Measurements, uncertainties and probabilistic inference/forecasting

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https://www.roma1.infn.it/~dagos/AQ2021/ (temporary web page)



Falsificationism and p-values

arXiv:physics/0412148 [physics.data-an]

- arXiv:1112.3620 [physics.data-an]
- arXiv:1609.01668 [physics.data-an]

Basic Idea:

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 → does it make sense?

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Let's review the practice and what is behind it \Rightarrow

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It seems OK - obvious'! - but it is indeed naïve for several aspects.

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- Assume that a hypothesis is true;
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is this extension legitimate?

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 - E.g. H_i being a Gaussian $f(x | \mu_i, \sigma_i)$
 - ⇒ Given any pair or parameters { μ_i, σ_i } (i.e. $\forall H_i$), <u>all</u> values of x from $-\infty$ to $+\infty$ are possible.



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 - ⇒ Having observed any value \mathbf{x} , <u>none</u> of H_i can be, strictly speaking, <u>falsified</u>.



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 \Rightarrow logically speaking, Popper's falsificationism has to be considered ... falsified!

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[I am particularly worried about claims concerning our health, or the status of the Planet, etc. ...]

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$$\Rightarrow$$
 C_i has small probability to be true
"most likely false"



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But it is behind the rational behind the statistical hypothesis tests

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In particular

A cause might produce a given effect with very low probability, and nevertheless could be the most probable cause of that effect, often the only one!

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→ What is the probability that x_{obs} comes from H_0 ? ► Certainly NOT $\approx 39 \times 10^{-6}$;

$$\begin{array}{rcl} P(x_{obs}=3.1416 \,|\, H_0) &\approx & 39 \times 10^{-6} \\ P(H_0 \,|\, x_{obs}=3.1416) &= & 1 \,. \end{array}$$

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Other, real life example:

I shut a picture with my faithful pocket camera.



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What else?

An so on...

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scientists and general public get cheated... (From the logical point of view the situation gets worsened: \rightarrow conclusions depend on events not actually observed!)

'p-value' = 'probability of the tail(s)'

Which p-value?... 'p-value' = 'probability of the tail(s)'

Of what?



'p-value' = 'probability of the tail(s)'

Of what?

 \rightarrow the test variable (' θ ') is absolutely arbitrary:

$$\theta = \theta(x)$$

 \rightarrow $f(\theta)$ [p.d.f]

Experiment: $\rightarrow \theta_{obs} = \theta(x_{obs})$

p-value =
$$P(\theta \ge \theta_{obs})$$
 ('one tail')





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► far from exhaustive list,



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- far from exhaustive list,
- with arbitrary variants:
- ⇒ practitioners chose the one that provide the result they like better:
 - \rightarrow like if you go around until "someone agrees with you"
 - personal 'golden rule': "the more exotic is the name of the test, the less I believe the result", because I'm pretty sure that several 'normal' tests have been discarded in the meanwhile...

Or look around, searching for 'significance'

If changing the test does not help, change hypotheses...



[http://xkcd.com/882/]

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P-hacking ("p-value hacking")

The 'science' of inventing significant results...

p-hacking, or cheating on a p-value

June 11, 2015 By arthur charpentier

Share

(This article was first published on **Freakonometrics** » **R-english**, and kindly contributed to **R-bloggers**)

Yesterday evening. I discovered some interesting slides on False-Positives, p-Hacking, Statistical Power, and Evidential Value, via @UCBITSS 's post on Twitter. More precisely, there was this slide on how cheating (because that's basically what it is) to get a 'good' model (by targeting the p-value)

- 1. Stop collecting data once p<.05
- Analyze many measures, but report only those with p<.05.
- Collect and analyze many conditions, but only report those with p<.05.
- Use covariates to get p<.05.
- 5. Exclude participants to get p<.05.

6. Transform the data to get p<.05.

http://www.r-bloggers.com/p-hacking-or-cheating-on-a-p-value/

► Google for "p-hacking"

Continuing

from last lecture

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Let us take randomly one of the boxes.

We are in a state of uncertainty concerning several *events*, the most important of which correspond to the following questions:

- (a) Which box have we chosen, H_0 , H_1 , ..., H_5 ?
- (b) If we extract randomly a ball from the chosen box, will we observe a white $(E_W \equiv E_1)$ or black $(E_B \equiv E_2)$ ball?

$$\bigcup_{j=0}^{5} H_{j} = \Omega$$
$$\bigcup_{i=1}^{2} E_{i} = \Omega.$$



- What happens after we have extracted one ball and looked its color?
 - Intuitively feel how to roughly change our opinion about
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Let us take randomly one of the boxes.

- What happens after we have extracted one ball and looked its color?
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 - Can we do it quantitatively, in an 'objective way'?
- And after a sequence of extractions?

Note: In general, we are uncertain about all the combinations of E_i and H_j :

$E_1 \cap H_0$, $E_1 \cap H_1$, ..., $E_2 \cap H_5$,

and these 12 constituents are not equiprobable.

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Probability depends on the status of information of the *subject* who evaluates it.

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$P(E) \longrightarrow P(E | I_s(t))$

where $I_s(t)$ is the information available to subject s at time t.

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Examples:

- tossing coins and dice;
- the three box problem.

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"Given the state of **our knowledge** about everything that could possible have any bearing on the coming true...the numerical **probability** P of this event is to be a real number by the indication of which we try in some cases to setup a **quantitative measure of the strength of our conjecture** or anticipation, founded on the said knowledge, that the event comes true"

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\Rightarrow How much we believe something

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ightarrow 'Degree of belief' \leftarrow

False, True and probable



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 - Coherent bet:
 - you state the odds according on your beliefs;
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Remarks:

- Subjective does not mean arbitrary!
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Is a 'conventional' 95% C.L. lower/upper bound a 19 to 1 bet?

$p = \frac{\# \text{ favorable cases}}{\# \text{ possible equiprobable cases}}$

$p = \frac{\# \text{ times the event has occurred}}{\# \text{ independent trials under same conditions}}$





It is easy to check that 'scientific' definitions suffer of circularity, plus other problems



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Future \Leftrightarrow Past: avoid the end of the *inductivist turkey*!
Very useful evaluation rules

A) $p = \frac{\# \text{ favorable cases}}{\# \text{ possible equiprobable cases}}$

B)
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If the implicit beliefs are well suited for each case of application.

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If the implicit beliefs are well suited for each case of application. BUT they cannot define the concept of probability!

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- Rule B results from a theorem of Probability Theory (under well defined assumptions).

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In the probabilistic approach we are following

- Rule A is recovered immediately (under the assumption of equiprobability, when it applies).
- Rule B results from a theorem of Probability Theory (under well defined assumptions):

 ⇒ Laplace's rule of succession (see later)

Mathematics of beliefs

The good news:

The basic laws of degrees of belief are the same we get from the inventory of favorable and possible cases, or from events occurred in the past.

It can be proved that

the requirement of coherence leads to the famous 4 basic rules \implies

[Details skipped...]

Basic rules of probability

1.
$$0 \leq P(A \mid I) \leq 1$$

$$2. \quad P(\Omega \mid \mathbf{I}) = 1$$

3.
$$P(A \cup B \mid I) = P(A \mid I) + P(B \mid I)$$
 [if $P(A \cap B \mid I) = \emptyset$]

4.
$$P(A \cap B | I) = P(A | B, I) \cdot P(B | I) = P(B | A, I) \cdot P(A | I)$$

Remember that probability is always conditional probability!

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Note: 4. <u>does not</u> define conditional probability. (Probability is <u>always</u> conditional probability!)

Mathematics of beliefs

An even better news:

The fourth basic rule can be fully exploited!

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Mathematics of beliefs

An even better news:

The fourth basic rule can be fully exploited!

(Liberated by a curious ideology that forbids its use)



P(A | B | I) P(B | I) = P(B | A, I) P(A | I)

 $P(A|B) = \frac{P(B|A) P(A)}{P(A)}$

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Take the courage to use it!

 $P(A|B) = \frac{P(B|A) P(A)}{P(B)}$

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$P(A|B) = \frac{P(B|A) P(A)}{P(B)}$ It's easy if you try...! © GdA, GSSI-02 8/06/21, 32/48



A nice and powerful formula!



GdA and Allen Caldwell, Stellenbosch, South Africa, November 2013

[T-shirts kindly provided by Pangea Formazione]

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"The greater the probability of an observed event given any one of a number of causes to which that event may be attributed, the greater the likelihood of that cause {given that event}.

$P(C_i \mid E) \propto P(E \mid C_i)$

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$$P(C_i | E) = \frac{P(E | C_i) P(C_i)}{P(E)}$$

(Philosophical Essai on Probabilities)

[In general $P(E) = \sum_{j} P(E | C_j) P(C_j)$ (weighted average, with weigths being the probabilities of the conditions) if C_j form a complete class of hypotheses]

$$P(C_i | E) = \frac{P(E | C_i) P(C_i)}{P(E)} = \frac{P(E | C_i) P(C_i)}{\sum_j P(E | C_j) P(C_j)}$$

"This is the fundamental principle ^(*) of that branch of the analysis of chance that consists of reasoning a posteriori from events to causes"

(*) In his "Philosophical essay" Laplace calls 'principles' the 'fundamental rules'.

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Most convenient way to remember Bayes theorem

$\frac{P(H_0 \mid \text{data})}{P(H_1 \mid \text{data})} = \frac{P(\text{data} \mid H_0)}{P(\text{data} \mid H_1)} \times \frac{P(H_0)}{P(H_1)}$

• We should possibly use the <u>data</u>, rather then the test variables ' θ ' (χ^2 etc);

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[although in some case 'sufficient summaries' do exist]

At least two hypotheses are needed!

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- If P(data | H_i) = 0, it follows P(H_i | data) = 0:
 ⇒ falsification (the 'serious' one) is a corollary of the theorem, rather than a principle.

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- If P(data | H_i) = 0, it follows P(H_i | data) = 0:
 ⇒ falsification (the 'serious' one) is a corollary of the theorem, rather than a principle.
- ▶ There is no conceptual problem with the fact that $P(\text{data} | H_1) \rightarrow 0$ (e.g. 10^{-37}), provided the ratio $P(\text{data} | H_0)/P(\text{data} | H_1)$ is not undefined.

Bayes factor ('likelihood ratio')

$$\frac{P(H_0 \mid \text{data})}{P(H_1 \mid \text{data})} = \frac{P(\text{data} \mid H_0)}{P(\text{data} \mid H_1)} \times \frac{P(H_0)}{P(H_1)}$$

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Prob. $ratio|_{posterior}$ = Bayes factor × Prob. $ratio|_{prior}$

(prior/posterior w.r.t. data)



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Prob. ratio $|_{posterior}$ = Bayes factor × Prob. ratio $|_{prior}$ (prior/posterior w.r.t. data)

If H_0 and H_1 are 'complementary', that is $H_1 = \overline{H}_0$, then

posterior odds = Bayes factor \times prior odds

(Left as exercise)

Apply this reasoning to the Aids test problem (Italian citizen <u>chosen at random</u>!) *taking* a number of HIV infected Italians of $\approx 100k$:

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- 2. use the Bayes factor;

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Apply this reasoning to the Aids test problem (Italian citizen chosen at random!) taking a number of HIV infected Italians of $\approx 100k$:

- 1. use the 'standard' Bayes theorem formula;
- 2. use the Bayes factor;
- 3. try to vary the assumed number of infected Italians



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dependence on priors;
Application to the Aids test problem

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And, needless to say, try to think to Covid-19 test issues:

- dependence on priors;
- dependence on the fact that the test performances unavoidably some degree of uncertanty.

Someone would object that p-values and, in general, 'hypothesis tests' *usually* do work!

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Certainly! I agree! As it usually work overtakes in curve on remote mountain road! Someone would object that p-values and, in general, 'hypothesis tests' *usually* do work!

Certainly! I agree!

As it *usually* work overtakes in curve on remote mountain road!

But now we are also able to explain the reason.



Why should the observation of θ_{mis} should diminish our confidence on H_0 ?



Because often we give some chance to a possible alternative hypothesis H_1 , even if we are not able to exactly formulate it.



Indeed, what really matters is not the area to the right of θ_{mis} . What matters is the ratio of $f(\theta_{mis} | H_1)$ to $f(\theta_{mis} | H_0)!$ \Rightarrow to a 'small' area it corresponds a 'small' $f(\theta_{mis} | H_0)$.



But is the alternative hypothesis H_1 is unconceivable, or hardly believable, the 'smallness' of the area is irrelevant

Telling it with Gauss' words

A quote from the Princeps Mathematicorum (Prince of Mathematicians) is <u>a must</u>.



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Arguments used to derive Gaussian distribution

- $f(\mu | \{x\}) \propto f(\{x\} | \mu) \cdot f_0(\mu)$
- $f_0(\mu)$ 'flat' (all values a priory equally possible)
- posterior maximized at $\mu = \overline{x}$

It might be curious to learn that Gauss had proved, **with emphasis**, the rule to update the ratio of probabilities of complementary hypotheses, in the light of an observed event which could be due to either of them.

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(And, by the way, Enrico Fermi derived analysis tools based on *his* Bayes Theorem...

 \Rightarrow arXiv:physics/0509080 [physics.hist-ph])

Application to the six box problem



Remind:

•
$$E_1 = White$$

 \blacktriangleright $E_2 = Black$

Our tool:

$$P(H_j \mid E_i, l) = \frac{P(E_i \mid H_j, l)}{P(E_i \mid l)} P(H_j \mid l)$$



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$$P(E_{i} | H_{j}, l) :$$

$$P(E_{1} | H_{j}, l) = j/5$$

$$P(E_{2} | H_{j}, l) = (5-j)/5$$

Our prior belief about H_j

Our tool:

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Probability of *E_i* under a well defined hypothesis *H_j*.
 It corresponds to the 'response of the apparatus' in measurements.

 \rightarrow likelihood (traditional, rather confusing name!)

Our tool:

$$P(H_j \mid E_i, l) = \frac{P(E_i \mid H_j, l)}{P(E_i \mid l)} P(H_j \mid l)$$

→ Probability of E_i taking account all possible H_j → How much we are confident that E_i will occur.

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$$P(H_j \mid E_i, I) = \frac{P(E_i \mid H_j, I)}{P(E_i \mid I)} P(H_j \mid I)$$

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 $P(E_2 | H_i, l) = (5-j)/5$

- Probability of E_i taking account all possible H_j \rightarrow How much we are confident that E_i will occur. (taking into account all possible hypotheses H_j)

Our tool:

$$P(H_j \mid E_i, I) = \frac{P(E_i \mid H_j, I)}{P(E_i \mid I)} P(H_j \mid I)$$

▶
$$P(H_j | l) = 1/6$$

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- But it easy to prove that $P(E_i | I)$ is related to the other ingredients, usually easier to 'measure' or to assess somehow, though vaguely

'decomposition law': $P(E_i | I) = \sum_j P(E_i | H_j, I) \cdot P(H_j | I)$ (\rightarrow Easy to check that it gives $P(E_i | I) = 1/2$ in our case).

Collecting the pieces of information we need Our tool:

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We are ready! \longrightarrow Let's play with our toy

Now that we have set up our formalism, let's play a little

- analyse real data
- some simulations
- make variations

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- analyse real data
- some simulations
- make variations

Let's play!

- Hugin Expert (Lite demo version);
- R scripts

Learning by simulations

▶ History of $P(H_j | \text{obs. sequence})$.

Learning by simulations

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- History of P(B/W | obs. sequence).

Learning by simulations

- History of $P(H_j | \text{obs. sequence})$.
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- Comparison of the P(B/W | obs. sequence) with the relative frequency with the color has occurred in the past ("probability evaluated by relative frequency").

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Why does the Bayesian solution performs better?

Learning by simulations

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 - Why does the Bayesian solution performs better?
 - → It takes into account at the best all available information. (The frequency based answer is, at most, the solution to a different problem...)
Playing with the six boxes

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NO!

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 - Why does the Bayesian solution performs better?
 - → It takes into account at the best all available information. (The frequency based answer is, at most, the solution to a different problem...)
- Comparison of P(H_j | obs. sequence) with frequentistic methods?

NO!

 Don't even think: frequentists refuse to assign probabilities to hypotheses (in general), to causes, to true values, etc. (And you have seen the results...)

Simple case (no reporter/composition/etc. complications)

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• Update probabilities of hypotheses (cause, Box): *inference*: $P^{(n)}(B_i) \propto P(E_i^{(n)} | B_i) \cdot P^{(n-1)}(B_i)$

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Update probabilities of next extraction: prediction:

$$P^{(n+1)}(E_i) = \sum_j P(E_i | B_j) \cdot P^{(n)}(B_j)$$

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• Condition on the 'observations': $P(C, B, \underline{E}, \underline{R}^{(k>n)} | \underline{R}^{(k \le n)}) = \frac{P(C, B, \underline{E}, \underline{R})}{P(R^{(k \le n)})}$

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No real distinction between inference and prediction (We shall see it later in the case of *continuous distributions*)

The End

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