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"Probability is good sense reduced to a calculus" (S. Laplace)

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- ► No collection of formulae.
- No collection of tests "with Russian names".
- Try to build up a consistent theory that can be used for a broad range of applications.
  - Avoid unneeded 'principles'... whose results will possibly be reobtained as approximations under well stated conditions.





"... today I'll learn to read,





"... today I'll learn to read, tomorrow to write,



"... today I'll learn to read, tomorrow to write, and the day after tomorrow I'll do arithmetic."



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["Then, clever as I am, I can earn a lot of money."]



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- No rush to get formulae
- $\rightarrow\,$  If you understand the basic reasoning you can derive many formulae by yourself' !













Two-photon invariant mass

#### ATLAS Experiment at LHC (CERN, Geneva)



#### ATLAS Experiment at LHC [length: 46 m; Ø 25 m]



 $\approx 3000\,\text{km}$  cables

pprox 7000 tonnes

pprox 100 millions electronic channels



Two flashes of 'light' (2  $\gamma$ 's) in a 'noisy' environment.



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Two flashes of 'light' (2  $\gamma$ 's) in a 'noisy' environment. Higgs  $\rightarrow \gamma \gamma$ ? Probably not...







Quite indirect measurements of something we do not "see"!

#### But, can we see our mass?





... or a voltage?





#### ... or our blood pressure?



## Certainly not!

## Certainly not!

- ... although for some quantities we can have
- a 'vivid impression' (in the David Hume's sense)



#### Measuring a mass on a scale



**Equilibrium:** 

 $mg - k\Delta x = 0$  $\Delta x \rightarrow \theta \rightarrow \text{scale reading}$ 

(with 'g' gravitational acceleration; 'k' spring constant.)


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From the reading to the value of the mass:

scale reading  $\xrightarrow{given g, k, "etc."...} m$ 

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scale reading 
$$\xrightarrow{given g, k, "etc."...} m$$
  
Dependence on 'g':  $g \stackrel{?}{=} \frac{GM_{t}}{R_{t}^2}$ 

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... not even ellipsoidal...





- Earth not spherical...
- ... not even ellipsoidal...
- ...and not even homogeneous.



- Position is usually <u>not</u> at "R<sub>b</sub>" from the Earth center;
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Position is usually <u>not</u> at "R<sub>5</sub>" from the Earth center;

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▶ ....



left to your imagination...





 $\Delta x \rightarrow \theta \rightarrow$  scale reading:

left to your imagination...

- + randomic effects:
  - stopping position of damped oscillation;
  - variability of all quantities of influence (in the ISO-GUM sense);
  - reading of analog scale.



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#### $\mathsf{Mass} \longrightarrow \mathsf{Reading}$



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#### $\mathsf{Mass} \longrightarrow \mathsf{reading}$





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# $\mathsf{Reading} \longrightarrow `\mathsf{true'} \ \mathsf{mass}$



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 $\rightarrow g$   $\rightarrow$ where?  $\rightarrow$ inertial effects subtracted?



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#### Note

- Sources not necessarily independent
- In particular, sources 1-9 may contribute to 10 (e.g. not-monitored electric fluctuations)

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Error and uncertainty are not synonyms!

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#### $u = \sigma_r$ .

 $\rightarrow$  Type B uncertainty due to 'statistical effects'.

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These cases have not to be seen as "the exception that confirms the rule" [in physics exceptions falsify laws!], but as symptoms of something flawed in the reasoning, that could seriously effects also results that are not as self-evidently paradoxical as in these cases!

There is no satisfactory theory or model to treat uncertainties due to systematic errors:

"my supervisor says ...."



- "my supervisor says ...."
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In my opinion, simply the reluctance to combine linearly 10, 20 or more contributions to a global uncertainty, as the (out of fashion) 'theory' of maximum bounds would require.

- $\rightarrow~$  Right in most cases!
- $\rightarrow~$  Good sense of physicists  $\iff$  cultural background

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(that is a probabilistic statement about  $\overline{X}$ : probabilistic statements about  $\mu$  are not allowed by the theory).

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$$P\left(\overline{x}-\sqrt{2}\frac{\sigma}{\sqrt{n}} \leq \overline{x}_f \leq \overline{x}+\sqrt{2}\frac{\sigma}{\sqrt{n}}\right)=68\%,$$

as we shall see later ( $\rightarrow$  'predictive distributions').

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    - 'technically' [see e.g. G. Zech, Frequentistic and Bayesian confidence limits, EPJdirect C12 (2002) 1]
    - 'in terms of performance'  $\rightarrow$  'very strange' that no quantities show in 'other side' of a 95% C.L. bound !
  - Not suited to express our confidence! Simply because it was not invented for that purpose!

The **pretended** peculiar characteristic of frequentistic coverage is not to express confidence, but, <u>when it works</u>, to 'ensure' that, when applied a great number of times, in a defined percentage of the report the coverage statement is true.

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#### (Neyman)

"that technological and commercial apparatus which is known as an acceptance procedure"

(Fisher, referring to Neyman's statistical confidence method)

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  - $[1.00000001 \times 10^{-300}, 1.00000002 \times 10^{-300}]$  with 31.7% probability.

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For a more argued criticism on how confidence intervals technically derive (trictly following the frequentistic prescription): ⇒ arXiv:physics/0605140 [physics.data-an]

#### Arbitrary probability inversions

How do we turn, just 'intuitively'

$$P\left(\mu - \frac{\sigma}{\sqrt{n}} \le \overline{X} \le \mu + \frac{\sigma}{\sqrt{n}}\right) = 68\%$$

into

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#### We can paraphrase as

"the dog and the hunter"

#### The dog and the hunter

We know that a dog has a 50% probability of being 100 m from the hunter

 $\Rightarrow$  if we observe the dog, what can we say about the hunter?


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The terms of the analogy are clear:

hunter  $\leftrightarrow$  true value dog  $\leftrightarrow$  observable.

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The terms of the analogy are clear:

 $\begin{array}{rcl} \text{hunter} & \leftrightarrow & \text{true value} \\ & \text{dog} & \leftrightarrow & \text{observable} \,. \end{array}$ 

Intuitive and reasonable answer:

"The hunter is, with 50% probability, within 100 m of the position of the dog."

▶ dog has a 50% probability of being 100 m from the hunter



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- the dog has no preferred direction of arrival at the point where we observe him.

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Easy to understand that this conclusion is based on some tacit assumptions:

- the hunter can be anywhere around the dog
- the dog has no preferred direction of arrival at the point where we observe him.
- $\rightarrow$  not always valid!

# Measurement at the edge of a physical region

Electron-neutrino experiment, mass resolution  $\sigma = 2 \text{ eV}$ , independent of  $m_{\nu}$ .





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Electron-neutrino experiment, mass resolution  $\sigma = 2 \text{ eV}$ , independent of  $m_{\nu}$ .



Observation: -4 eV. What can we tell about  $m_{\nu}$ ?  $m_{\nu} = -4 \pm 2 \text{ eV}$  ?  $P(-6 \le m_{\nu}/\text{eV} \le -2) = 68\%$  ?  $P(m_{\nu} \le 0 \text{ eV}) = 98\%$  ?

Imagine a cosmic ray particle or a bremsstrahlung  $\gamma$ .



Observed x = 1.1.

Imagine a cosmic ray particle or a bremsstrahlung  $\gamma$ .



Observed x = 1.1.

What can we say about the true value  $\mu$  that **has caused** this observation?

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Also in this case the formal definition of the confidence interval does not work.

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Imagine a cosmic ray particle or a bremsstrahlung  $\gamma$ .



Also in this case the formal definition of the confidence interval does not work.

Intuitively, we feel that there is more chance that  $\mu$  is on the left of 1.1 than on the right one. In the jargon of the experimentalists, "there are more migrations from left to right than from right to left".

#### Asymmetric detector response

These two examples deviate from the dog-hunter picture only because of an asymmetric possible position of the 'hunter', i.e our expectation about  $\mu$  is not uniform.

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#### Summing up:

the intuitive inversion of probability

$$P(\ldots \leq \overline{X} \leq \ldots) \Longrightarrow P(\ldots \leq \mu \leq \ldots),$$

besides being theoretically unjustifiable in the frequestist approach to probability, yields results which are numerically correct only in the case of symmetric problems.

# Summary about 'standard methods'

Situation is not satisfactory in the critical situations that often occur in HEP, both in

hypotheses tests

confidence intervals

Summary about 'standard methods'

Situation is not satisfactory in the critical situations that often occur in HEP, both in

- hypotheses tests
- confidence intervals

Moreover there are issues not easy to treat in that frame [and I smile at the heroic effort to get some result :-)]

- systematic errors
- background

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We shall see that, similarly, there are hidden assumptions behind the naive probabilistic inversions.

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Curiously enough, these methods are advertised as objective because they do not need as input our scientific expectations of where the value of the quantity might lie, or of which physical hypothesis seems more reasonable!

# Implicit assumptions

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We shall see that, similarly, there are hidden assumptions behind the naive probabilistic inversions.

Curiously enough, these methods are advertised as objective because they do not need as input our scientific expectations of where the value of the quantity might lie, or of which physical hypothesis seems more reasonable!

But if we are convinced (by logic, or by the fact that neglecting that knowledge paradoxical results can be achieved) that prior expectation is relevant in inferences, we cannot accept methods which systematically neglect it and that, for that reason, solve problems different from those we are interested in!

# Let's restart

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# Observation $\rightarrow$ value of a quantity



scale reading 
$$\xrightarrow{given g, k, "etc."...} m$$

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# $Observations \rightarrow hypotheses$

This problem occurs not only "determining" *the* value of a physical quantity.

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• Experimental observation ('data')  $\rightarrow$  responsible cause.



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• Experimental observation ('data')  $\rightarrow$  responsible cause.

(But logically no substantial difference.)

# Human ancestral problem



???

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# Human ancestral problem



???

 $\begin{array}{l} \rightarrow \mbox{ Chase} \\ \rightarrow \mbox{ Run away} \end{array}$ 

# $Observation \rightarrow hypotheses$





# Chase o Run away?

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# Chase o Run away?

... or simply stay quite





## Chase o Run away?

... or simply stay quite

if it is a mold in a museum, or an artificial track in a school garden,



# Chase o Run away?

#### ... or simply stay quite

if it is a mold in a museum, or an artificial track in a school garden,

(... or we are just sated tourists, with no interest in chasing, well protected inside our safari minibus e)
## Contemporary anthropology (and technology)



???

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Effect: car broken down

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Effect: car broken down



- no gasoline
- broken pump
- electrical failure





Effect: car broken down

#### Causes:

- no gasoline
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  - he looks for (or ask about) collateral effects (noise, ...)
  - he has his own ideas about most likely causes.



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- no gasoline
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- other (I am not a mechanic...)
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Action: balance between probability of the several hypotheses, costs and times.
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## $\mathsf{Causes} \to \mathsf{effects}$

The same apparent cause might produce several, different effects



Given an observed effect, we are not sure about the exact cause that has produced it.

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 $\mathsf{E}_2 \Rightarrow \{\mathit{C}_1, \ \mathit{C}_2, \ \mathit{C}_3\}?$ 



The "essential problem" of the Sciences

"Now, these problems are classified as *probability of causes*, and are most interesting of all for their scientific applications. I play at *écarté* with a gentleman whom I know to be perfectly honest. What is the chance that he turns up the king? It is 1/8. This is a problem of the probability of effects. The "essential problem" of the Sciences

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I play with a gentleman whom I do not know. He has dealt ten times, and he has turned the king up six times. What is the chance that he is a sharper? This is a problem in the probability of causes. It may be said that it is the essential problem of the experimental method."

(H. Poincaré – Science and Hypothesis)

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(H. Poincaré – Science and Hypothesis)

Why we (or most of us) have not been taught how to tackle this kind of problems?





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# Let's change orientation

(pure despair...)



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Such an information, lacking details about

what the points mean;

Such an information, lacking details about

- what the points mean;
- how it has been obtained;



Such an information, lacking details about

- what the points mean;
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Distrust the

Dogma of the Immaculate Observation

Things change completely when we get informed that

▶ it comes from an GW interferometer;

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the 'signer' is 'someone' well known to experts of the field. [We tend to believe what trusted people believe]



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- ► The expected 'signer'?
- Coherent micro-earthquake? (3000 km apart?)





- The expected 'signer'?
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(The last two causes are not just amenities!)

On the basis of the best knowledges about the possible causes

 $\Rightarrow$  Gravitational wave



On the basis of the best knowledges about the possible causes

 $\Rightarrow$  Gravitational wave

And if instead would have been this other 'scribble'

???

On the basis of the best knowledges about the possible causes

 $\Rightarrow$  Gravitational wave

And if instead would have been this other 'scribble'

Perhaps more likely a local random tremble...

Our beliefs are strengthened by the fact that we can extract from the shape of the signal several parameters (masses, distance, etc...).

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Note the *logical thread*:

We cannot say (at least for the very first event) to have observed a gravitational wave, and then we search for the phenomenon which has produced it.

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On the contrary, **we believe it is gravitational wave** because of the overall consistency of the scenario.

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On the contrary, **we believe it is gravitational wave** because of the overall consistency of the scenario.

Despite of the 'sigmas'...

What is the difference between the two "scribbles"?



# What is the difference between the two "scribbles"? A)



What is the difference between the two "scribbles"? A)



B)

**NOTHING** (as far as we understand it <u>now</u>...)

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An example easy to understand:

- two causes;
- two effects;



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- two causes;
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- medical diagnostics helps to clarify the issues:
  - easier to reach intuitive answers

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- two effects;

medical diagnostics helps to clarify the issues:

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- ...although if someone might have fallacious intuitions
  a formal guide helps us avoiding errors
  - $\Rightarrow$  logics of the uncertain (theory of probabilities)

An Italian citizen is selected at random to undergo an AIDS test.

 $\rightarrow$  Performance of clinical trial is not perfect, as customary:

P(Pos | HIV) = 100%  $P(\text{Pos} | \overline{\text{HIV}}) = 0.2\%$   $P(\text{Neg} | \overline{\text{HIV}}) = 99.8\%$   $H_1 = \text{'HIV'} \text{ (Infected)} \qquad E_1 = \text{Positive}$   $H_2 = \text{'HIV'} \text{ (Not infected)} \qquad E_2 = \text{Negative}$ 

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Result:  $\Rightarrow$  <u>Positive</u>

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#### Result: $\Rightarrow$ <u>Positive</u>

Infected or not infected?

Being  $P(Pos | \overline{HIV}) = 0.2\%$  and having observed 'Positive', can we say?

"It is practically impossible that the person is not infected, since it was practically impossible that a non infected person would result positive"

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- "It is practically impossible that the person is not infected, since it was practically impossible that a non infected person would result positive"
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# NO

Being  $P(Pos | \overline{HIV}) = 0.2\%$  and having observed 'Positive', can we say

- "It is practically impossible that the person is not infected, since it was practically impossible that a non infected person would result positive"
- "There is only 0.2% probability that the person has no HIV"
- "We are 99.8% confident that the person is infected"
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(We will learn in the sequel how to evaluate it correctly)

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⇒ Serious mistake! (not just 99.8% instead of 98.3% or so) ... from which bad decisions might result!

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- ... and in these issues intuition can be fallacious!
- $\Rightarrow$  A sound formal guidance can rescue us

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Pay attention not to arbitrary revert conditional probabilities:

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 $P(E \mid H) \ll 1 \quad \frac{\text{does not imply}}{\text{and 'hence'}} \quad P(H \mid E) \ll 1$  $\implies P(\overline{H} \mid E) \approx 1$  $\implies Prosecutor's fallacy$ 

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An so on...

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Extract a number 'a random' integer between 1 and 1 billion (indeed pseudo-random, but it is the same for the purpose)

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What else?

## Learning from data



## Learning from data



(\*) A quantity might be meaningful only within a theory/model



Our task:

Describe/understand the 'physical world'

 ⇒ inference of laws ('models') and their parameters [Θ]
 ⇒ [Θ | X<sub>past</sub>]

 Predict observations [X]

 ⇒ forecasting
 ⇒ [X<sub>future</sub> | Θ]
 → [X<sub>future</sub> | X<sub>past</sub>]



#### Process

- neither automatic
- nor purely contemplative
  - $\rightarrow$  'scientific method'
  - $\rightarrow$  planned experiments ('actions')  $\Rightarrow$  decision.



 $\Rightarrow$  The role of theories/models

- a theory and its parameters are the 'distillate' of all our knowledge about the 'universe' of interest;
- empirical analogical thinking is in most cases not usable:
  - A theory can predict effects never observed before
  - Example: shooting a bullet



- $\Rightarrow$  The role of theories/models
  - a theory and its parameters are the 'distillate' of all our knowledge about the 'universe' of interest;
  - empirical analogical thinking is in most cases not usable:

"La cognizione d'un solo effetto acquistata per le sue cause ci apre l'intelletto a 'ntendere ed assicurarci d'altri effetti senza bisogno di ricorrere alle esperienze" (Galileo)

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What really matters is to have a Model which links parameters to observations

But remind that "all models are wrong, some are useful"....



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(S. Raman, Science with a smile)

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Even if the (*ad hoc*) model fits perfectly the data, we do not believe the predictions because we don't trust the model!

[Many 'good' models are *ad hoc* models!]

## 2011 IgNobel prize in Mathematics

- D. Martin of USA (who predicted the world would end in 1954)
- P. Robertson of USA (who predicted the world would end in 1982)
- E. Clare Prophet of the USA (who predicted the world would end in 1990)
- L.J. Rim of KOREA (who predicted the world would end in 1992)
- C. Mwerinde of UGANDA (who predicted the world would end in 1999)
- H. Camping of the USA (who predicted the world would end on September 6, 1994 and later predicted that the world will end on October 21, 2011)
2011 IgNobel prize in Mathematics

# "For teaching the world to be careful when making mathematical assumptions and calculations"

# Uncertainty



#### $\Rightarrow$ Uncertainty:

- 1. Given the past observations, in general we are not sure about the parameters of the model (and/or the model itself)
- 2. Even if we were sure about theory and parameters, there could be internal ("noise", variables out of our control) or external effects (initial/boundary conditions, 'errors', etc) that make the forecasting uncertain.

# Uncertainty



 $\Rightarrow$  Uncertainty:

No certainties, only probabilities

P(⊖ | X<sub>past</sub>)
P(X<sub>future</sub> | ⊖)
P(X<sub>future</sub> | X<sub>past</sub>)

# Deep source of uncertainty



# Deep source of uncertainty



# $\mathsf{Causes} \to \mathsf{effects}$

The same apparent cause might produce several, different effects



Given an observed effect, we are not sure about the exact cause that has produced it.

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 $\mathsf{E}_2 \Rightarrow \{\mathit{C}_1, \ \mathit{C}_2, \ \mathit{C}_3\}?$ 



# $\rightarrow$ Probability of causes

#### "the essential problem of the experimental method"



# From 'true value' to observations



Given  $\mu$  (exactly known) we are uncertain about x

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## From 'true value' to observations



Uncertainty about  $\mu$  makes us more uncertain about x

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The observed data is certain:  $\rightarrow$  'true value' uncertain.

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The observed data is certain:  $\rightarrow$  'true value' uncertain. "data uncertainty" ?



The observed data is certain:  $\rightarrow$  'true value' uncertain. "data uncertainty" ? Data corrupted?



The observed data is certain:  $\rightarrow$  'true value' uncertain.

"data uncertainty" ? Data corrupted? Even if the data were corrupted, the <u>data</u> were the corrupted data!!...



Where does the observed value of x comes from?

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We are now uncertain about  $\mu$ , given x.

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Note the symmetry in reasoning.

Let's make an experiment

#### Let's make an experiment

- ► Here
- ► Now



#### Let's make an experiment



Now

For simplicity

•  $\mu$  can assume only six possibilities:

$$0, 1, \ldots, 5$$

x is binary:

#### 0, 1

[(1,2); Black/White; Yes/Not; ...]



#### Let's make an experiment



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```
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```

 $\Rightarrow$  Later we shall make  $\mu$  continuous.







#### Let us take randomly one of the boxes.

We are in a state of uncertainty concerning several *events*, the most important of which correspond to the following questions:

- (a) Which box have we chosen,  $H_0$ ,  $H_1$ , ...,  $H_5$ ?
- (b) If we extract randomly a ball from the chosen box, will we observe a white  $(E_W \equiv E_1)$  or black  $(E_B \equiv E_2)$  ball?

$$\bigcup_{j=0}^{5} H_{j} = \Omega$$
$$\bigcup_{i=1}^{2} E_{i} = \Omega.$$



- What happens after we have extracted one ball and looked its color?
  - Intuitively feel how to roughly change our opinion about
    - the possible cause
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- What happens after we have extracted one ball and looked its color?
  - Intuitively feel how to roughly change our opinion about
    - the possible cause
    - a future observation
  - Can we do it quantitatively, in an 'objective way'?
- And after a sequence of extractions?

# The toy inferential experiment

The aim of the experiment will be to guess the content of the box without looking inside it, only extracting a ball, record its color and reintroducing in the box

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This toy experiment is conceptually very close to what we do in the pure and applied sciences

⇒ try to guess what we cannot see (the electron mass, a magnetic field, etc)

... from what we can see (somehow) with our senses.

The rule of the game is that we are not allowed to watch inside the box! (As we cannot open and electron and read its properties, unlike we read the MAC address of a PC interface.)

We all agree that the experimental results change

- the probabilities of the box compositions;
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# Where is probability?

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Where is probability?

# Certainly not in the box!

# The End

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