt{n}}$$

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Binomial distribution

Barplot with R

> n=10; p=0.3; x=0:n; P=dbinom(x, n, p)

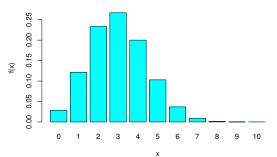
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Barplot with R

- > n=10; p=0.3; x=0:n; P=dbinom(x, n, p)
- > barplot(P, names=x, col='cyan', xlab='x', ylab='f(x)',
- + main=sprintf("binomial distr. n=%d, p=%.2f",n,p))

Barplot with R

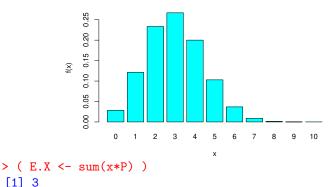
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binomial distr. n=10, p=0.30

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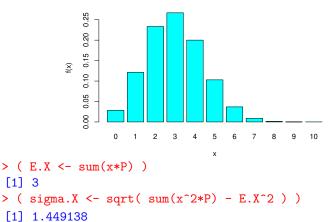
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binomial distr. n=10, p=0.30

Binomial for $n \to \infty$ and $p \to 0$

m = n p = 1						
X	f(x)					
	$\mathcal{B}_{2,\frac{1}{2}}$	$\mathcal{B}_{4,\frac{1}{4}}$	$\mathcal{B}_{10,rac{1}{10}}$	$\mathcal{B}_{50,rac{1}{50}}$	$\mathcal{B}_{1000,\frac{1}{1000}}$	$\mathcal{B}_{10^{6},10^{-6}}$
0	0.25	0.316	0.349	0.364	0.368	0.368
1	0.50	0.422	0.387	0.372	0.368	0.368
2	0.25	0.211	0.194	0.186	0.184	0.184
3		0.047	0.057	0.061	0.061	0.061
4		0.004	0.011	0.015	0.015	0.015
5			0.001	0.003	0.003	0.003
6					0.001	0.001
10			10^{-10}			
50				$pprox 10^{-85}$		
1000					$pprox 10^{-3000}$	
1000000						$pprox 10^{-6 imes 10^6}$

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Calculating extreme probabilities with R

```
> n=10; dbinom(n, n, 1/n)
[1] 1e-10
```



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> n=10; dbinom(n, n, 1/n)
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> n=50; dbinom(n, n, 1/n, log=TRUE)/log(10)
[1] -84.9485
> n=1000; dbinom(n, n, 1/n, log=TRUE)/log(10)
[1] -3000
> n=1000000; dbinom(n, n, 1/n, log=TRUE)/log(10)
[1] -6e+06
```

 \Rightarrow Trial number at which the *k*-th 'success' (exactly) occurs. (For k = 1 it recovers the Geometric distribution.)

Pascal distribution

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 - **Exercise**: get $f(x | \mathcal{P}a_{k,p})$

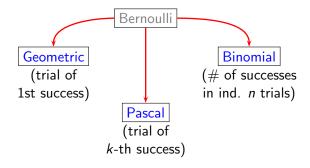
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Pascal distribution

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 - we shall see in the sequel how to evaluate simply expected value and standard deviation:





(Binomial well known. We shall not use the Pascal)



Poisson distribution

One of the best known distributions by physicists.

For a while, just take a mathematical approach:

$$f(x \,|\, \mathcal{P}_{\lambda}) = rac{\lambda^x}{x!} \, e^{-\lambda} \qquad \left\{ egin{array}{c} 0 < \lambda < \infty \ x = 0, 1, \dots, \infty \end{array}
ight. .$$

Reminding also the well known property

$$\begin{array}{c} \mathcal{B}_{n,p} \xrightarrow{n \to \infty} P_{\lambda} \\ p \to 0 \\ (n \, p = \lambda) \end{array}$$



Let us consider some phenomena that might happen at a give instant





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• Probability of 1 count in
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 is proportional to ΔT , with ΔT 'small'.

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Let us divide a finite interval T in n small intervals, i.e. $T = n \Delta T$, and $\Delta T = T/n$.

Poisson process \rightarrow Poisson distribution



Considering the possible occurrence of a count in each small interval ΔT an independent Bernoulli trial, of probability

$$p = r \Delta T = r \frac{T}{n}$$

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But $n \to \infty$ and $p \to 0 \Rightarrow \mathcal{B}_{n,p} \to \mathcal{P}_{\lambda}$ where $\lambda = n p = r T$

 $\Rightarrow \lambda$ depends only on the intensity of the process and on the finite time of observation.

 $\begin{array}{c} \text{Poisson process} \rightarrow \text{waiting time} \\ + \times & \times & \times & \times \\ 0 & & t \end{array}$

Another interesting problem: how long do we have to wait for the first count? (Starting from any arbitrary time)

Problem analogous to the Geometric, but now it makes no sense to talk about the *i*-th small interval the counts will occur!

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$$P(X > x) = \sum_{i > x} f(i \mid \mathcal{G}_p) = (1 - p)^x$$

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Poisson process \rightarrow Exponential distribution

Knowing P(T > t) we get easily the cumulative F(t):

 $F(t) = P(T \le t) = 1 - P(T > t) = 1 - e^{-rt}$.

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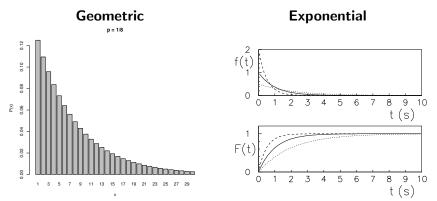
In some region of t there is a concentration of probability more than in other regions.

 \rightarrow This leads us to define a probability density function (pdf) for continuous variables:

 $f(t)=\frac{d\,F(t)}{d\,t}\,.$

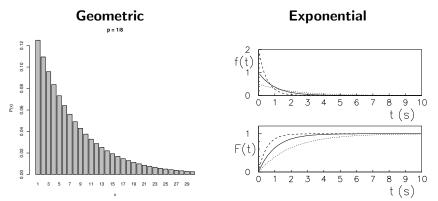
- In this case $f(t) = r e^{-rt} = \frac{1}{\tau} e^{-t/\tau}$
- \rightarrow Exponential distribution ($\tau = 1/r$): E[T] = $\sigma(T) = \tau$.

 $(\Rightarrow$ Properties of pdf assumed to be known for the moment.)



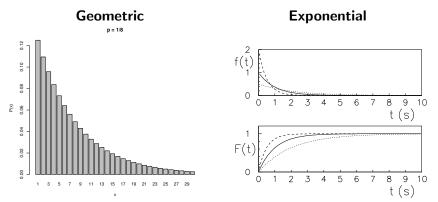
Exponential is just the limit to the continuum of the Geometric.

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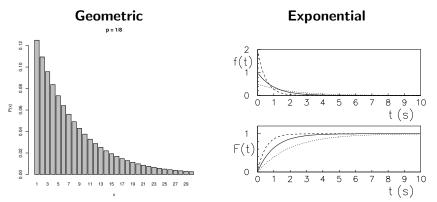


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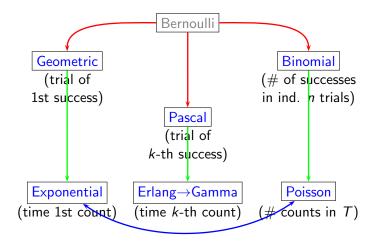
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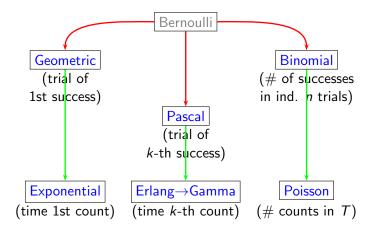


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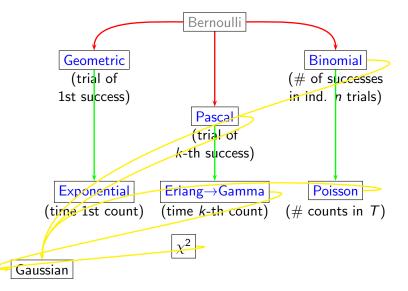


Exponential is just the limit to the continuum of the Geometric. 'No memory' property for both: Assuming that a success (or a count) has not happened until a certain trial (or time), the distributions restart from there. No need to know the instant of particle creation to measure 'life time' (\rightarrow the "10²⁵ year old" proton!).





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Important properties of probability distributions

(Assumed known)

 $E(\cdot)$ is a linear operator:

$$\mathsf{E}(aX+b)=a\,\mathsf{E}(X)+b\,.$$

Transformation properties of variance and standard deviation:

$$egin{array}{rcl} {\sf Var}({\sf a}X+{\sf b})&=&{\sf a}^2\,{\sf Var}(X)\,,\ \sigma({\sf a}X+{\sf b})&=&|{\sf a}|\,\sigma(X)\,. \end{array}$$

From probability to future frequencies

Let us think to n independent Bernoulli trials that <u>have to be made</u>.

Number of successes $X \sim \mathcal{B}_{n,p}$, with p.

We might be interested to the relative frequency of successes, i.e. $f_n = X/n$: $f_n = 0, 1/n, 2/n, ..., 1$

What do we expect for f_n ?

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We expect p, with uncertainty that decreases with \sqrt{n} : \rightarrow *Bernoulli's theorem*, the most known, misunderstood and misused theorem of probability theory.

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In particular, it justifies neither the 'increased probability' of 'late numbers' at lotto, nor frequency based definition of probability (Circular: cannot define probability from a theorem resulting from Probability Theory!)

About the misuse of Bernoulli theorem

"For those who seek to connect the notion of probability with that of frequency, results which relate probability and frequency in some way (and especially those results like the 'law of large numbers') play a pivotal rôle, providing support for the approach and for the identification of the concepts.

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Probabilistic inference

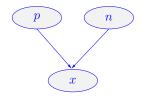
applied to the 'binomial case'



General case

General case

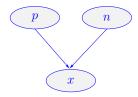
Model





General case

Model

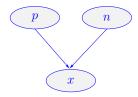


$$f(x, p, n) = f(x | p, n)$$



General case

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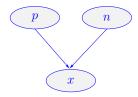


$$f(x, p, n) = f(x | p, n) \cdot f(p, n)$$



General case

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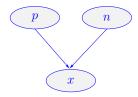


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= $f(x | p, n) \cdot f(p | n) \cdot f(n)$

General case

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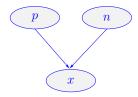


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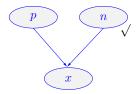


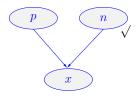
Joint pdf (omitting background condition *I*):

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= $f(x | p, n) \cdot f(p | n) \cdot f(n)$
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(*n* and *p* are independent)

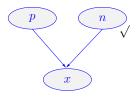




Joint pdf

 $f(x,p \mid n) = f(x \mid p,n) \cdot f(p)$

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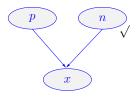


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Typical problems

▶ *p* is assumed \rightarrow interested in f(x | n, p) \rightarrow well known binomial;

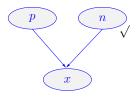


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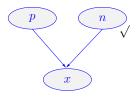


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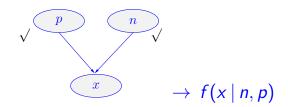
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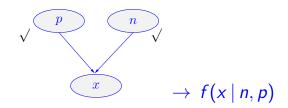
▶ x is assumed ('observed') $\rightarrow f(p \mid n, x)$: \rightarrow ?

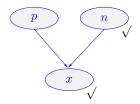
Graphical models of the typical problems





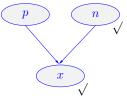
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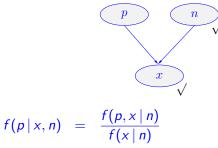




 $\rightarrow f(p \mid n, x)$

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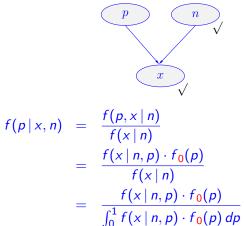




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(denominator just normalization!

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(The binomial coefficient is irrelevant, not depending on p)

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- In our case these two numbers are integer and the integral becomes equal to

$$\frac{x!(n-x)!}{(n+1)!}$$

Solution for uniform prior (think to Bayes' billard)

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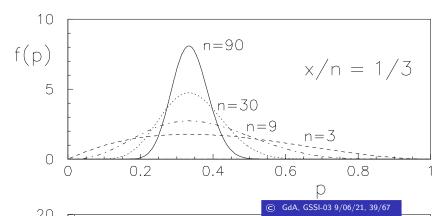
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$$Var(p) = \frac{(x+1)(n-x+1)}{(n+3)(n+2)^{2}}$$

$$= \frac{x+1}{n+2} \left(\frac{n+2}{n+2} - \frac{x+1}{n+2}\right) \frac{1}{n+3}$$

$$= E(p) (1 - E(p)) \frac{1}{n+3}$$

About the meaning of E(p)

• We have used the "first" (*) n trials to learn about "p".

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E(p) (and not the mode!) is the probability of every 'future' event which is believed to have the same p of the 'previous' ones. (But keep in mind the **inductivist turkey**!) G GdA, GSSI-03 9/06/21, 41/67

Large number behaviour

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(Similarly to Bernoulli's theorem, it is not a 'mathematical' limit!)

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• •

Large number behaviour: summary

When

- ▶ *n* large;
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$$\begin{split} \mathsf{E}(p) &\approx \frac{x}{n} \\ \sigma(p) &\approx \frac{1}{\sqrt{n}} \sqrt{\frac{x}{n} \left(1 - \frac{x}{n}\right)} \end{split}$$

— f(p | x, n) tends to Gaussian

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 The probability of a future events is evaluated from the relative frequency of the past events

Inferring the "Bernoulli's p"

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- f(p | x, n) tends to Gaussian, a reflection of the Gaussian limit of f(x | p, n)
- The probability of a future events is evaluated from the relative frequency of the past events
- No need of 'frequentistic definition' !

Frequency and probability are related in probability theory:

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- ► There is no need to identify the two concepts.
- It does not justify the frequentistic definition.

From a recent 'tesi di laurea' in Rome ('quadriennale') (undergraduate thesis)

Da questa analisi si ottengono $\mathbf{N} = (82502 \pm 287) \qquad \mathbf{n}_{\mathrm{S}} = (82378 \pm 287).$ dove $\sigma_{N(n)} = \sqrt{N(n)}.$ Da N e \mathbf{n}_{S} si ricava il valore dell'efficienza in Pos 1: $\epsilon_{\mathrm{S}(\mathrm{Pos1})} = \frac{\mathbf{n}_{\mathrm{S}}}{\mathbf{N}} = (99.847)\%$

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 $\sigma_{N}: ???$ $\sigma_{n}: ???$ (hereafter $n_{s} \rightarrow n$) N - n = 124 $\rightarrow \text{ with } \sigma_{N} = \sigma_{n} = 287:$

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$$\sigma = \frac{1}{N}\sqrt{n + \frac{n^2}{N}} \tag{4.51}$$

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Propagation of errors...and of mistakes

Eseguendo queste operazioni otteniamo il seguente risultato:

 $\epsilon_{S(Pos1)} = (99.847 \pm 0,005^{(stat)} \pm 0,010^{(sist)})\%.$

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Good luck to the experiment!

Inferring the "Bernoulli's p"

Approximate solution using the 'Gaussian trick'

Exercise

- Given f(p) ∝ p^x (1 − p)^{n−x},
 define φ(p) = − ln f(p)
 and evaluate

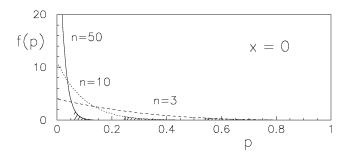
 dφ/dp
 d²φ/dp²
- Then estimate
 - $E(p) \approx p_m$ from minimum;
 - $\sigma^2(p)$ from second derivative at the minimum.

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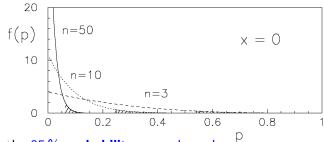
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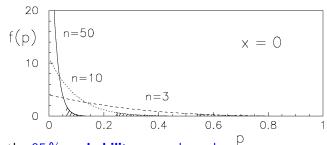
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$$F(p_{\circ} | x = 0, n, B) = 0.95$$

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$$F(p_{\circ} | x = 0, n, \mathcal{B}) = 0.95,$$

$$p_{\circ} = 1 - \sqrt[n+1]{0.05}.$$

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Inferring "Bernoulli's p" Observing x = n

$$f(n \mid \mathcal{B}_{n,p}) = p^n$$

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95% probability lower bound

$$F(p_{\circ} | x = n, B) = 0.05,$$

 $p_{\circ} = \sqrt[n+1]{0.05}$

.

A glance to upper/lower probabilistic limits

	Probability level $= 95 \%$		
n	x = n	x = 0	
	binomial	binomial	Poisson approx.
			$(p_{\circ} = 3/n)$
3	<i>p</i> ≥ 0.47	<i>p</i> ≤ 0.53	$p \leq 1$
5	$p \ge 0.61$	<i>p</i> ≤ 0.39	$p \le 0.6$
10	$p \ge 0.76$	<i>p</i> ≤ 0.24	<i>p</i> ≤ 0.3
50	<i>p</i> ≥ 0.94	$p \le 0.057$	$p \le 0.06$
100	$p \ge 0.97$	$p \le 0.029$	$p \le 0.03$
1000	$p \ge 0.997$	$p \le 0.003$	$p \leq 0.003$

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Imagine that p refers to a branching ratio: f₀(p) = 1 implies

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...

Really do you believe so?

Exercise: try to plot f(p | x = 0, n = 100) in log-log scale > $p=10^{seq}(-5, -1, len=100)$;

> plot(p, (1-p)^100, ty='l', log='xy'); grid()
(and think about it!)

Sensitivity bounds: some hints for self study

Let us restart from the Bayes' rule

$$f(p \mid x, n) \propto p^{x} (1-p)^{n-x} f_{\circ}(p)$$

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- Do the math and calculate the posterior.
- Anticipation of the result
 - if the prior is not updated at all, or if it is not changed significantly, than the experimental information is irrelevant.

Mathematically convenient priors

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Indeed, such a pdf exists (a = r - 1; b = s - 1).



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$$f(x | \text{Beta}(r, s)) = \frac{1}{\beta(r, s)} x^{r-1} (1-x)^{s-1} \qquad \begin{cases} r, s > 0 \\ 0 \le x \le 1 \end{cases}$$

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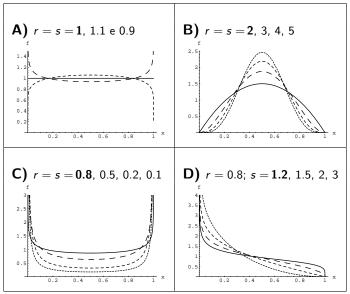
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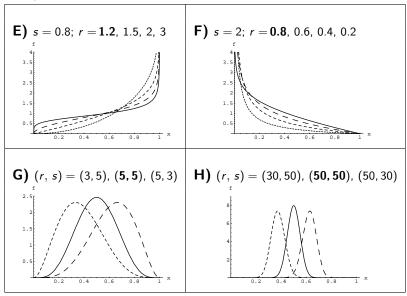
Try e.g. > p<-seq(0,1,by=0.01) > plot(p, dbeta(p, 3, 5), ty='l', col='blue')

Some examples



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Some examples



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Summaries

$$E(X) = \frac{r}{r+s}$$

Var(X) = $\frac{rs}{(r+s+1)(r+s)^2}$.

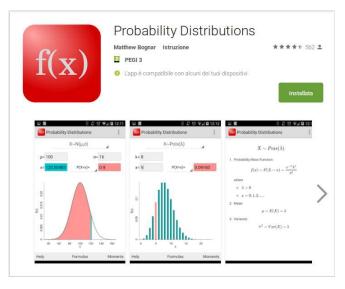
Mode, unique if r > 1 and s > 1:

$$\frac{r-1}{r+s-2}$$

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A useful app

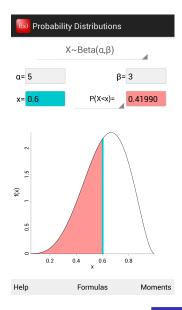
https://play.google.com/store/apps/details?id=com.mbognar.probdist



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A useful app

An example



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Beta distribution as prior

Let us finally apply it to infer the Bernoulli's p

 $\begin{aligned} f(p \mid n, x, \text{Beta}(r_i, s_i)) &\propto \quad \left[p^x (1-p)^{n-x} \right] \times \left[p^{r_i - 1} (1-p)^{s_i - 1} \right] \\ &\propto \quad p^{x + r_i - 1} (1-p)^{n-x + s_i - 1} \,. \end{aligned}$

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 $r_f = r_i + x$ $s_f = s_i + (n - x)$

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$$mode(X) = \frac{r_f - 1}{r_f + s_f - 2} = \frac{x}{n}$$

Let us finally apply it to infer the Bernoulli's p

$$\begin{array}{ll} f(p \mid n, x, \operatorname{Beta}(r_i, s_i)) & \propto & \left[p^x (1-p)^{n-x} \right] \times \left[p^{r_i-1} (1-p)^{s_i-1} \right] \\ & \propto & p^{x+r_i-1} (1-p)^{n-x+s_i-1} \,. \end{array}$$

Simple updating rule:

 $r_f = r_i + x$ $s_f = s_i + (n - x)$

$$E(X) = \frac{r_f}{r_f + s_f} = \frac{x+1}{n+2}$$

$$Var(X) = \frac{r_f s_f}{(r_f + s_f + 1)(r_f + s_f)^2} = \frac{(x+1)(n-x+1)}{(n+3)(n+2)^2}$$

$$mode(X) = \frac{r_f - 1}{r_f + s_f - 2} = \frac{x}{n} \qquad \checkmark$$

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not all *conjugate priors* are as flexible as the Beta.
 (In particular, the Gaussian is self-conjugate, which is not so great...)

Data dominated inference

Let's look again at how the prior gets updated

$$\begin{array}{ll} f(p \mid n, x, r_i, s_i) & \propto & \left[p^x (1-p)^{n-x} \right] \times \left[p^{r_i - 1} (1-p)^{s_i - 1} \right] \\ & \propto & p^{x+r_i - 1} (1-p)^{n-x+s_i - 1} \end{array}$$



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$$= \frac{(r_i + x) \cdot (s_i + n - x)}{(r_i + s_i + n + 1)(r_i + s_i + n)^2}$$

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$$r_f = r_i + x$$

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$$= \frac{(r_i + x) \cdot (s_i + n - x)}{(r_i + s_i + n + 1)(r_i + s_i + n)^2}$$

If $x \gg r_i$ and $(n-x) \gg s_i$

$$r_f \approx x$$

 $s_f \approx (n-x)$

Predicting future nr. of successes and future frequences

▶ Imagine we have have got 5 successes in 10 trials.

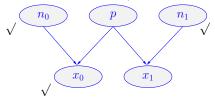


- Imagine we have have got 5 successes in 10 trials.
- Imagine that we want to make another 10 trials: what is the probability to get 0, 1, ..., 10 successes?

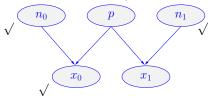
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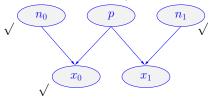
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- From the past data (and assuming a flat prior), we 'know' that p ≈ 0.5.
- If we were sure that p was 1/2, then we could simply use B_{10,1/2}.
- But we are not sure about it: we need to take into account all possible values, each weighted by f(p)



Predicting future nr. of successes and future frequences

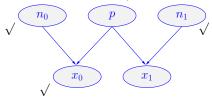


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 f(x) = ∫₀¹ f(x | p) f(p) dp.

Predicting future nr. of successes and future frequences

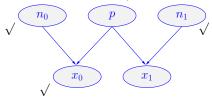


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- More precisely,

$$f(x_1 \mid n_1, n_0, x_0) = \int_0^1 f(x_1 \mid n_1, p) f(p \mid x_0, n_0) \, dp$$

 $\blacktriangleright X_1 \to f_1$

Predicting future nr. of successes and future frequences



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X₁ → f₁ (Predicting a future frequency from a past frequency)

 GdA, A. Esposito, Checking individuals and sampling populations with imperfect tests, arXiv:2009.04843 [q-bio.PE]

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Both written (also) with teaching purposes, also providing R and JAGS code.

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Both written (also) with teaching purposes, also providing R and JAGS code. (The R code can be used as a kind of *pseudocode* by those who prefer to call JAGS from Python.)

The End

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